

Netherlands Institute for Radio Astronomy

Calibration and Imaging Tiger Team: Phase screen fitting and SelfCal

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ASTRON is part of the Netherlands Organisation for Scientific Research (NWO)

Direction Dependent Calibration: Overview





Direction Dependent Calibration: Motivations

- The ionosphere can cause time- and position-dependent phase shifts
- Using direction-dependent calibration, these shifts can be measured and corrected (e.g., with phase screens as in SPAM)
- The SPAM approach assumes that instrumental effects have been removed, but this has not been possible with LOFAR => Beam and ionosphere varying in time and frequency.
- One solution: use phase differences between sources



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Direction Dependent Calibration: Strategy



- Perform direction-dependent calibration for patches of sources
- Assume that instrumental effects are the same in all directions
- Subtracting phase solutions for two sources will result in purely ionospheric effects =>TEC screen generation.
- Test with MSSS (Multifrequency Snapshot Sky Survey), LBA data: 8 2-MHz bands, 9 11-minute snapshots (*Heald et al in prep*)

Direction Dependent Calibration: MSSS field of view





credits: David Rafferty

Direction Dependent Calibration: Example of TEC screen



- TEC value was derived for each pierce point every 10 seconds using fit to phases across all 8 Bands
- All core stations + 5 remote stations were Used
- 7 11-minute snapshots were used (first two snapshots not used due to poor solutions)



credits: David Rafferty

Direction Dependent Calibration: TEC screen used by the imager (AWimager) AST(RON



credits: Bas Van Der Tol

Direction Dependent Calibration: conclusion



- Using TEC screen, 50% more sources are detected at 30 MHz, 30% more at 45 MHz
- Position of extracted sources is more accurate => beam FWHM 167"x133" => error on the position ~20x10" are removed thanks to phase screens.
- \Rightarrow **Conclusion**: Real improvements ! But ...

⇒ Performances: generate TEC screen for 11 min snapshots every 10s Time computing ~ 20 hours ! Need more tests on different Data set and optimize time computing (also memory) ...

Self-Calibration phase only direction independent: Overview AST(RON



Self-Calibration phase only direction independent: Motivation **AST(RON**

- Goal: improve the phase solution and the final image quality using a generic tool (i.e black box tool, parameters are computed internally and automatically)
- How to do: Improve the Sky model as much as possible at highest possible resolution and calibrate data with this skymodel.

Self-Calibration phase only direction independent: Strategy AST(RON

• Concept:

 Using a starting sky model (VLSSr), calibrate data, image at 15 times the best resolution and extract a skymodel

- Calibrate with the extracted sky model and image at higher resolution that previously, extract a new skymodel.
- Loop this procedure until the best possible resolution of the observation (~longest baseline)

Self-Calibration phase only direction independent: Strategy AST(RON

Consequences: A generic tool

Increasing resolution implies to compute internally:

- Image size at each cycle (nof pixel and pixel size)
- UVmax and wmax cut at each cycle
- Image threshold cleaning at each cycle
- Robust parameter at each cycle (1 to -2)

Self-Calibration phase only direction independent: Example: scheme of selfcal **AST(RON**



Self-Calibration phase only direction independent: Results on HBA data (~140 MHz) **AST(RON**



Rms~30mJyRms~10mJyRms~2mJyThermal noise ~ 0.7 mJy

Self-Calibration phase only direction independent: Results on High HBA data (~200 MHz) **AST(RON**



At 200 MHz, The fov is tight: 2° instead 5° at lower frequency

credits: Raymond Oonk

Self-Calibration phase only direction independent: Results on LBA data (~60 MHz) **AST(RON**



At 60 MHz, Maximum useful Baseline ~20km Beam ~ 50"

Higher baselines, Ionospheric effects dominates !

credits: Ilse Bemmel

Self-Calibration phase only direction independent: Perspectives **AST(RON**

- Selfcal works on each LOFAR frequency bands
- Finish to validate the method:
 - Using mask and calibrate with dot model
 - Important time computing increase and memory consuption ... need a compromise
- Final implementation in the imaging pipeline
- Implement direction dependant calibration (TEC screens)