

# Polarisation II

ATNF Radio Astronomy School 2009

Willem van Straten

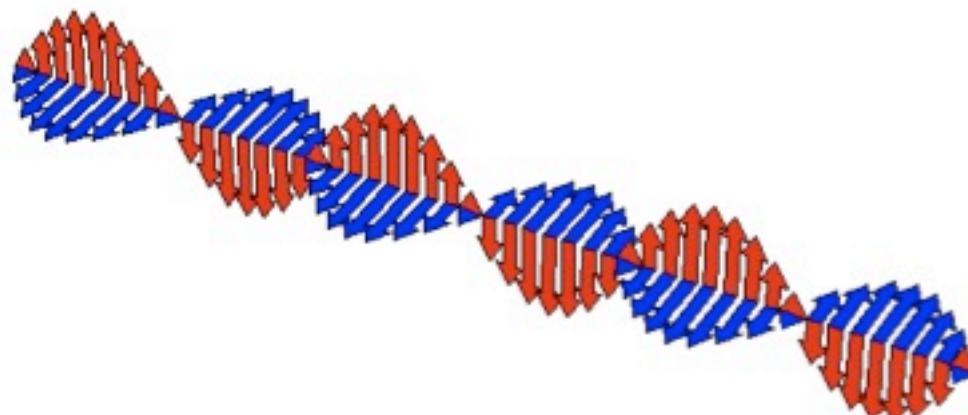
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UNIVERSITY OF NEWCASTLE

# Outline

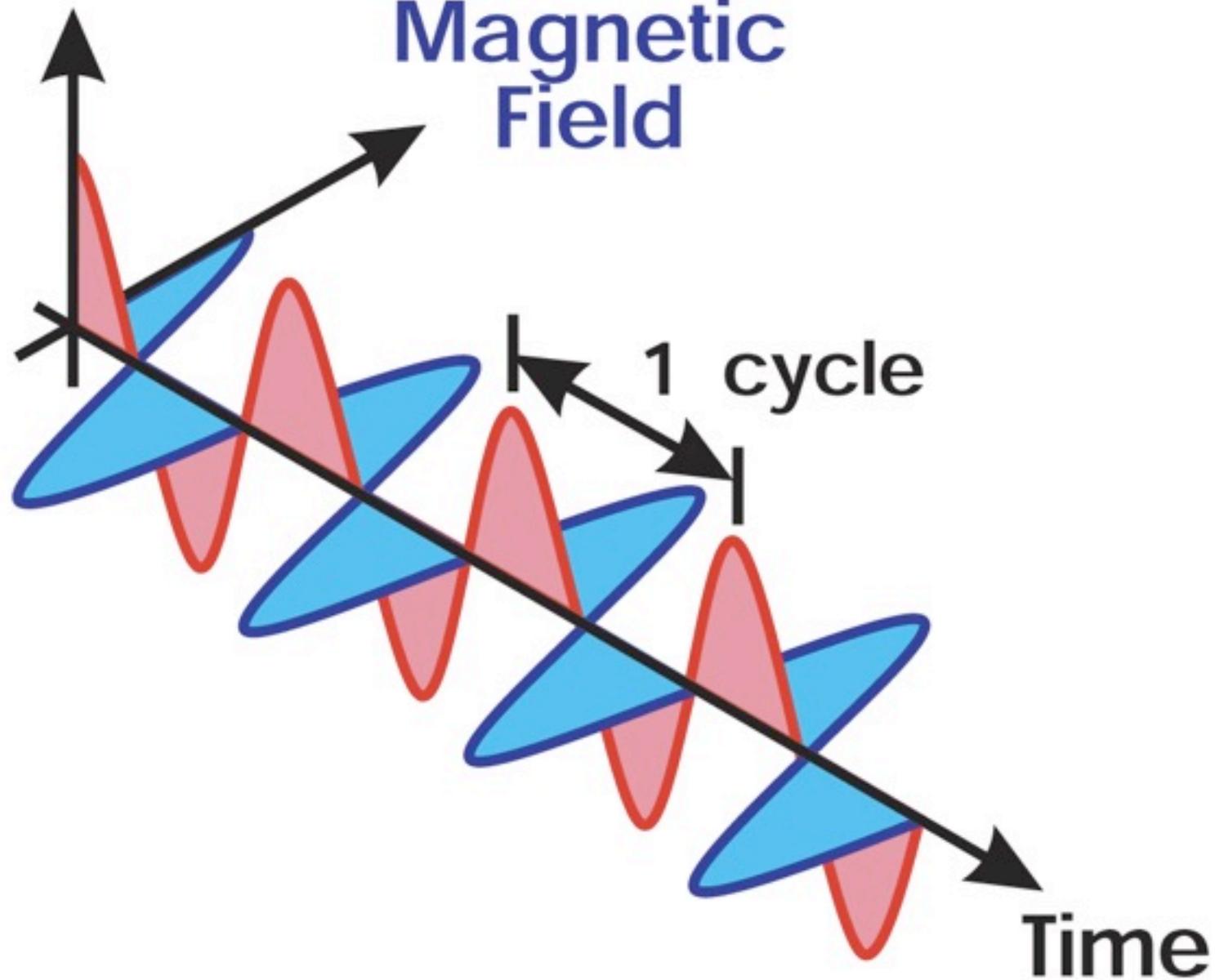
- Representations of polarisation
  - geometric and statistical
- Radio pulsar polarisation
  - rotating vector model, single pulses, Faraday rotation, high-precision timing
- Polarimetric calibration
- The Future

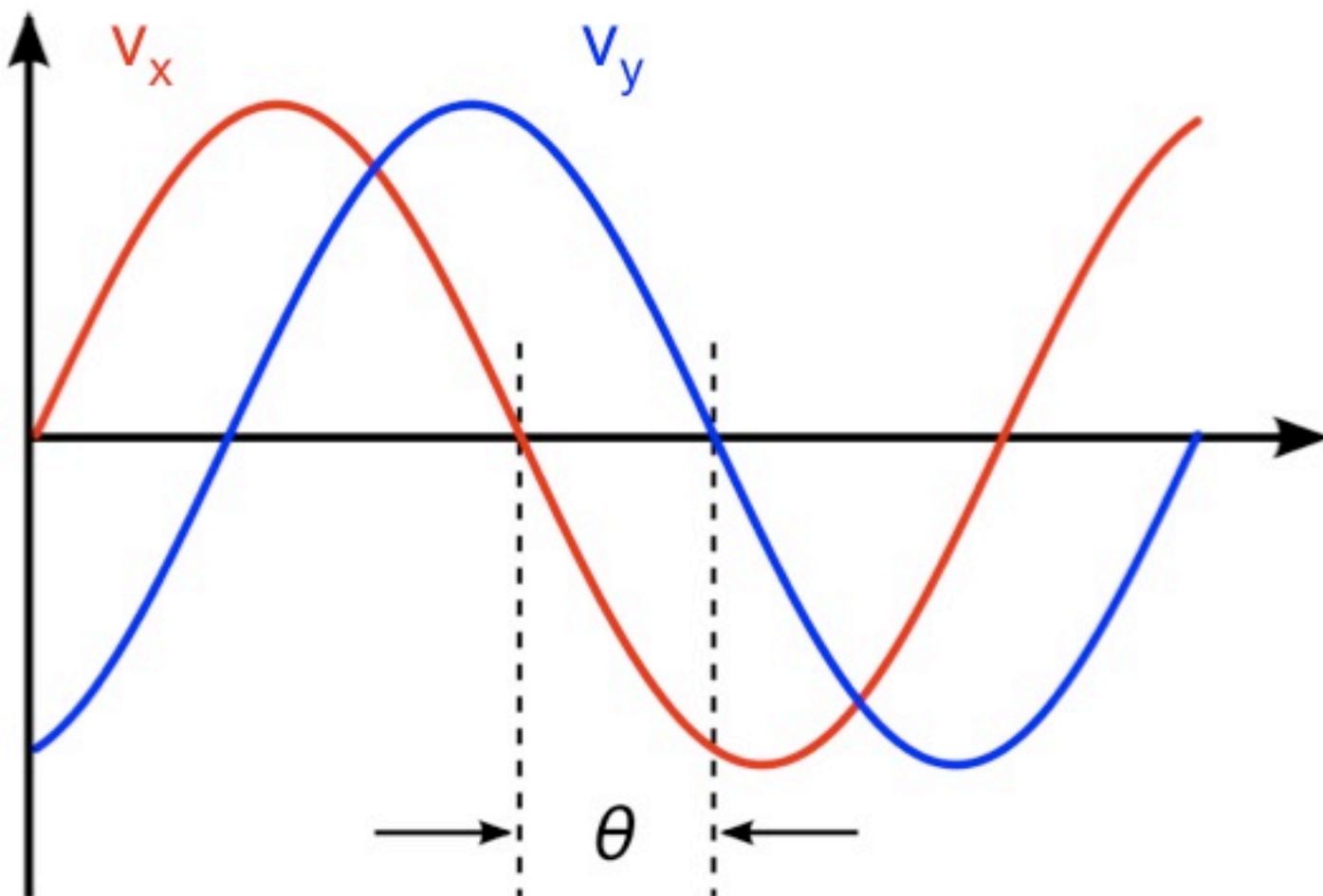
# Electromagnetic Plane Wave

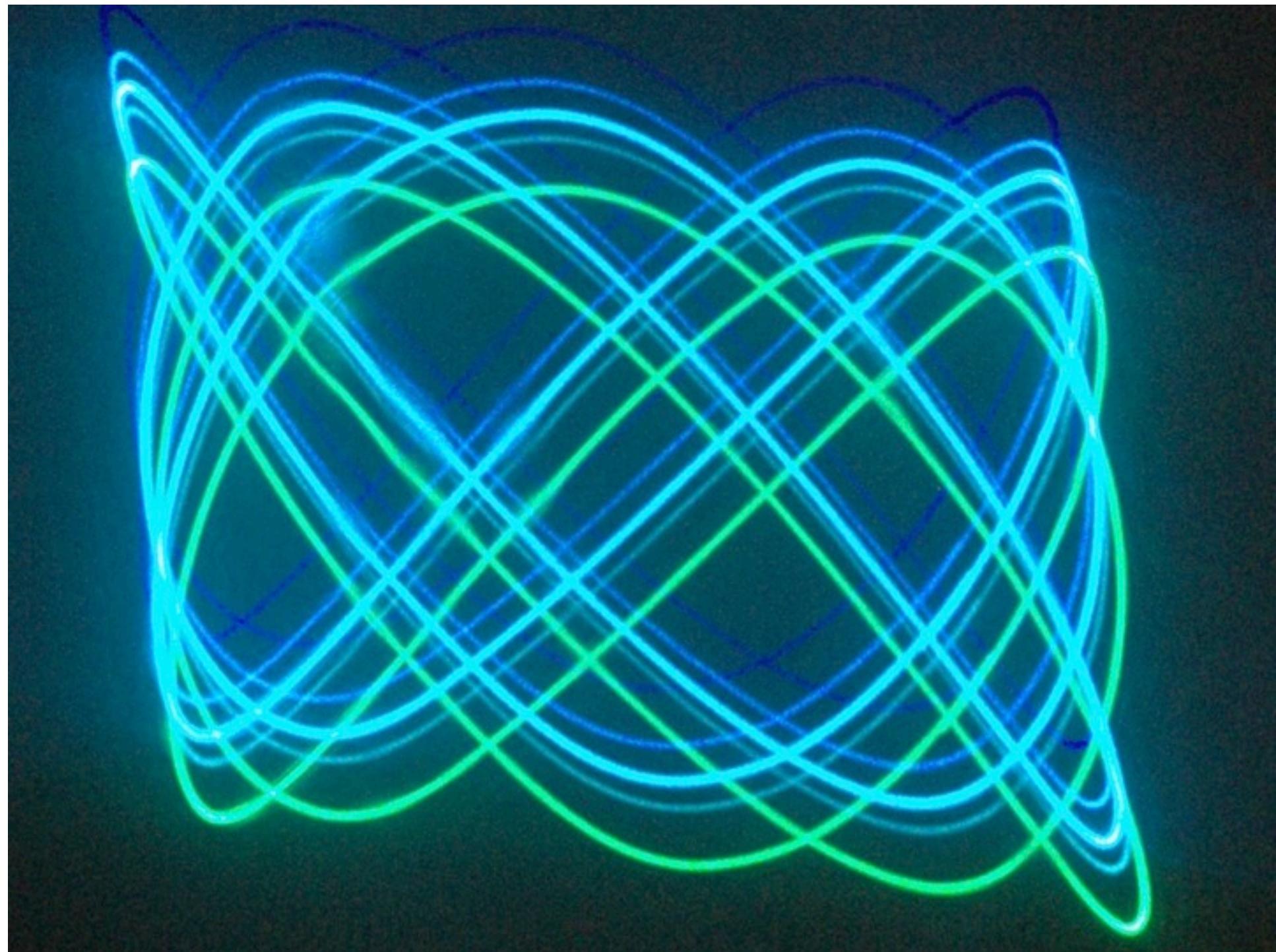


**Electric  
Field**

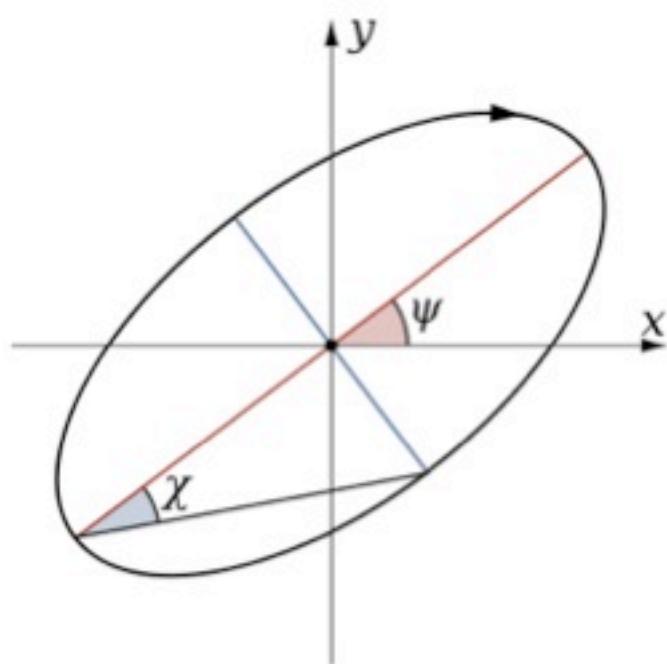
**Magnetic  
Field**





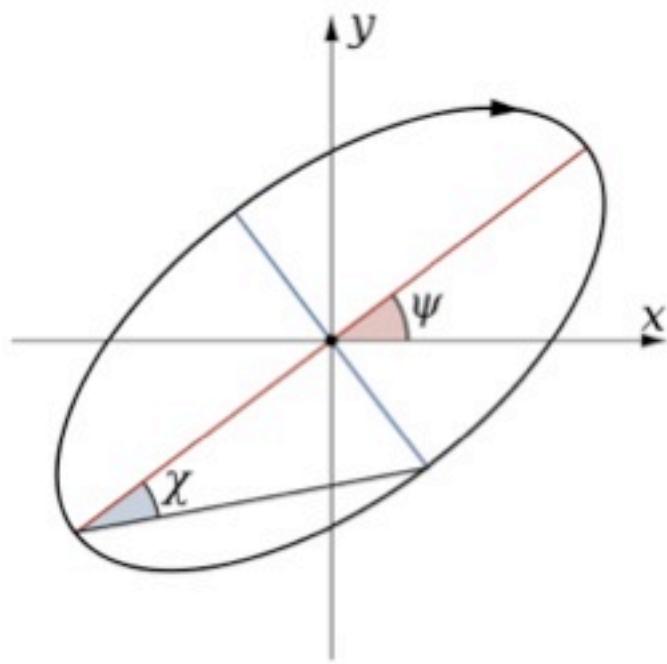


# Polarisation Ellipse



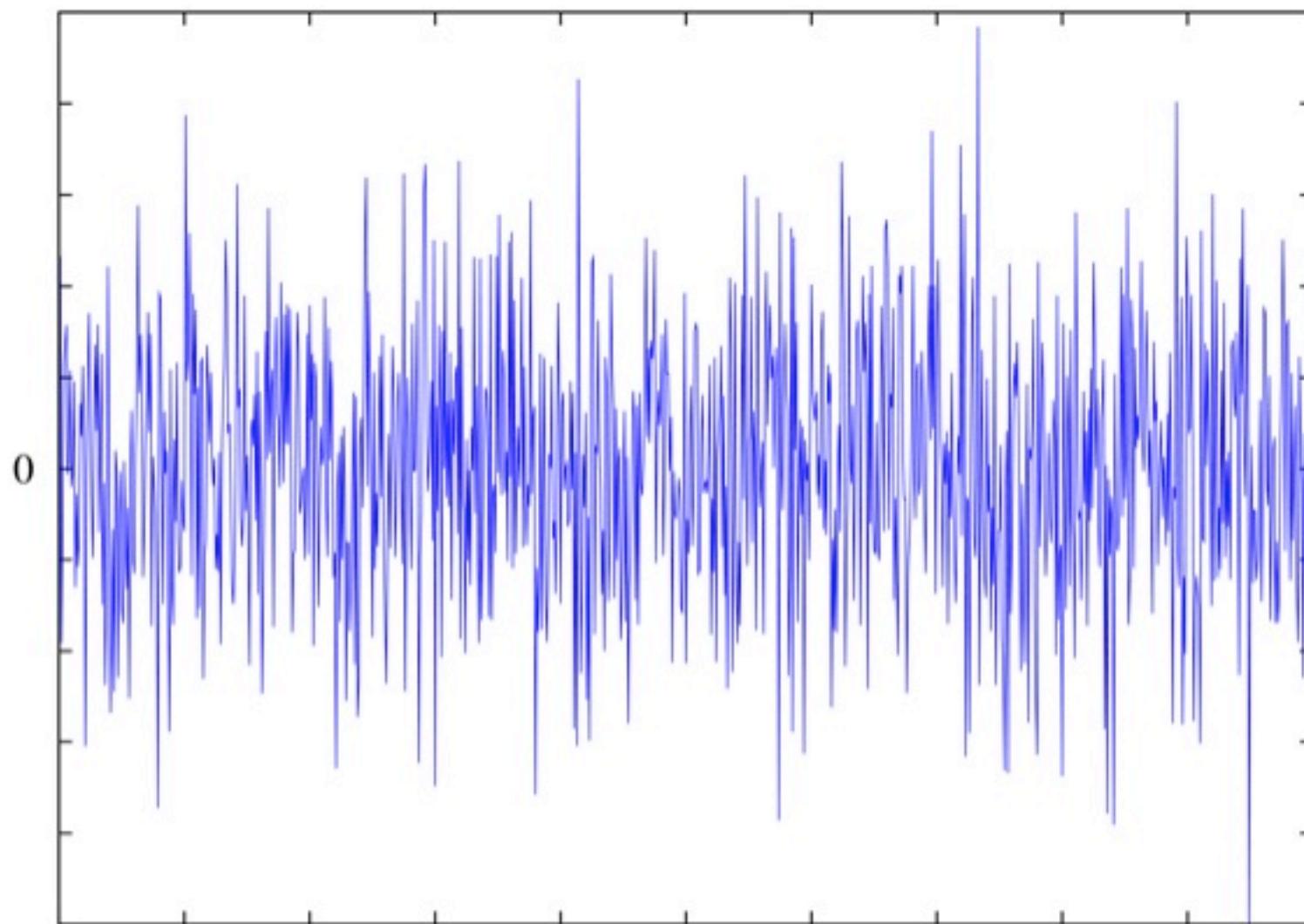
- 3 degrees of freedom
  - size, orientation  $\psi$ , and axial ratio  $\tan\chi$
  - direction = sign of  $\chi$
- insensitive to absolute phase

# Polarisation Ellipse



- $0 < \text{size} < \infty$
- $0 < \psi < \pi$
- $-\pi/4 < \chi < \pi/4$

# Partially polarised light



## Need for Complex Numbers

$$v_x(t) = a_x(t) \cos(\phi_x(t))$$

$$v_y(t) = a_y(t) \cos(\phi_y(t))$$

$$\langle \phi_x(t) - \phi_y(t) \rangle ?$$

# Analytic Signal

$$\begin{aligned}e_x(t) &= v_x(t) + i\hat{v}_x(t) = a_x(t) \exp(i\phi_x(t)) \\e_y(t) &= v_y(t) + i\hat{v}_y(t) = a_y(t) \exp(i\phi_y(t))\end{aligned}$$

$\hat{v}(t)$  is the Hilbert transform of  $v(t)$

$e(t)$  is the analytic representation of  $v(t)$

$$\langle e_x(t)e_y^*(t) \rangle = \langle a_x(t)a_y(t) \exp(i[\phi_x(t) - \phi_y(t)]) \rangle$$

# Coherency Matrix

$$\rho \equiv \langle e e^\dagger \rangle = \begin{pmatrix} \langle e_0 e_0^* \rangle & \langle e_0 e_1^* \rangle \\ \langle e_1 e_0^* \rangle & \langle e_1 e_1^* \rangle \end{pmatrix}$$

$$\rho = \rho^\dagger$$

# Stokes Parameters - Definition

$$\rho = S_k \boldsymbol{\sigma}_k / 2$$

$$S_k = \text{Tr}(\boldsymbol{\sigma}_k \rho)$$

$$\boldsymbol{\sigma}_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \boldsymbol{\sigma}_1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\boldsymbol{\sigma}_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \boldsymbol{\sigma}_3 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

# Eigen Decomposition

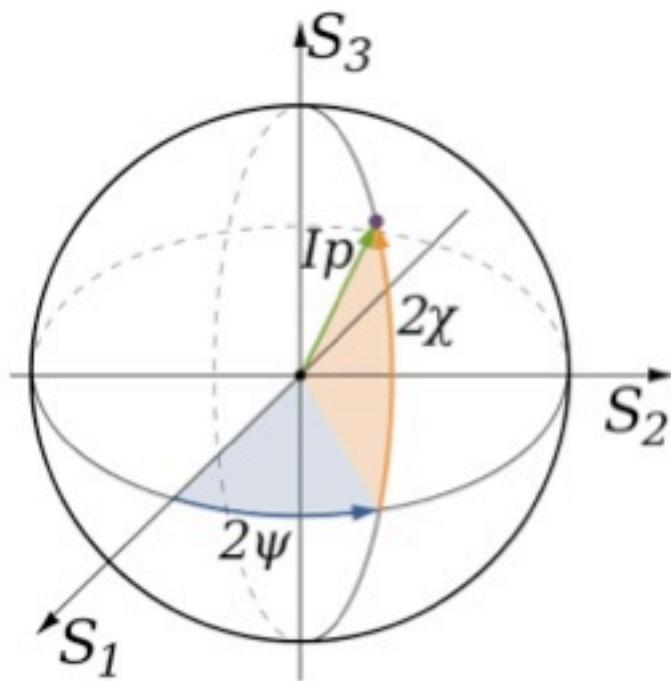
$$\rho' = \mathbf{R}\rho\mathbf{R}^{-1} = \begin{pmatrix} \lambda_0 & 0 \\ 0 & \lambda_1 \end{pmatrix}$$

$$S'_0 = \lambda_0 + \lambda_1$$

$$S'_1 = \lambda_0 - \lambda_1$$

$$S'_2 = S'_3 = 0$$

# Stokes Parameters - 4 vector

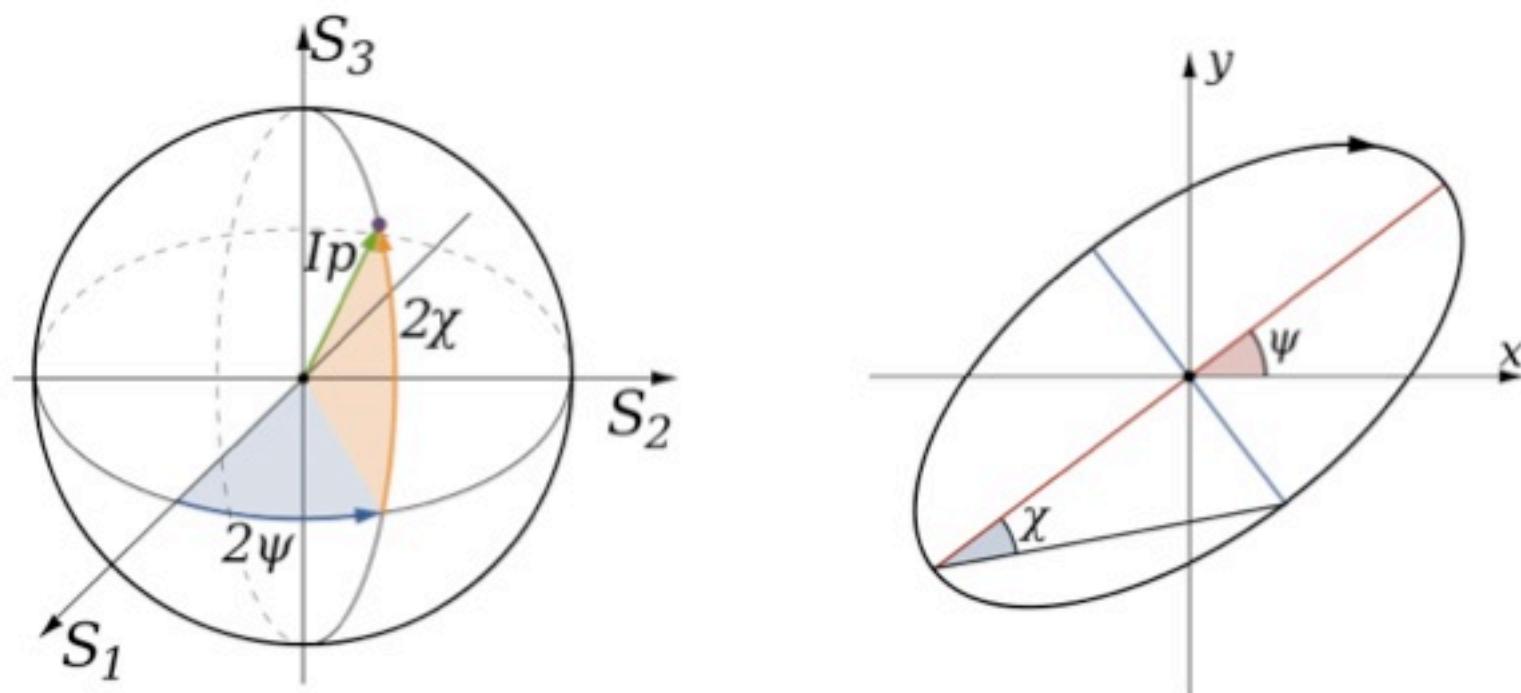


$S_0 = I$  total intensity  
 $\mathbf{S} = (S_1, S_2, S_3)$  polarisation vector

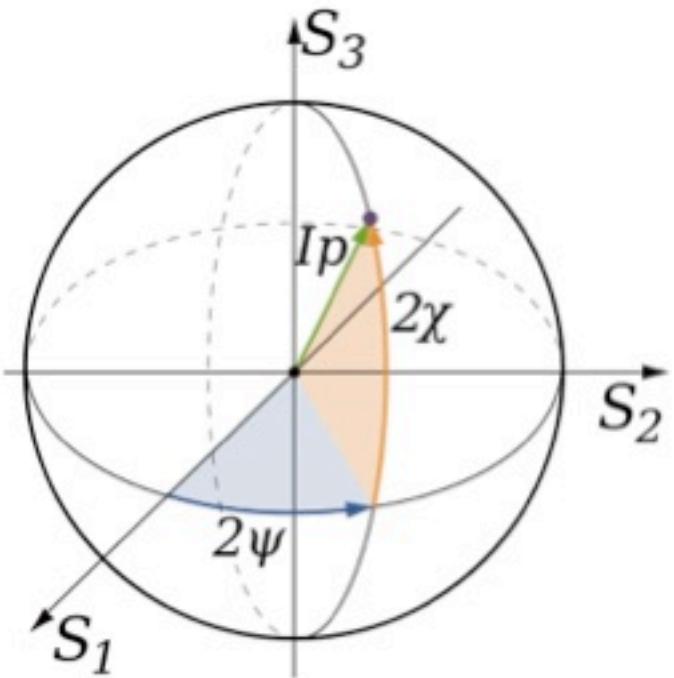
All have units of intensity

$p = |\mathbf{S}|/I$  degree of polarisation

# Stokes Parameters - Ellipse



# Stokes Parameters - Intensities



$$S_1 = \lambda_{\psi=0} - \lambda_{\psi=90}$$

$$S_2 = \lambda_{\psi=45} - \lambda_{\psi=135}$$

$$S_3 = \lambda_{\chi=45} - \lambda_{\chi=-45}$$

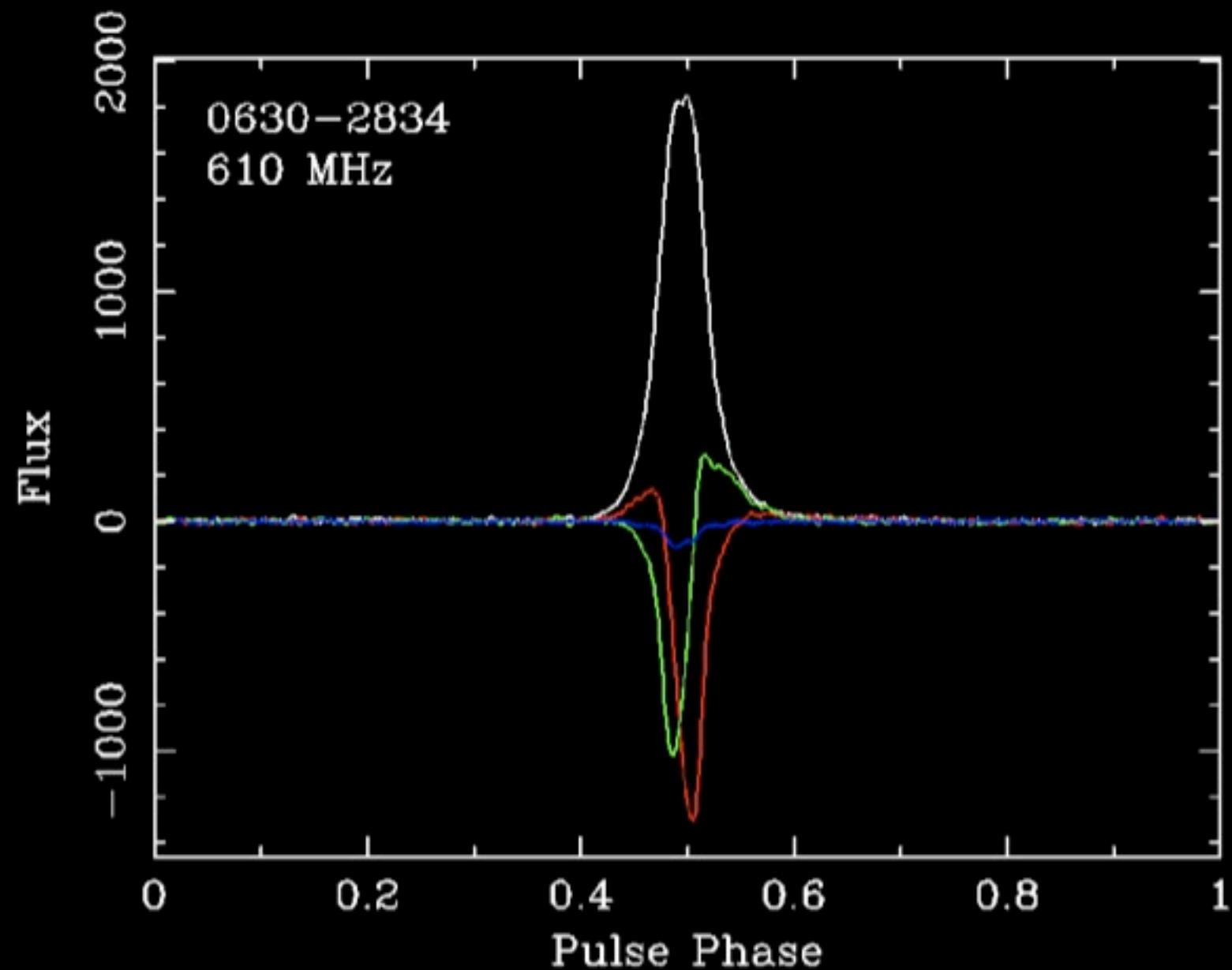
# Stokes Parameters - Mnemonic

$\begin{matrix} + & - & + \\ + & X & + \end{matrix}$

Q U V



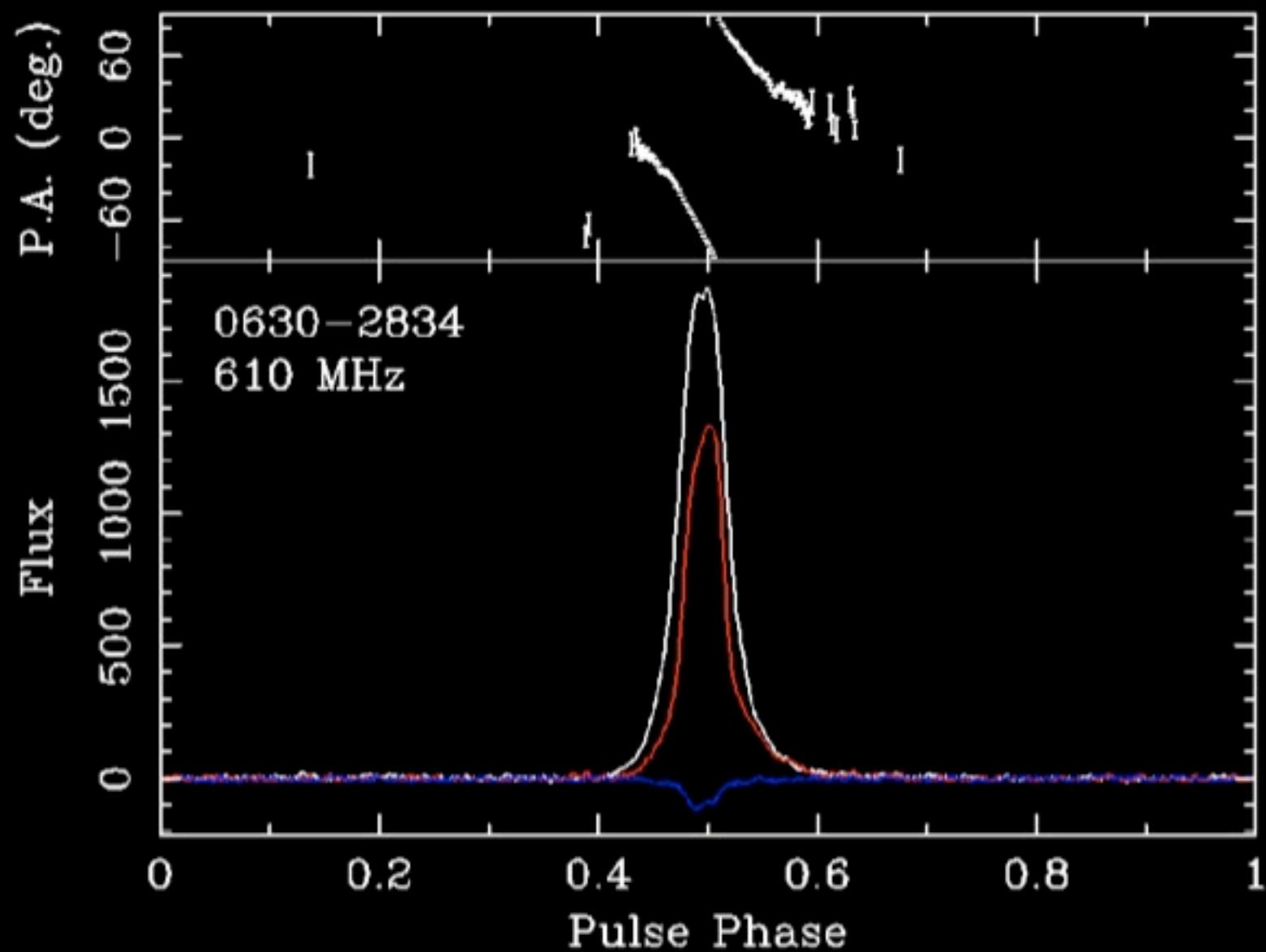
Animation Credit:  
Andrew Jameson



# Stokes Parameters - Cylindrical

$$L = \sqrt{Q^2 + U^2}$$

$$\psi = \frac{1}{2} \tan^{-1} \frac{U}{Q}$$

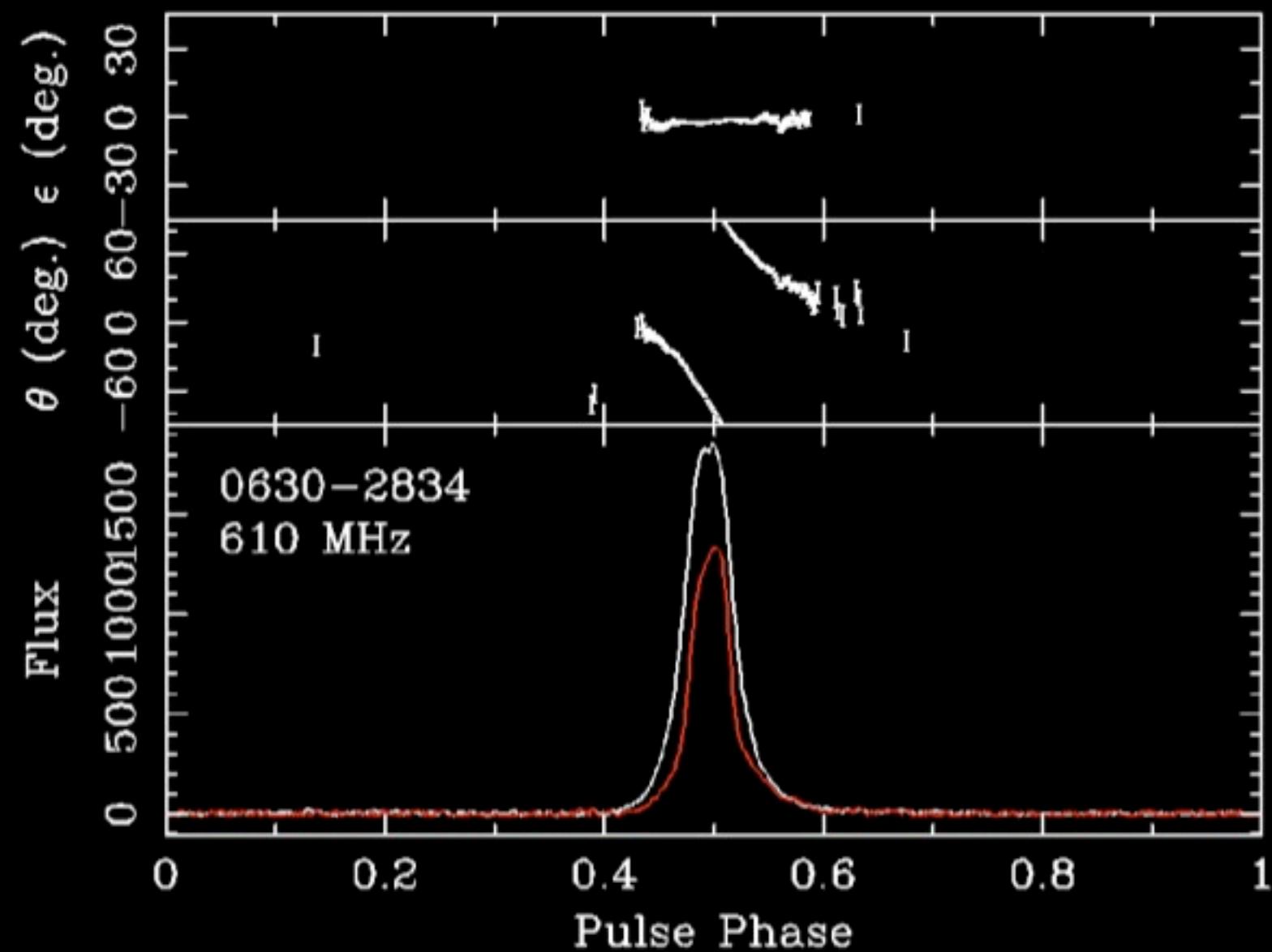


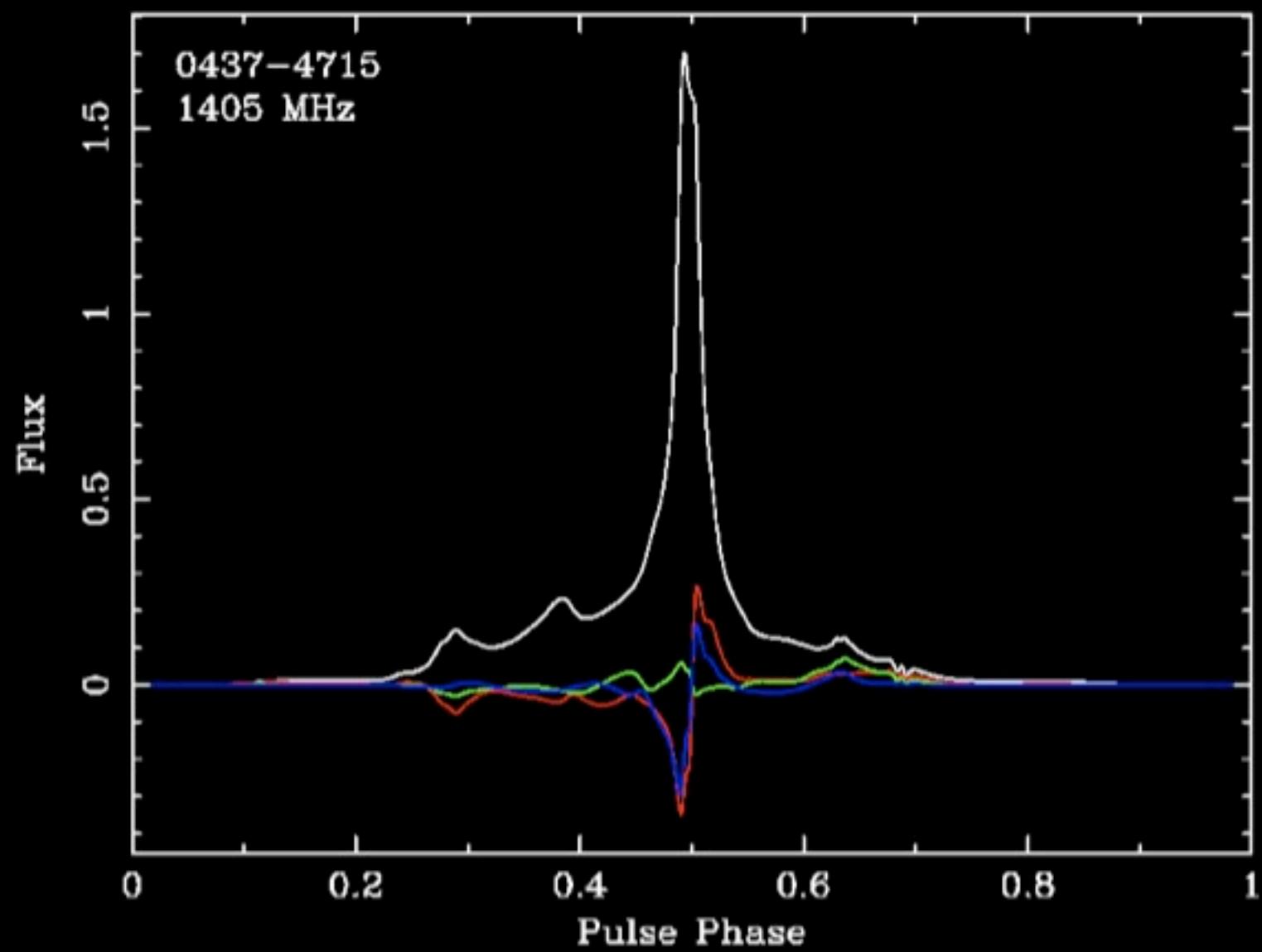
# Stokes Parameters - Spherical

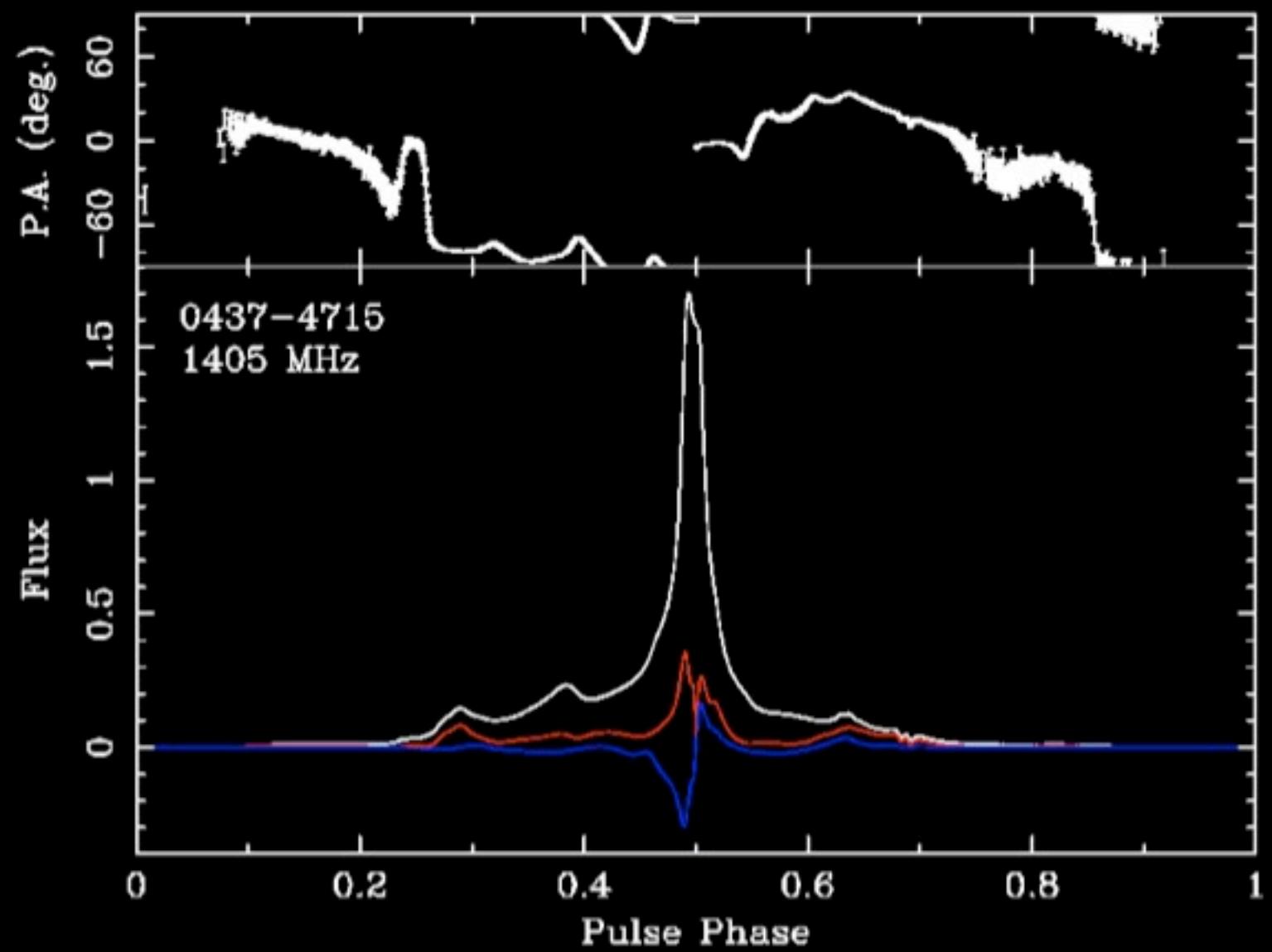
$$P = \sqrt{L^2 + V^2}$$

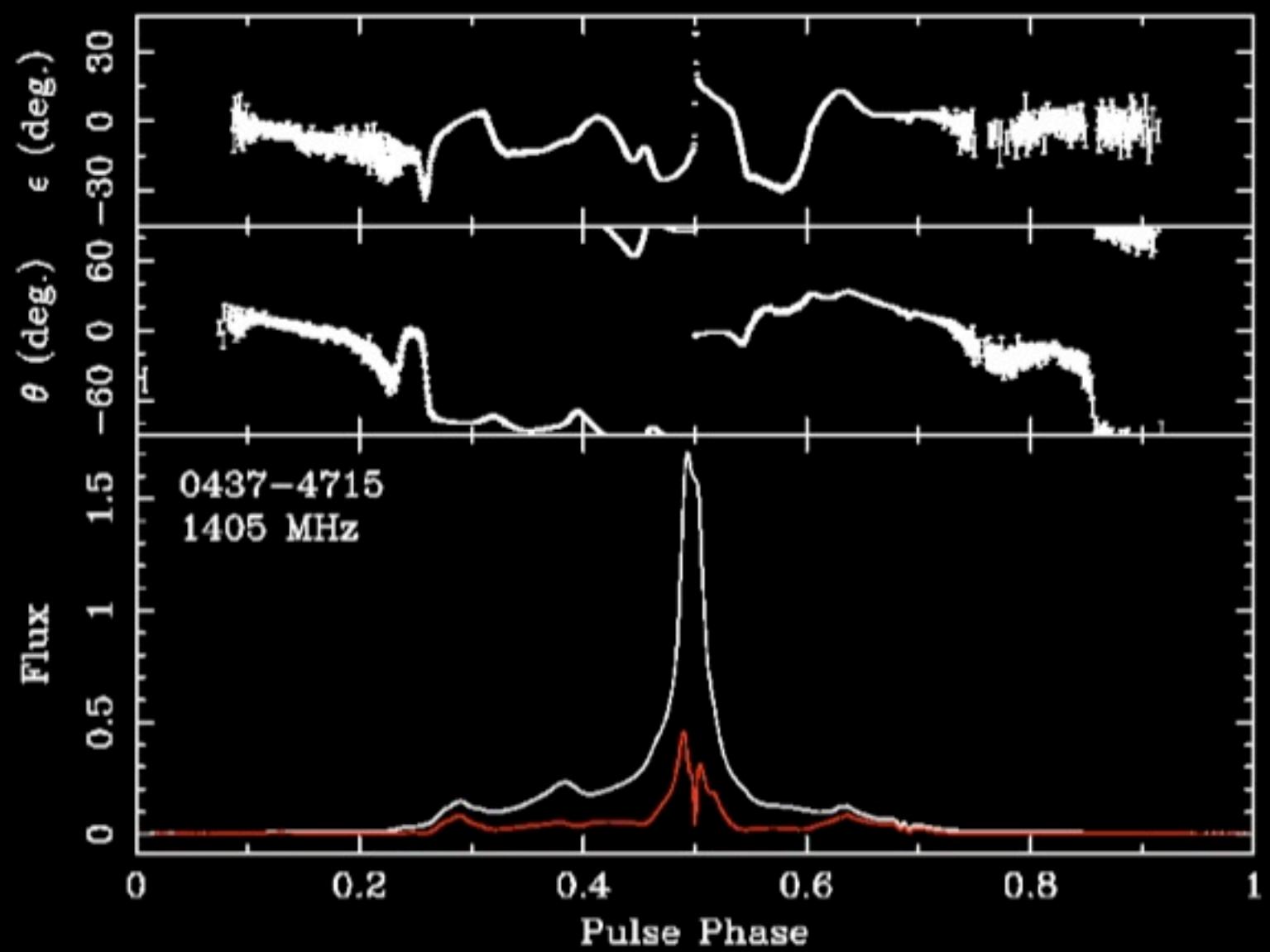
$$\psi = \frac{1}{2} \tan^{-1} \frac{U}{Q}$$

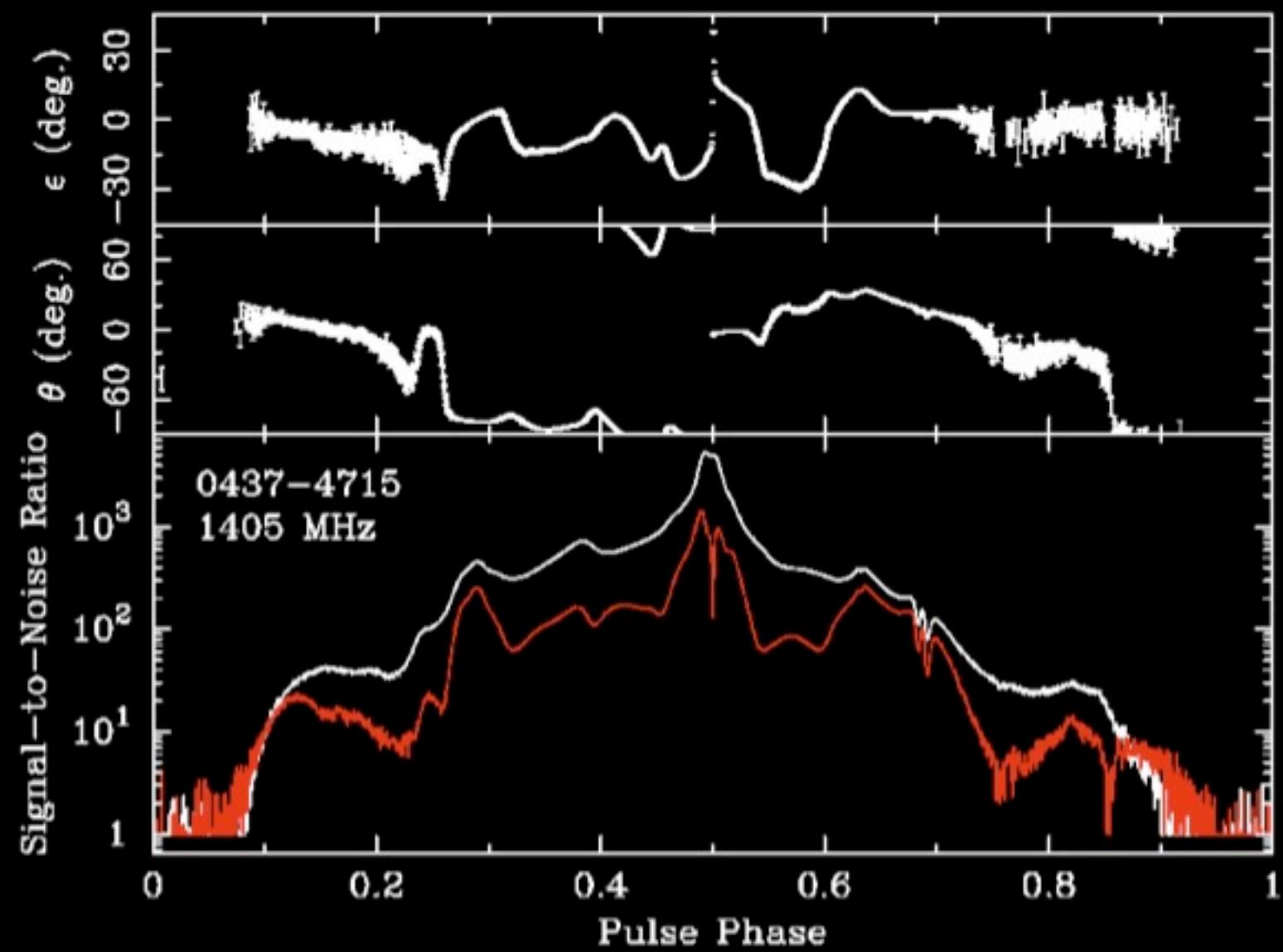
$$\chi = \frac{1}{2} \tan^{-1} \frac{V}{L}$$

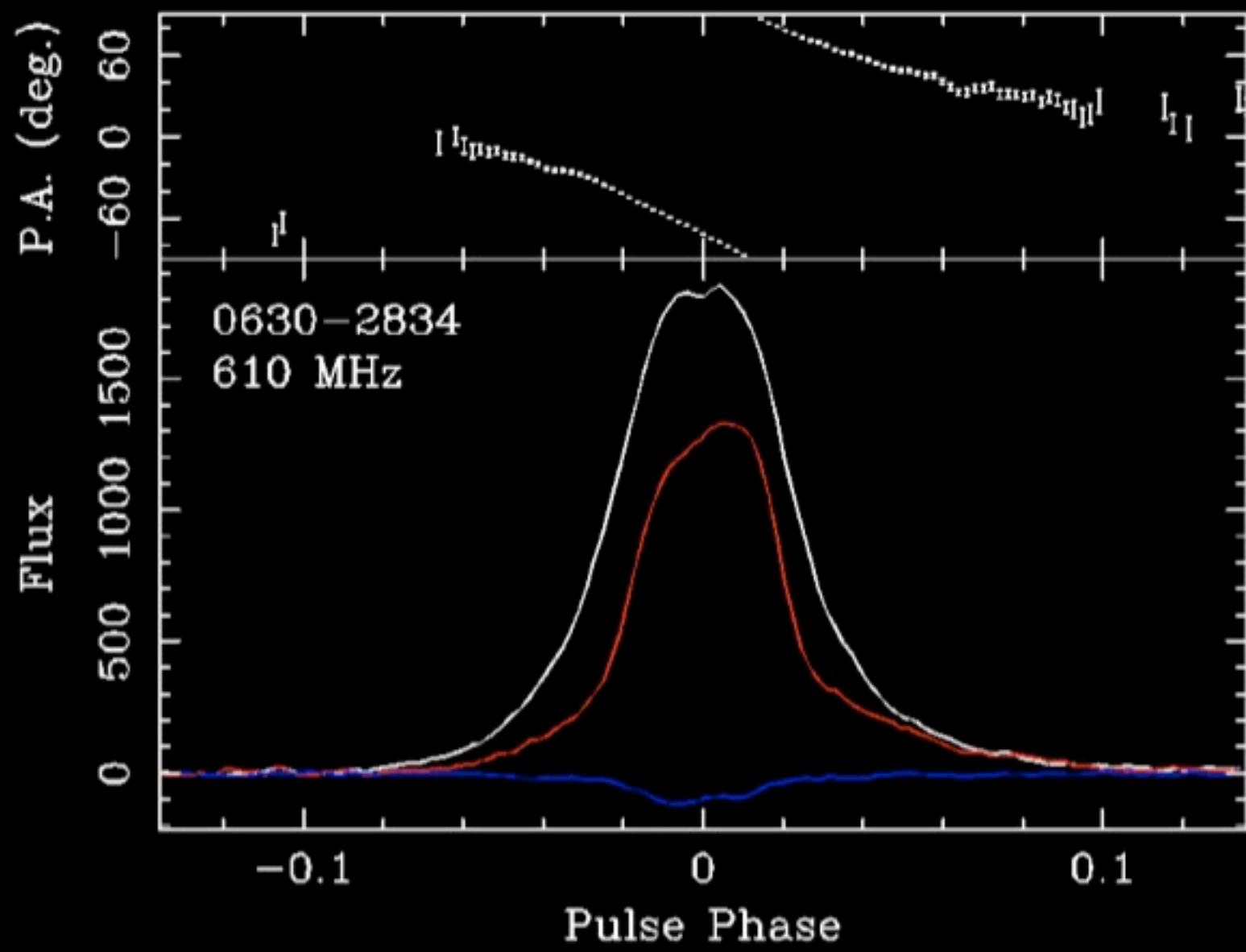


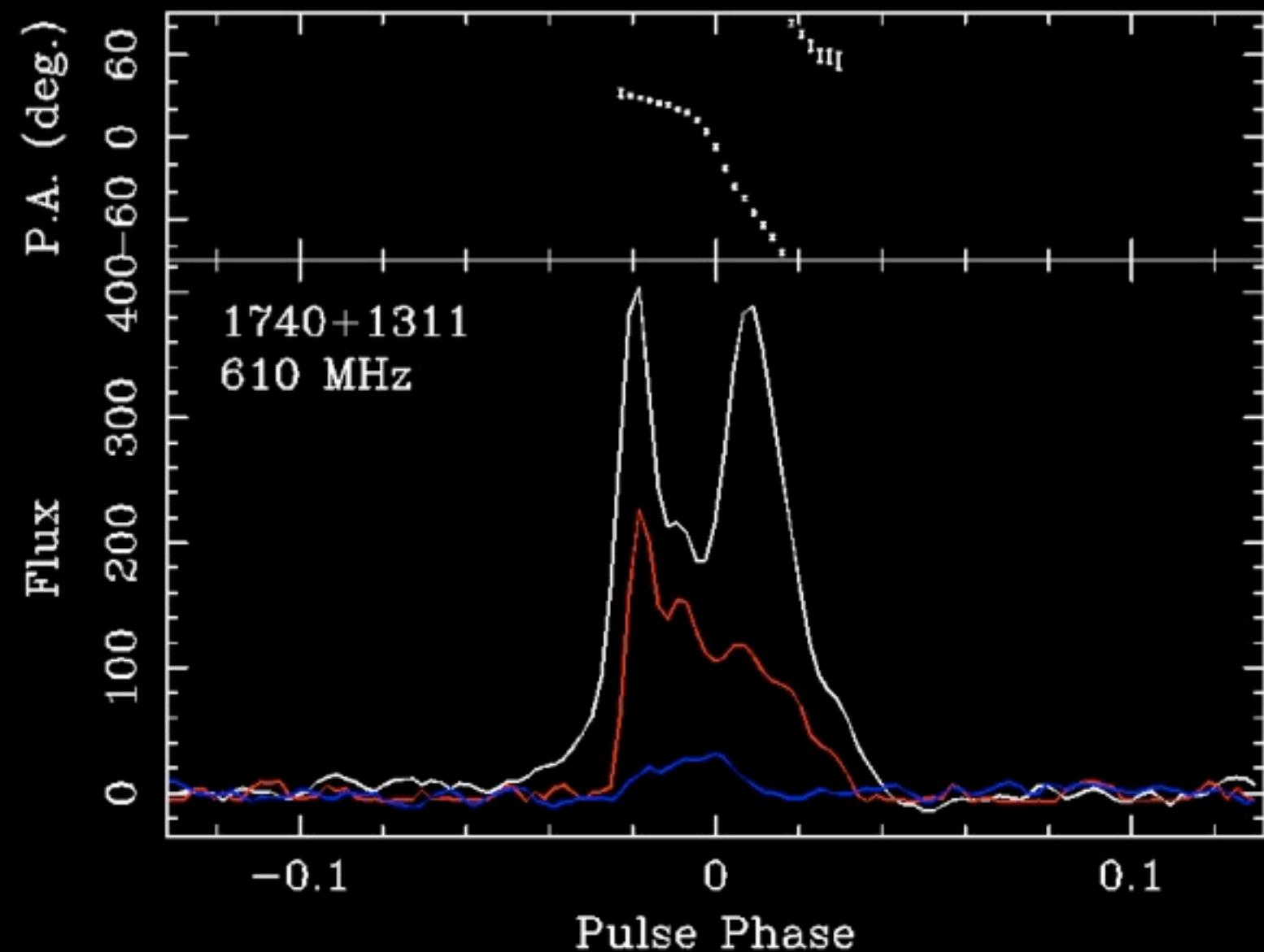


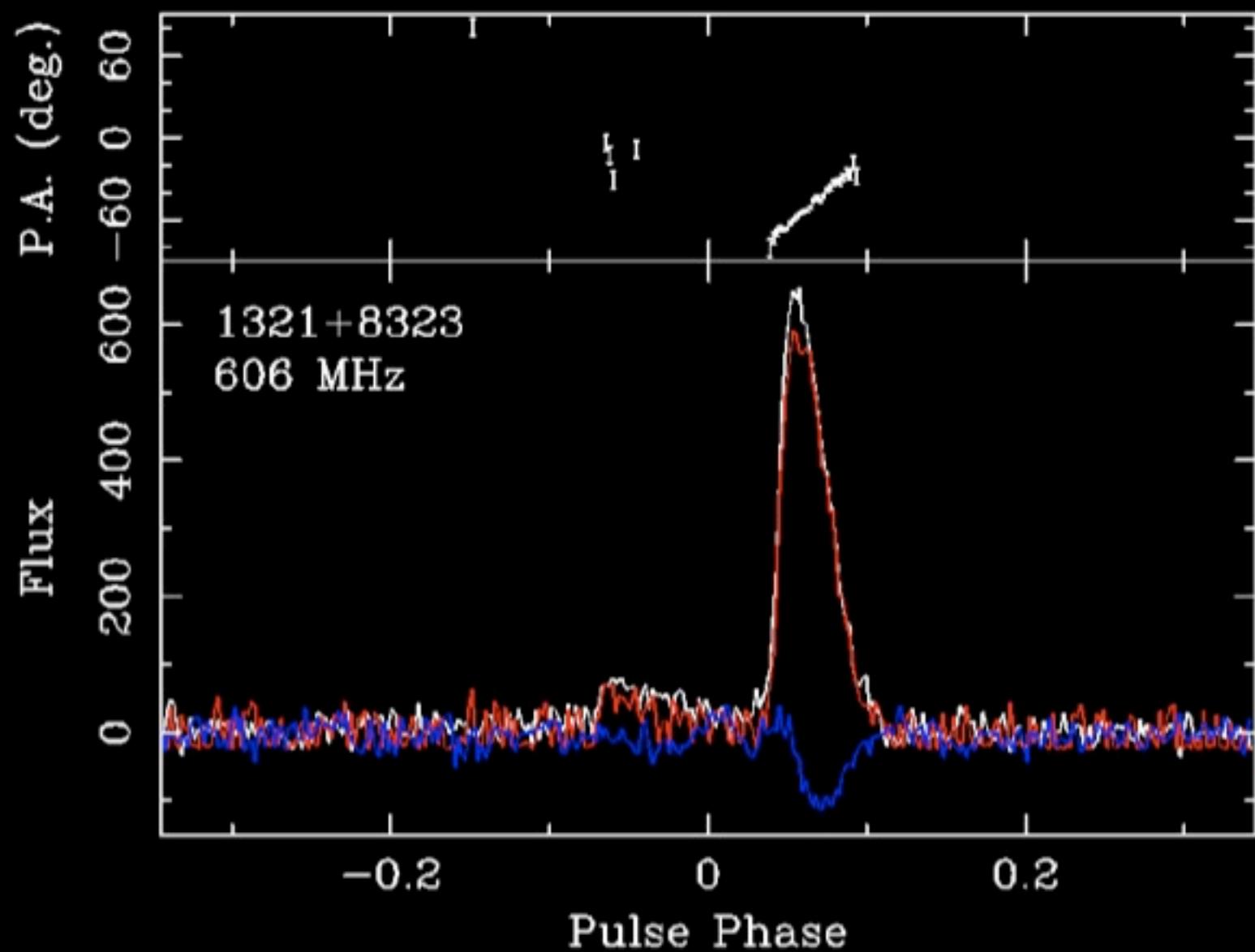


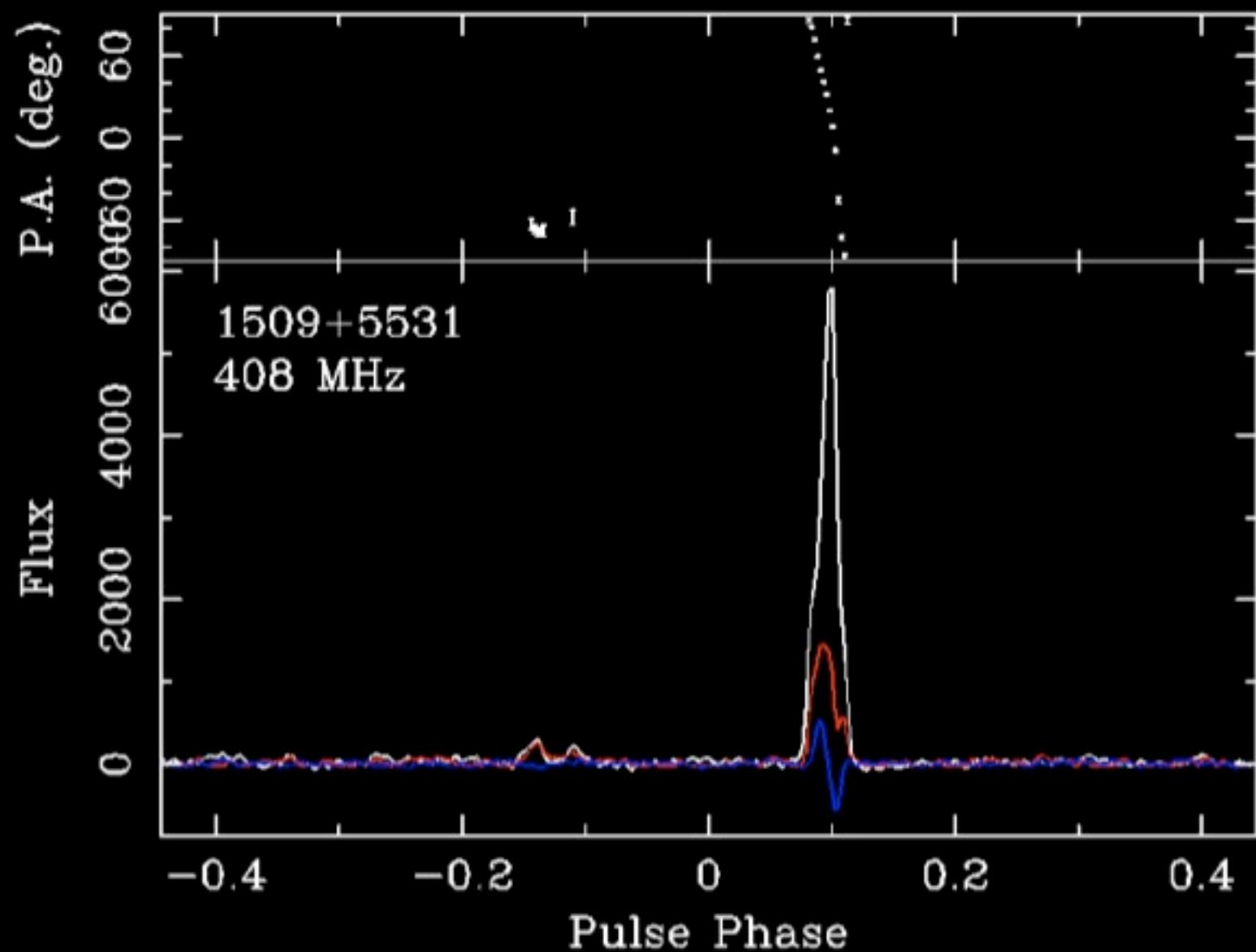


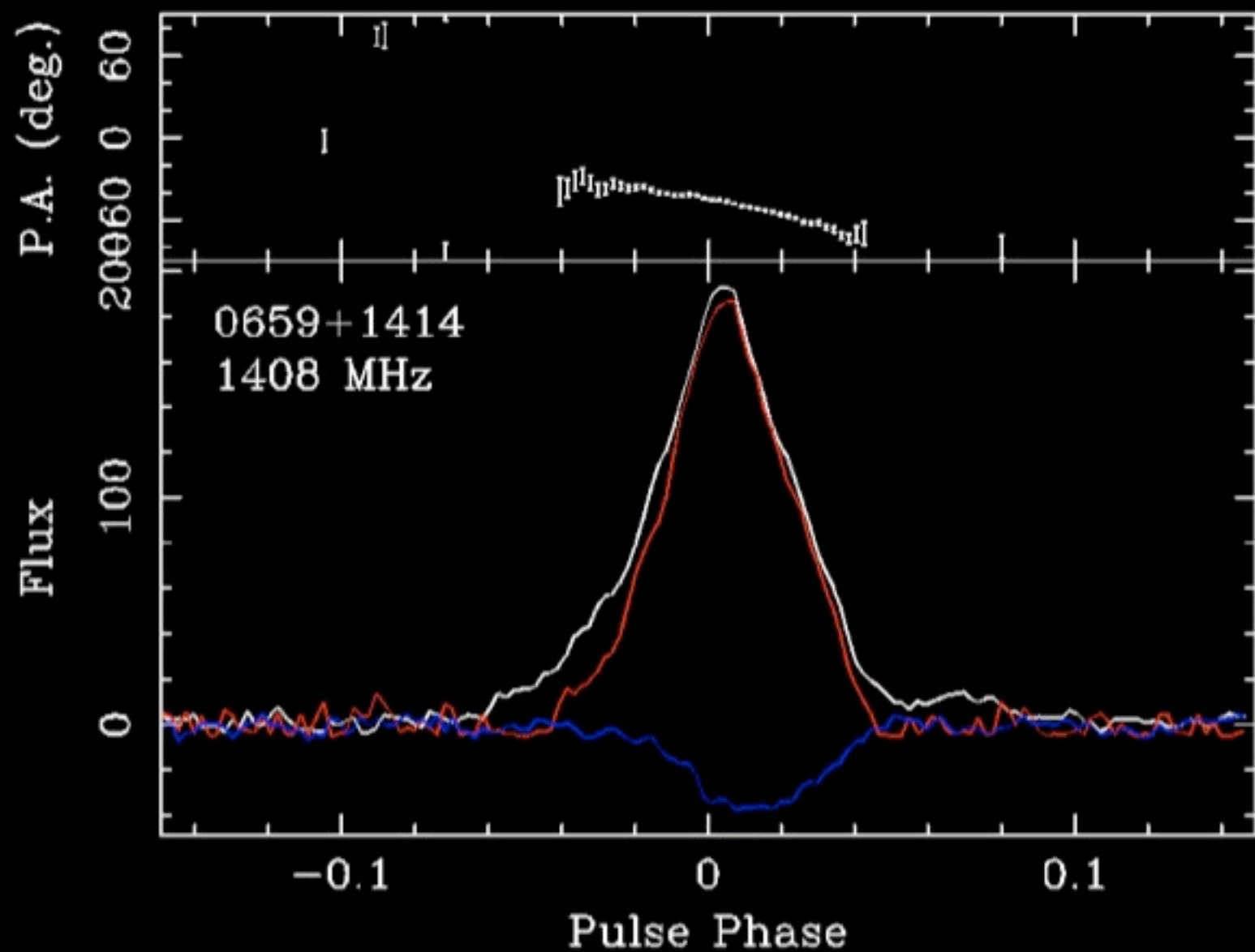


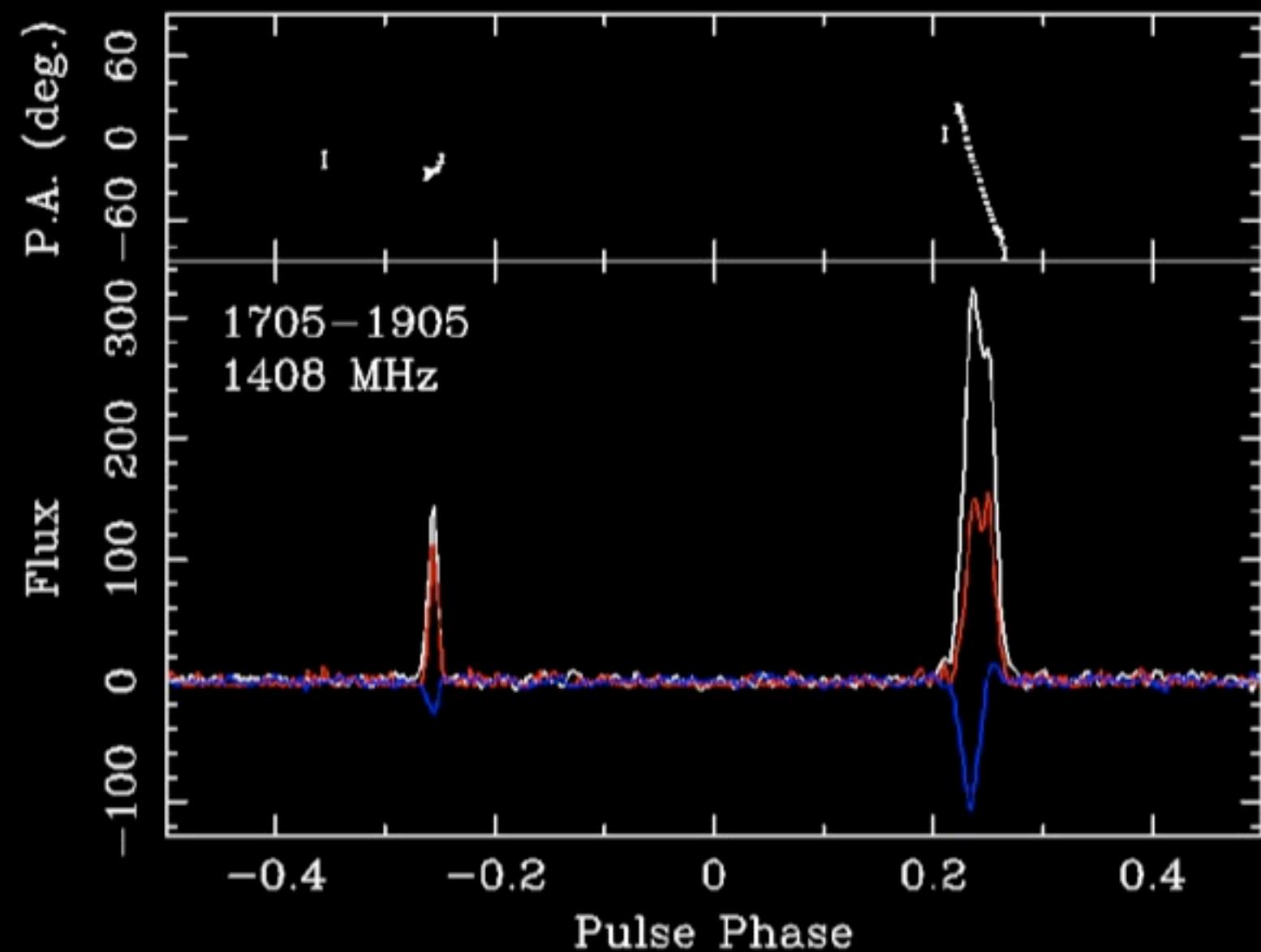


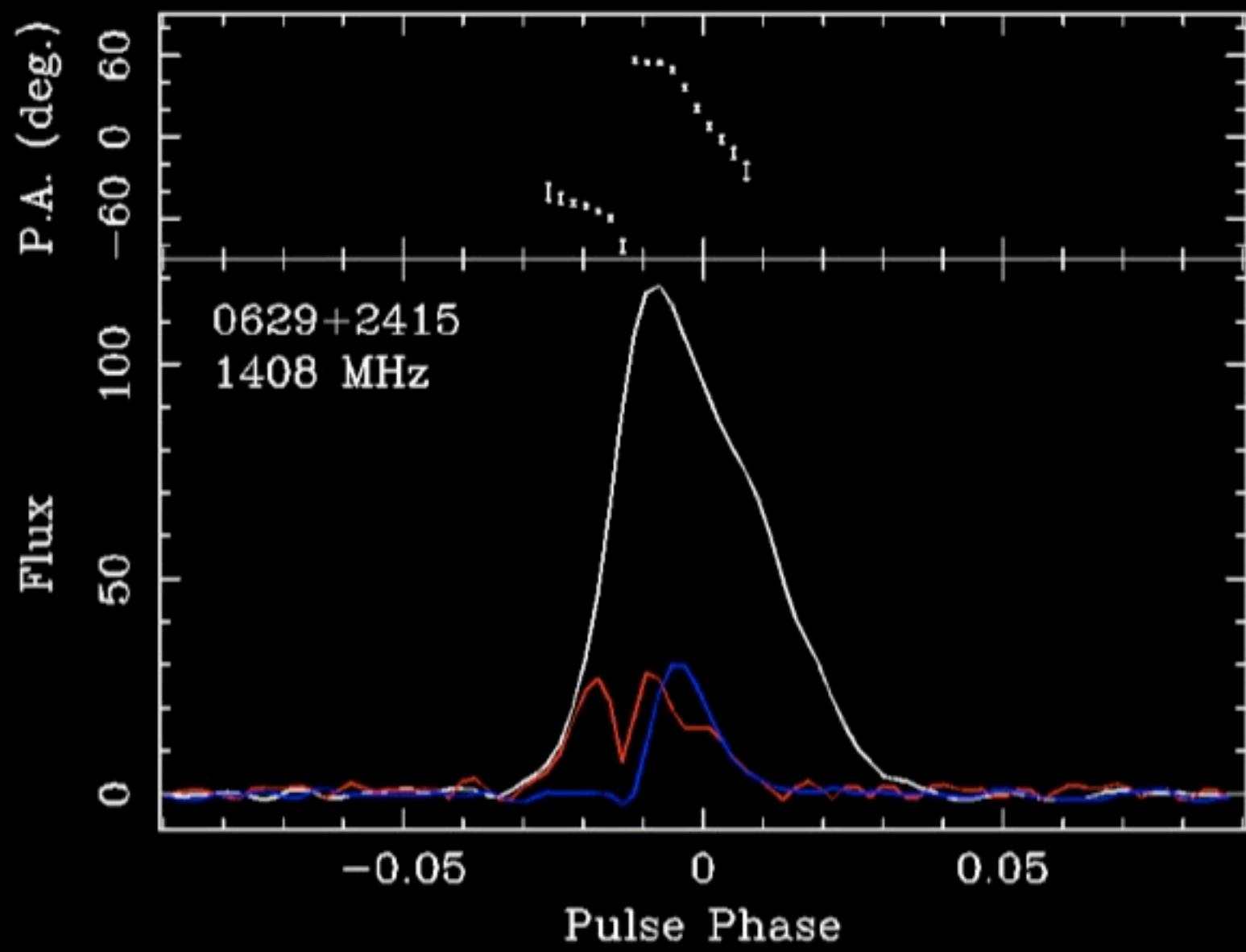


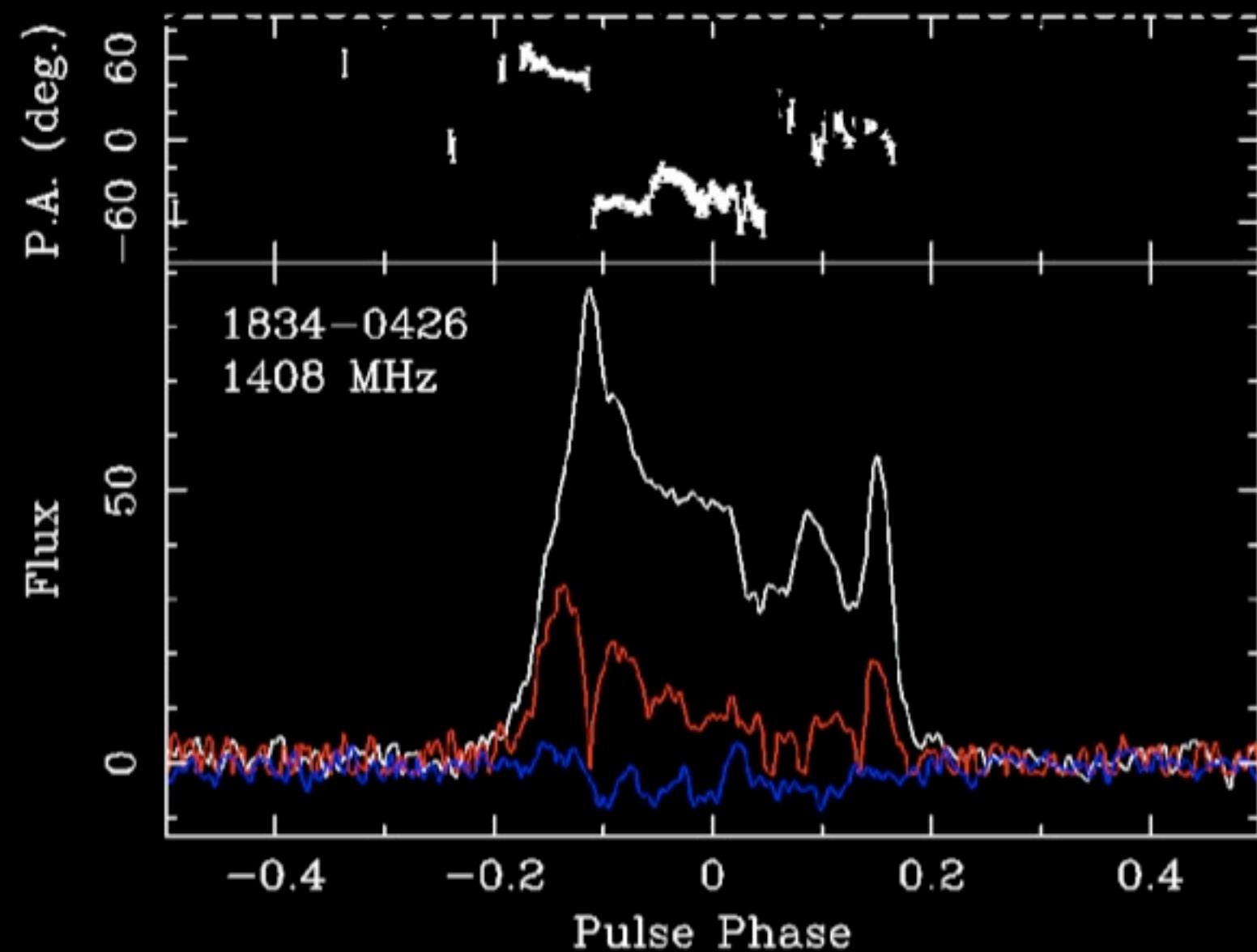


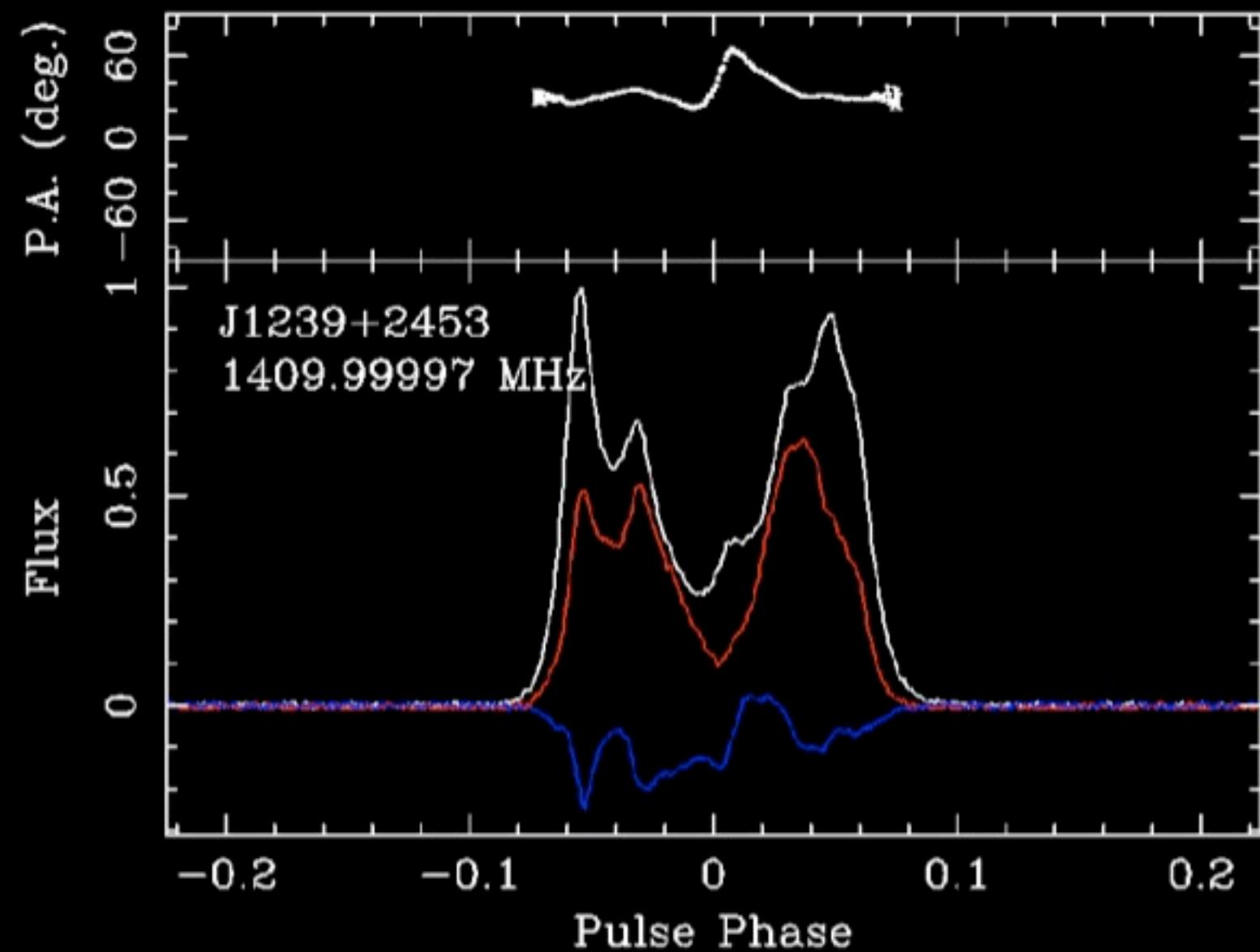


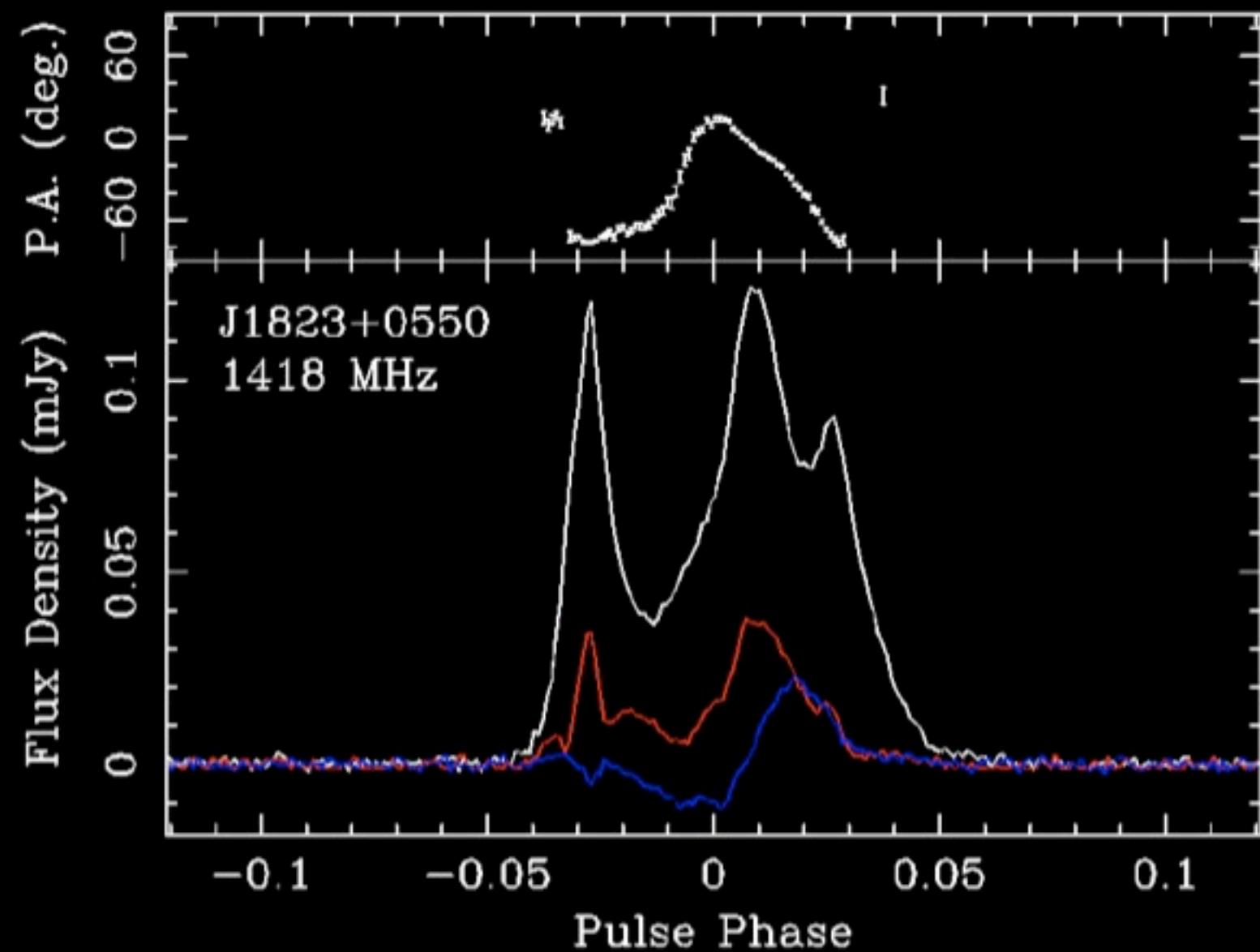






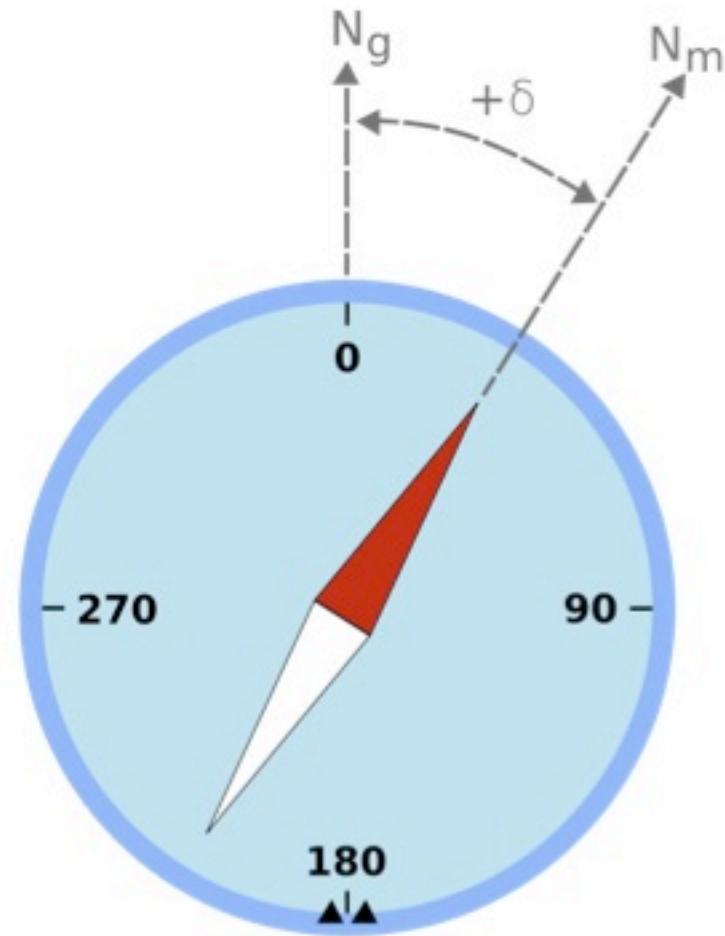




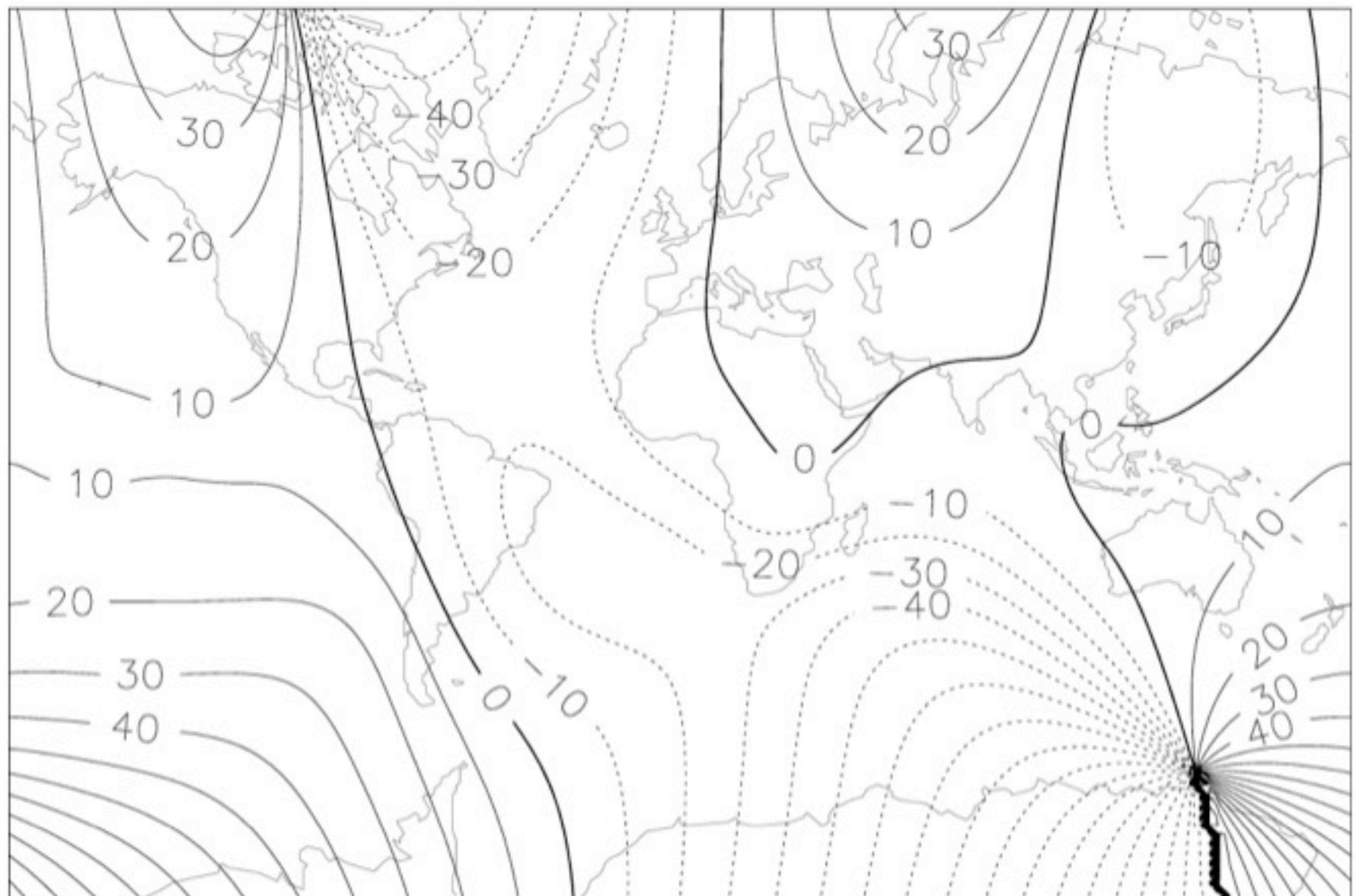


# Rotating Vector Model

- Like magnetic declination on Earth

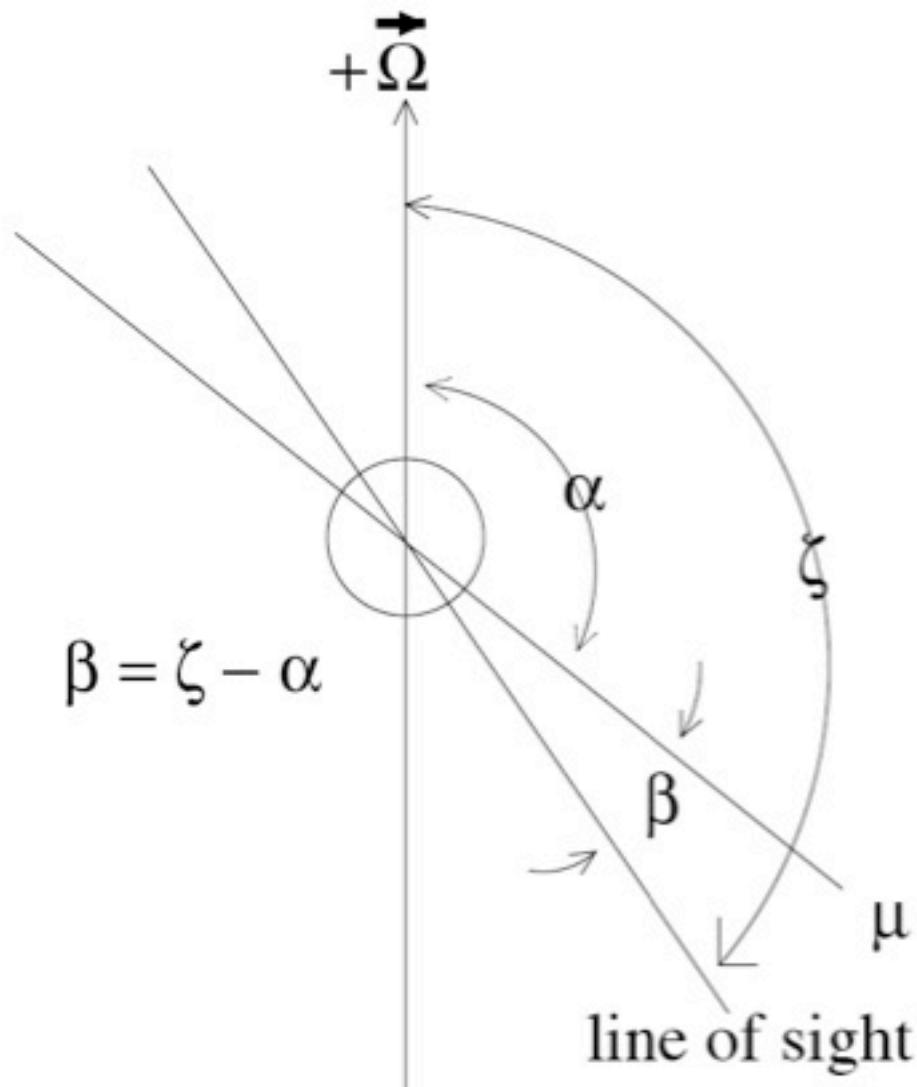


2000  
Declination (degrees east)



International Geomagnetic Reference Field (IGRF)

<http://geomag.usgs.gov>



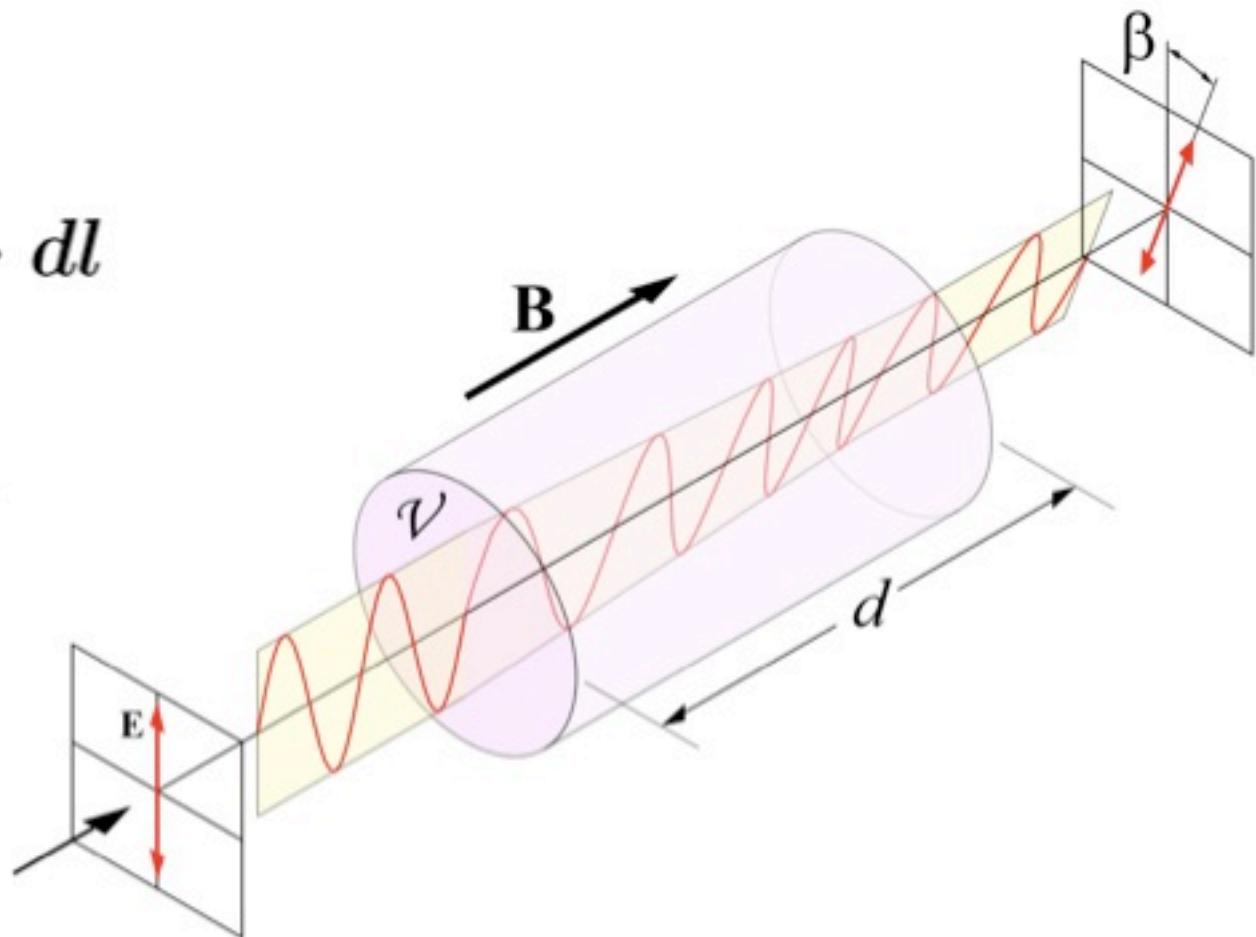
$$\tan(\psi' - \psi'_0) = \frac{\sin \alpha \sin (\phi - \phi_0)}{\sin \zeta \cos \alpha - \cos \zeta \sin \alpha \cos (\phi - \phi_0)}$$

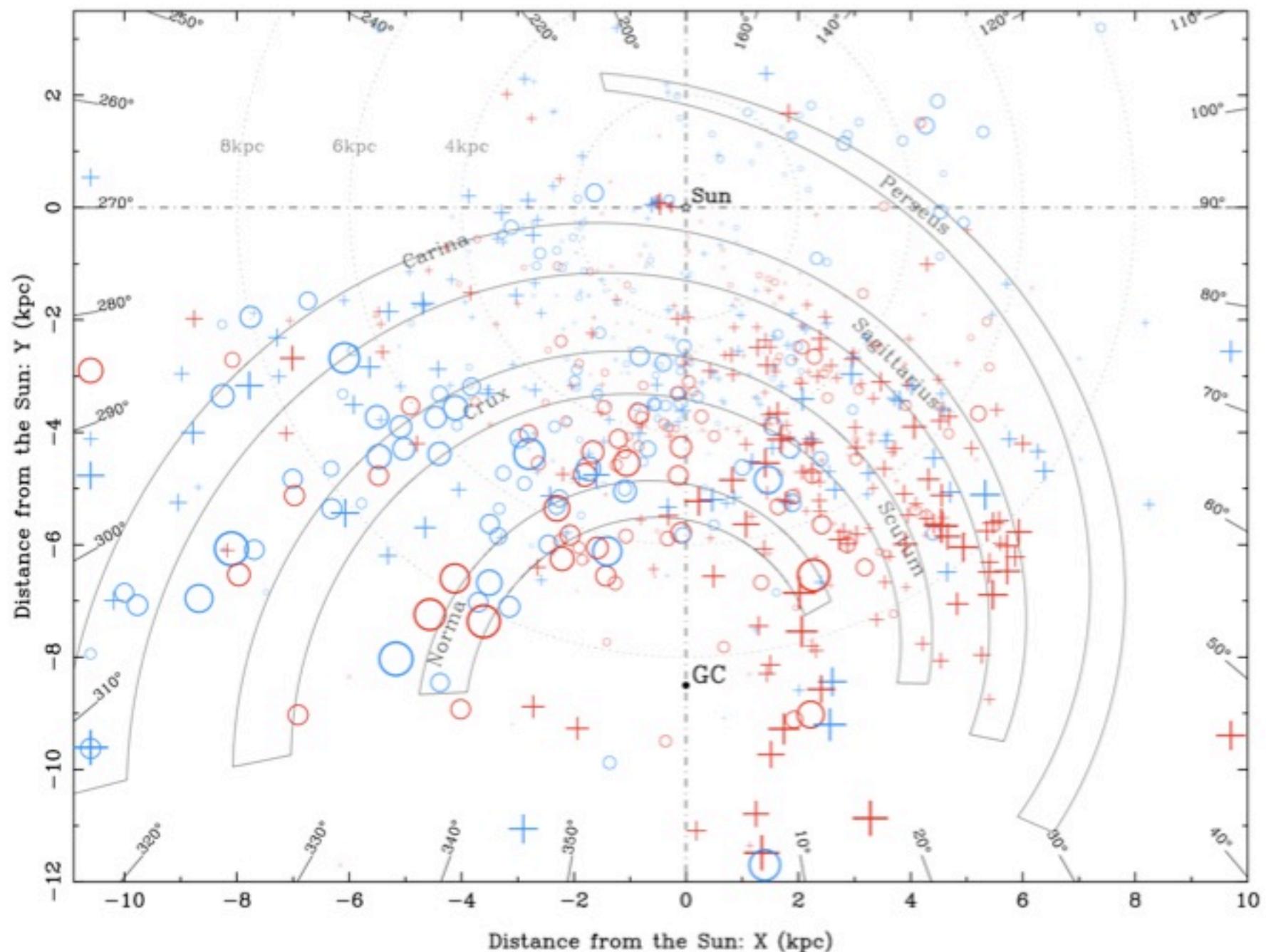
# Faraday Rotation

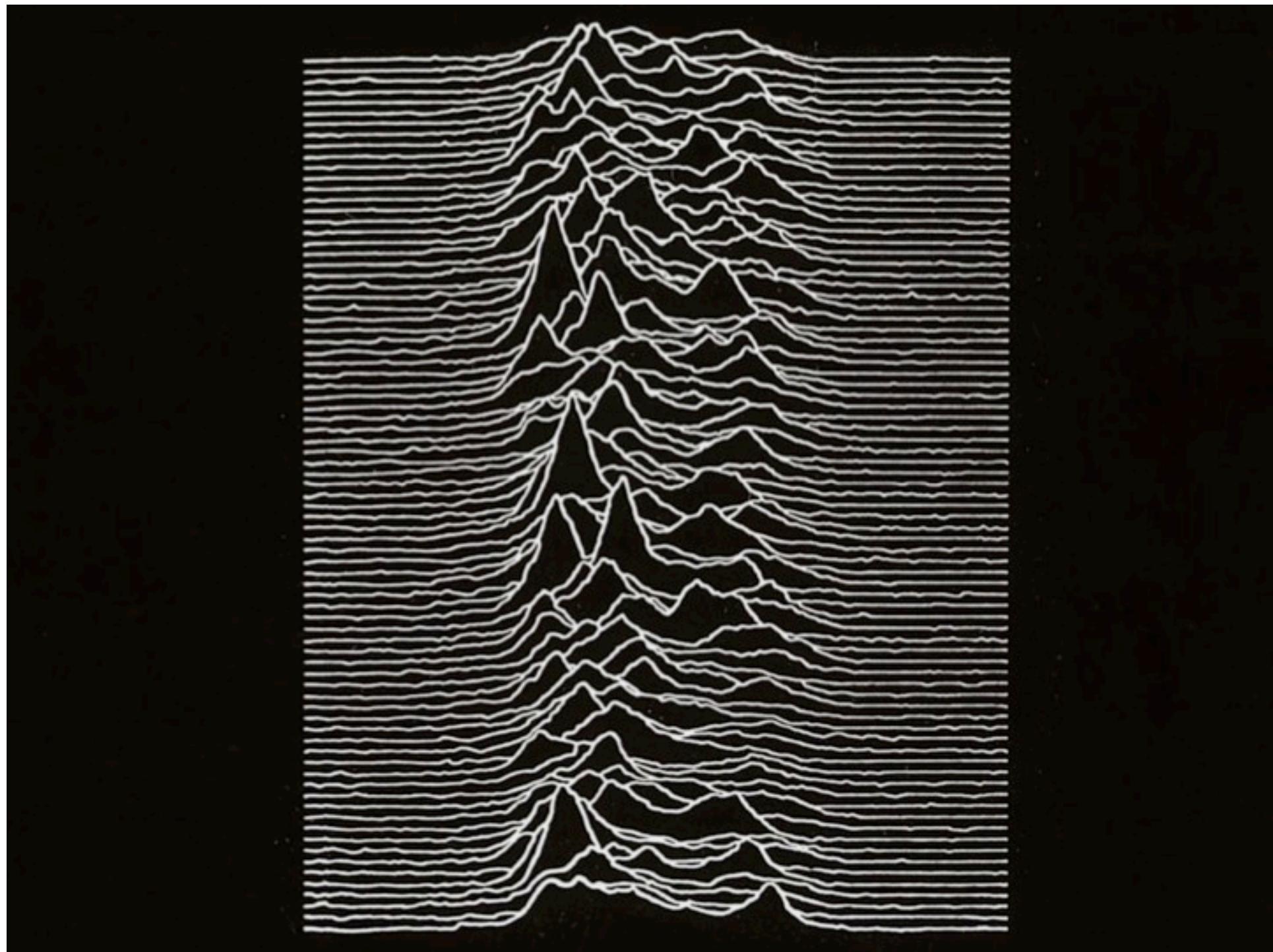
$$DM \propto \int_0^D n_e dl$$

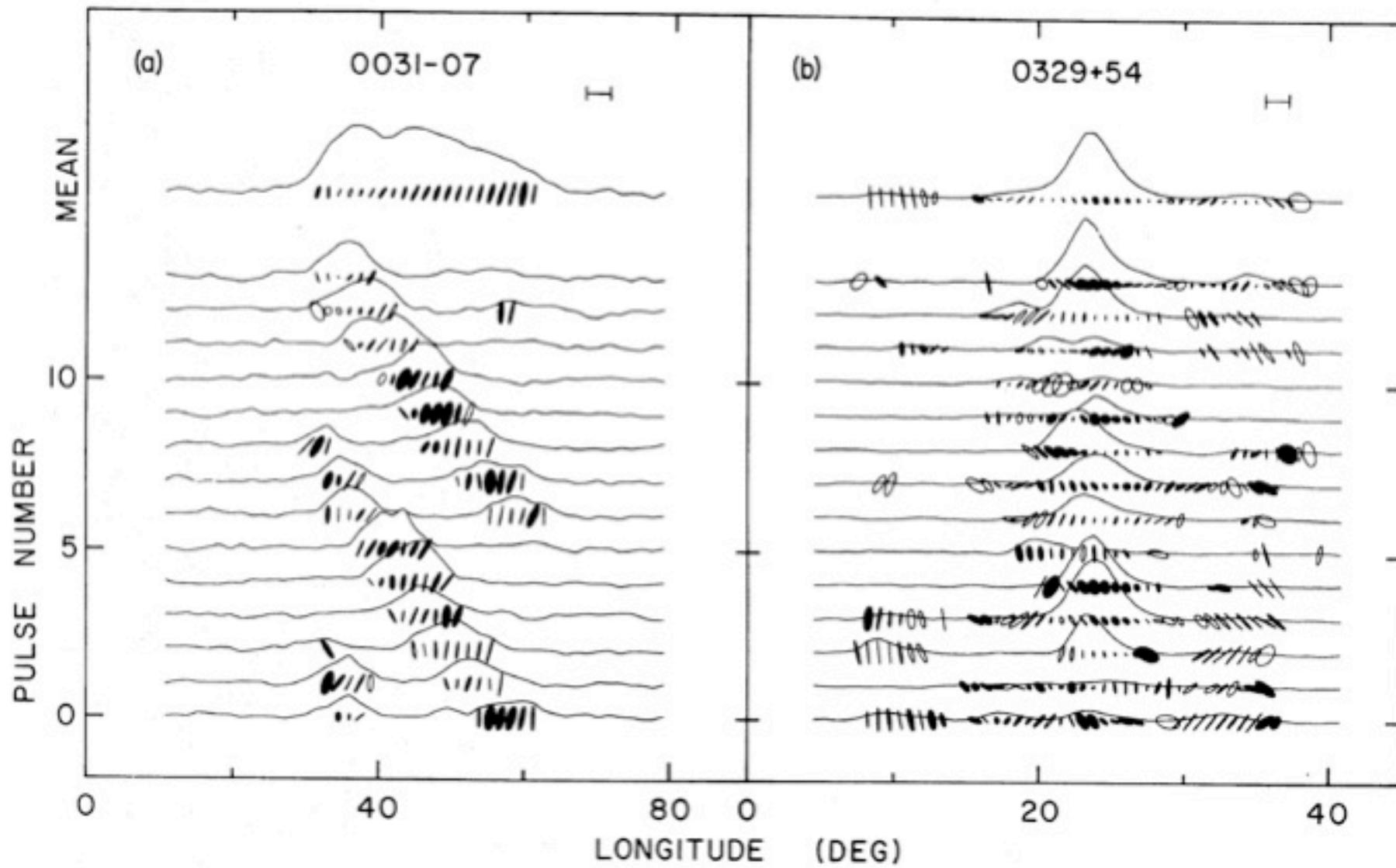
$$RM \propto \int_0^D n_e \mathbf{B} \cdot d\mathbf{l}$$

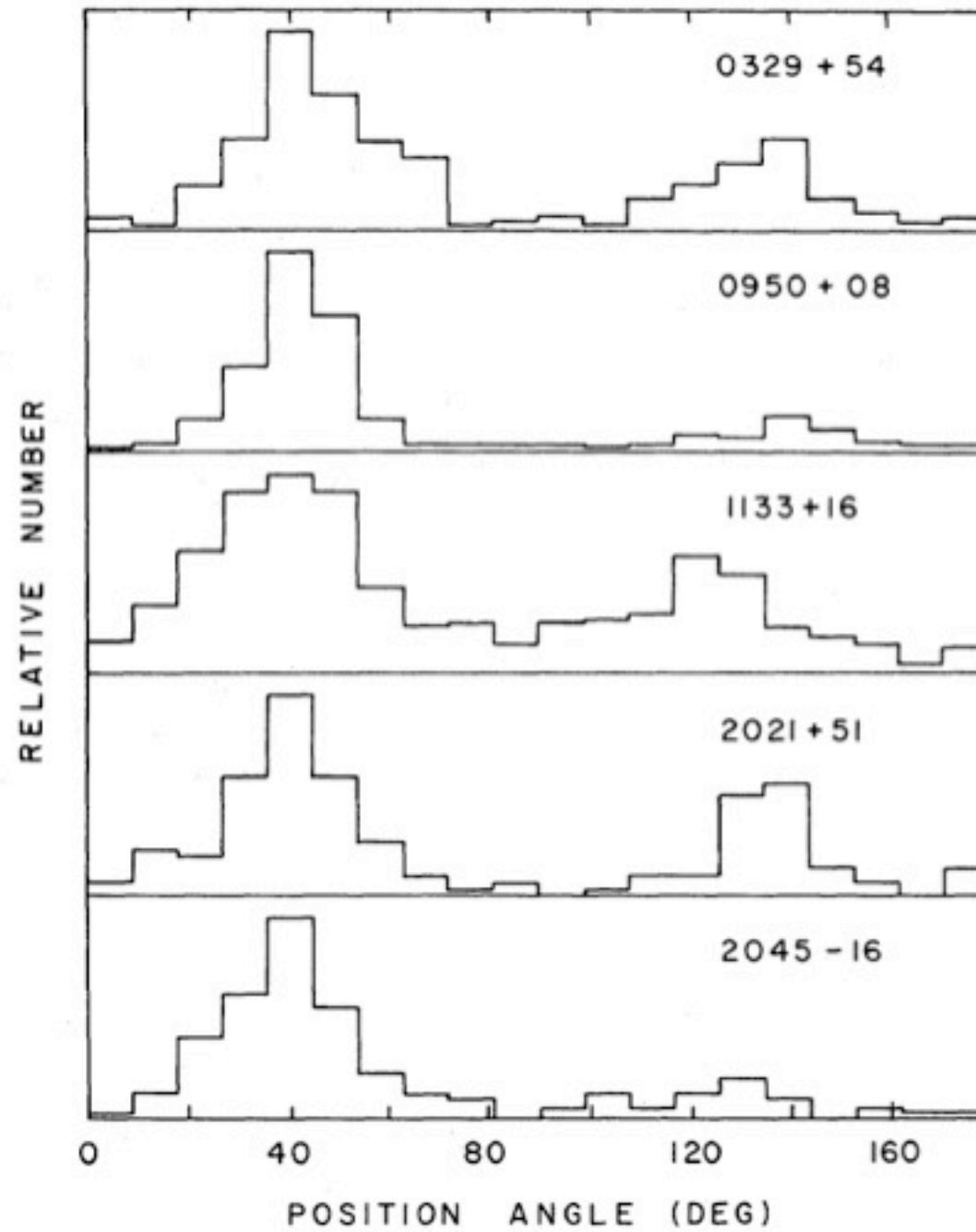
$$\langle B_{\parallel} \rangle \propto RM/DM$$

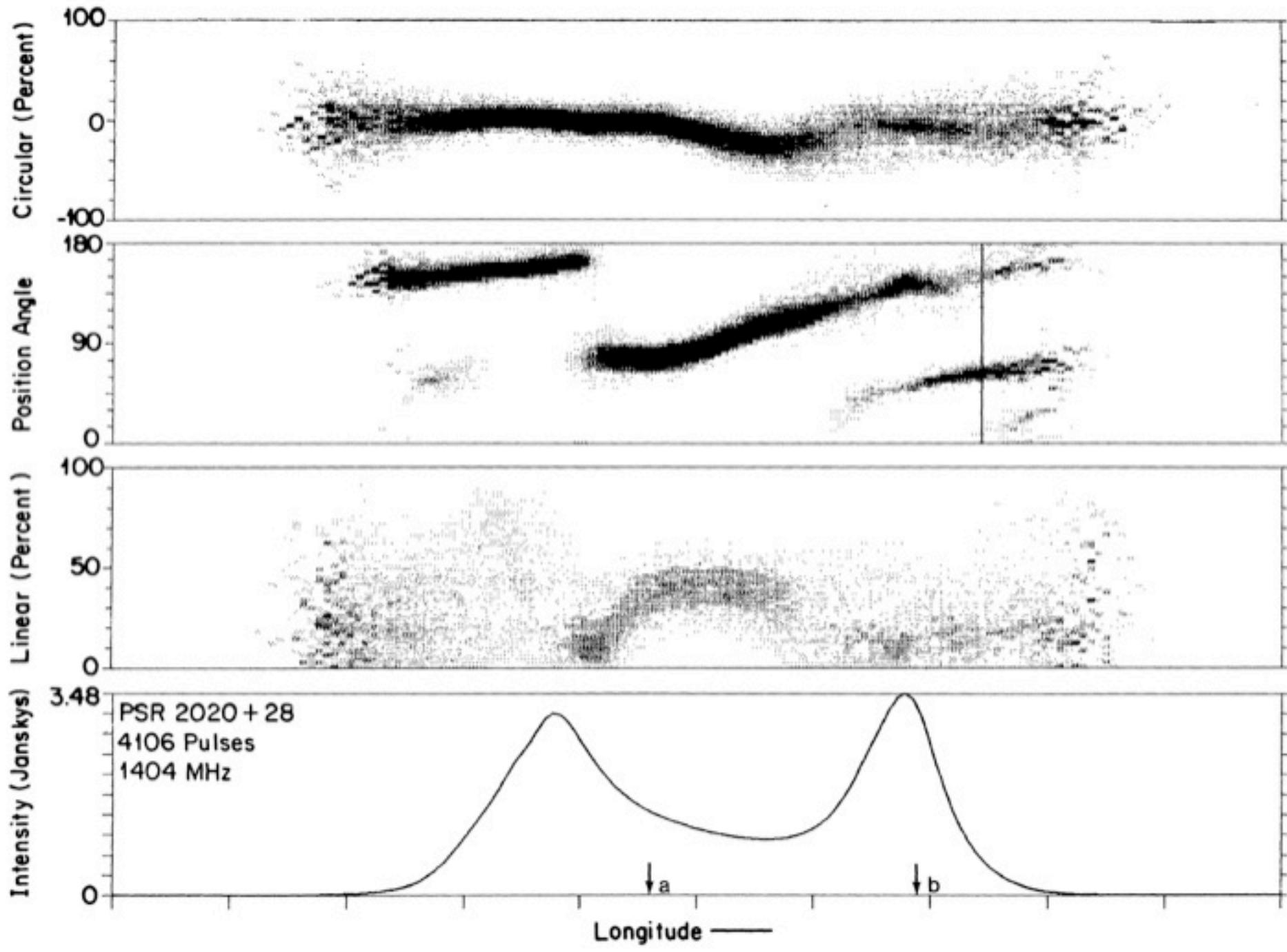


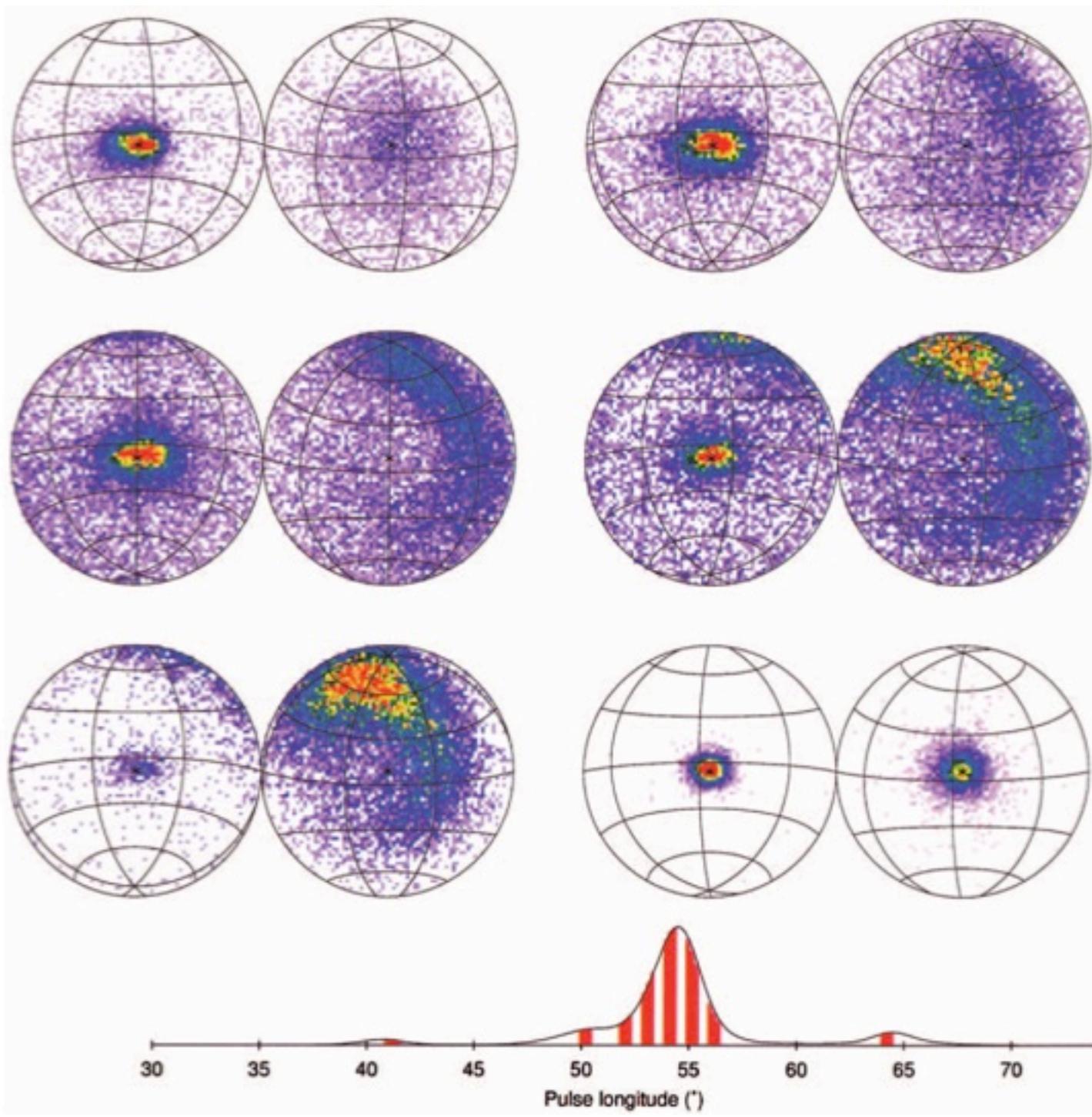


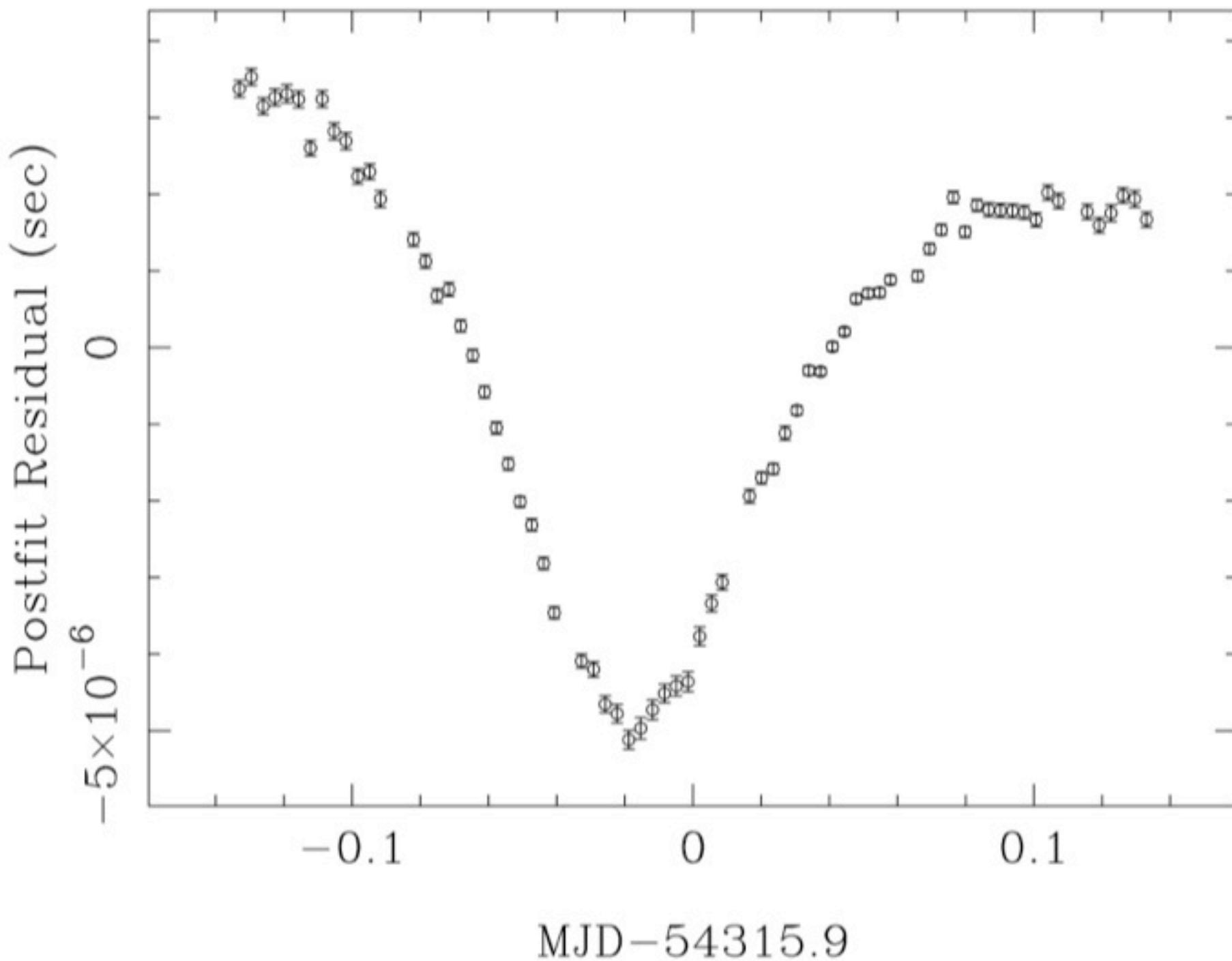


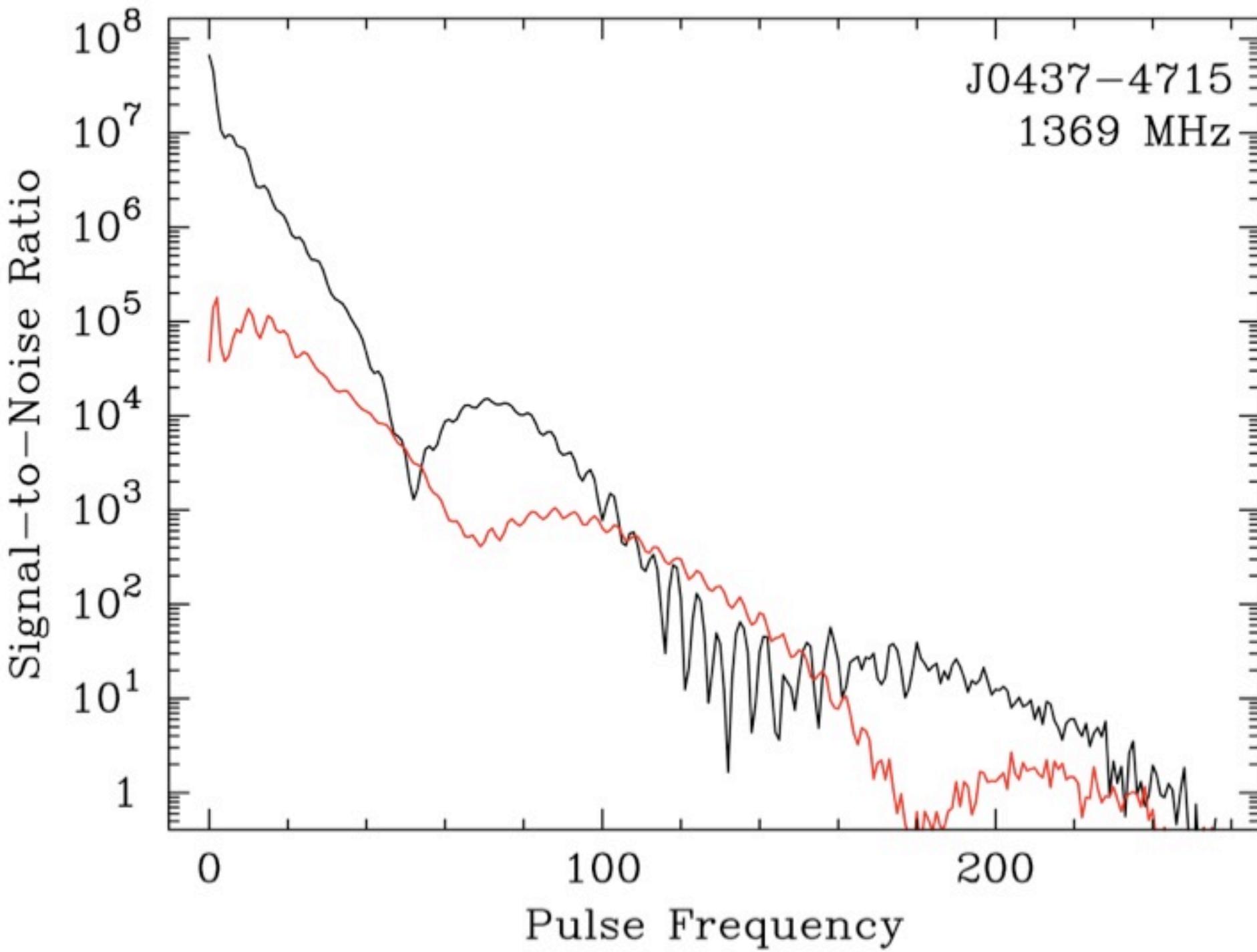












# Calibration

$$e' = \mathbf{J}e \quad \text{Jones matrix, } \mathbf{J}$$

$$\rho' = \mathbf{J}\rho\mathbf{J}^\dagger$$

$$S'_i = M_i^k S_k \quad \text{Mueller matrix, } \mathbf{M}$$

$$M_i^k = \frac{1}{2} \text{Tr}(\boldsymbol{\sigma}_i \mathbf{J} \boldsymbol{\sigma}_k \mathbf{J}^\dagger)$$

# 7 degrees of freedom

$$\hat{\mathbf{J}} = \mathbf{J} e^{i\phi}$$

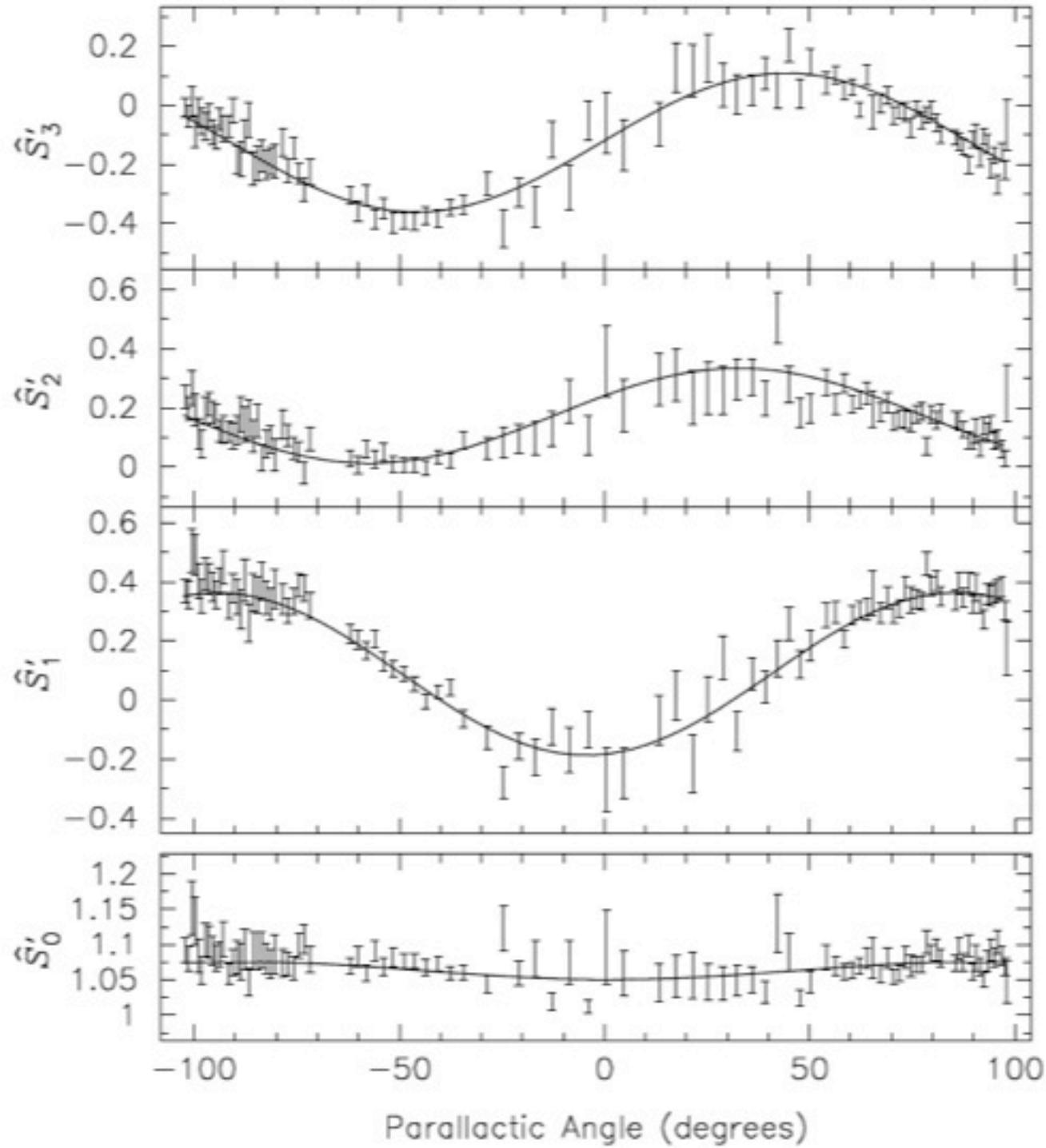
$$\begin{aligned}\rho' &= \hat{\mathbf{J}} \rho \hat{\mathbf{J}}^\dagger \\ &= \mathbf{J} e^{i\phi} \rho e^{-i\phi} \mathbf{J}^\dagger \\ &= \mathbf{J} \rho \mathbf{J}^\dagger\end{aligned}$$

# Receptor parameterisation

$$e = r^\dagger e$$

$$\mathbf{r} = g e^{i\phi} \begin{pmatrix} \cos \theta \cos \epsilon + i \sin \theta \sin \epsilon \\ \sin \theta \cos \epsilon - i \cos \theta \sin \epsilon \end{pmatrix}$$

$$\mathbf{J} = (\mathbf{r}_0 \ \mathbf{r}_1)^\dagger$$



# No Unique Solution

$$S' = \mathbf{M} \mathbf{R}_v(\Psi) S$$

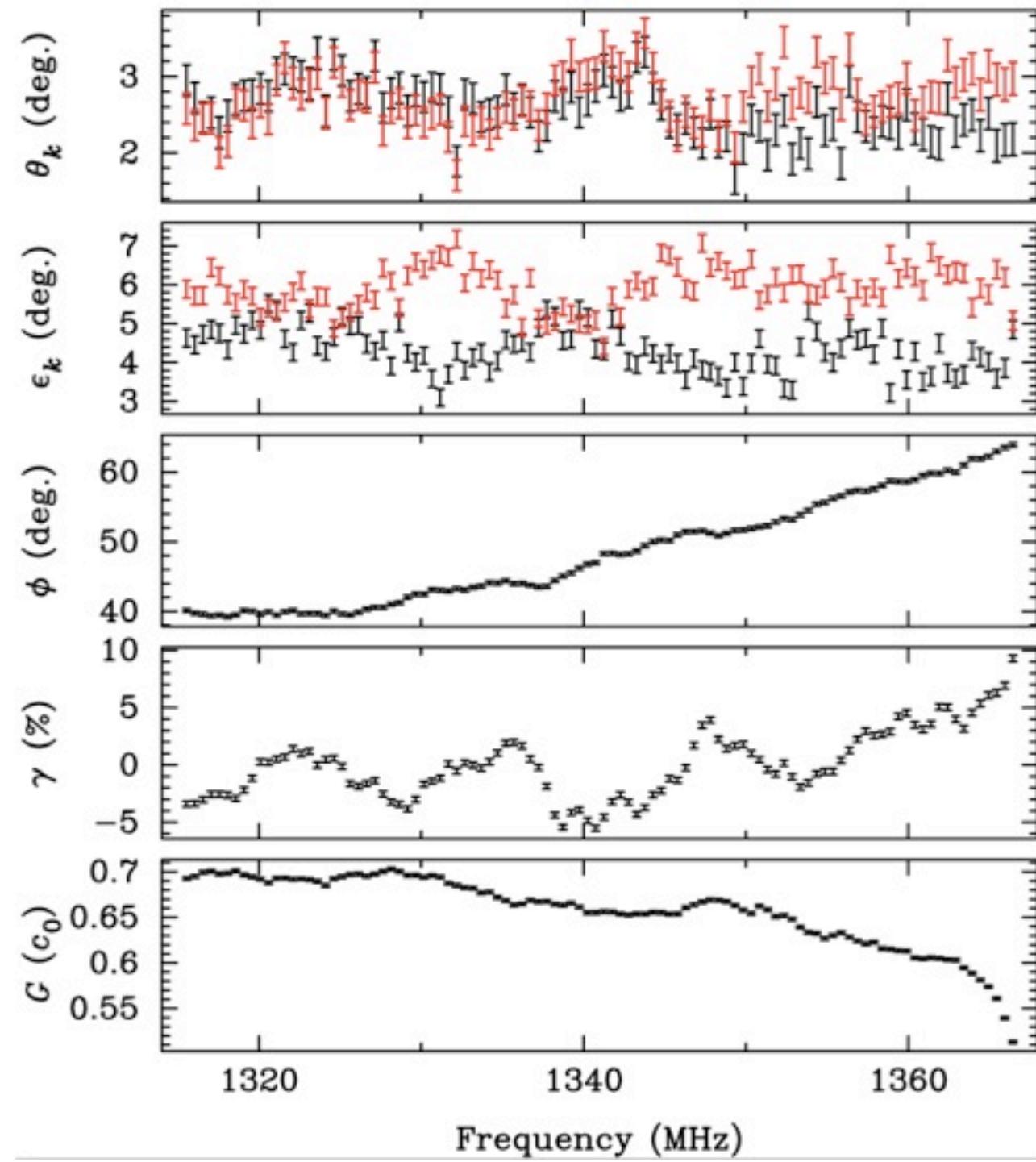
(cf.  $const = xy$ )

$$S' = \mathbf{M}^u \mathbf{R}_v(\Psi) S^u$$

$$\mathbf{M}^u = \mathbf{M} \mathbf{U}_v^{-1}$$

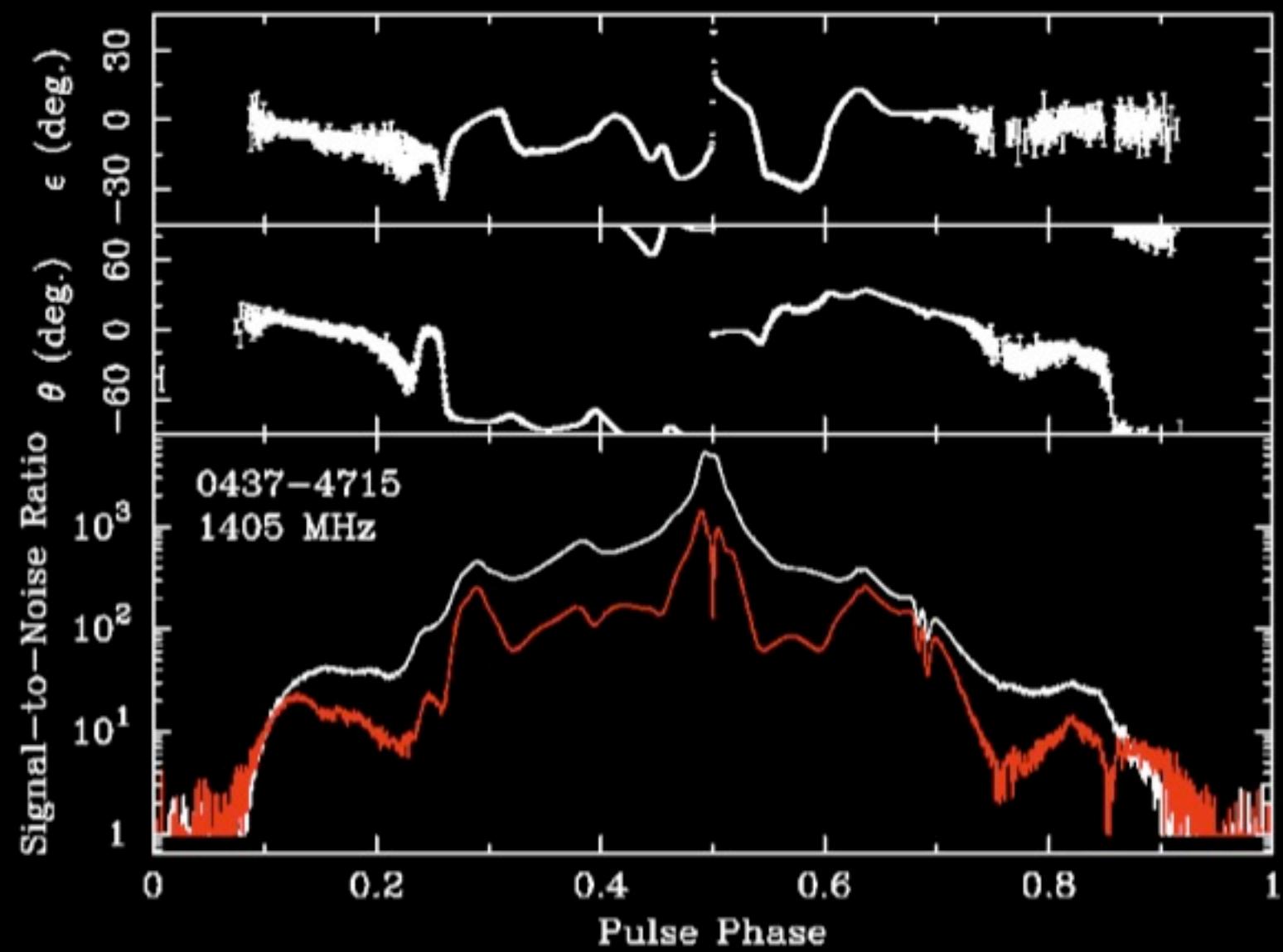
$$S^u = \mathbf{U}_v S$$

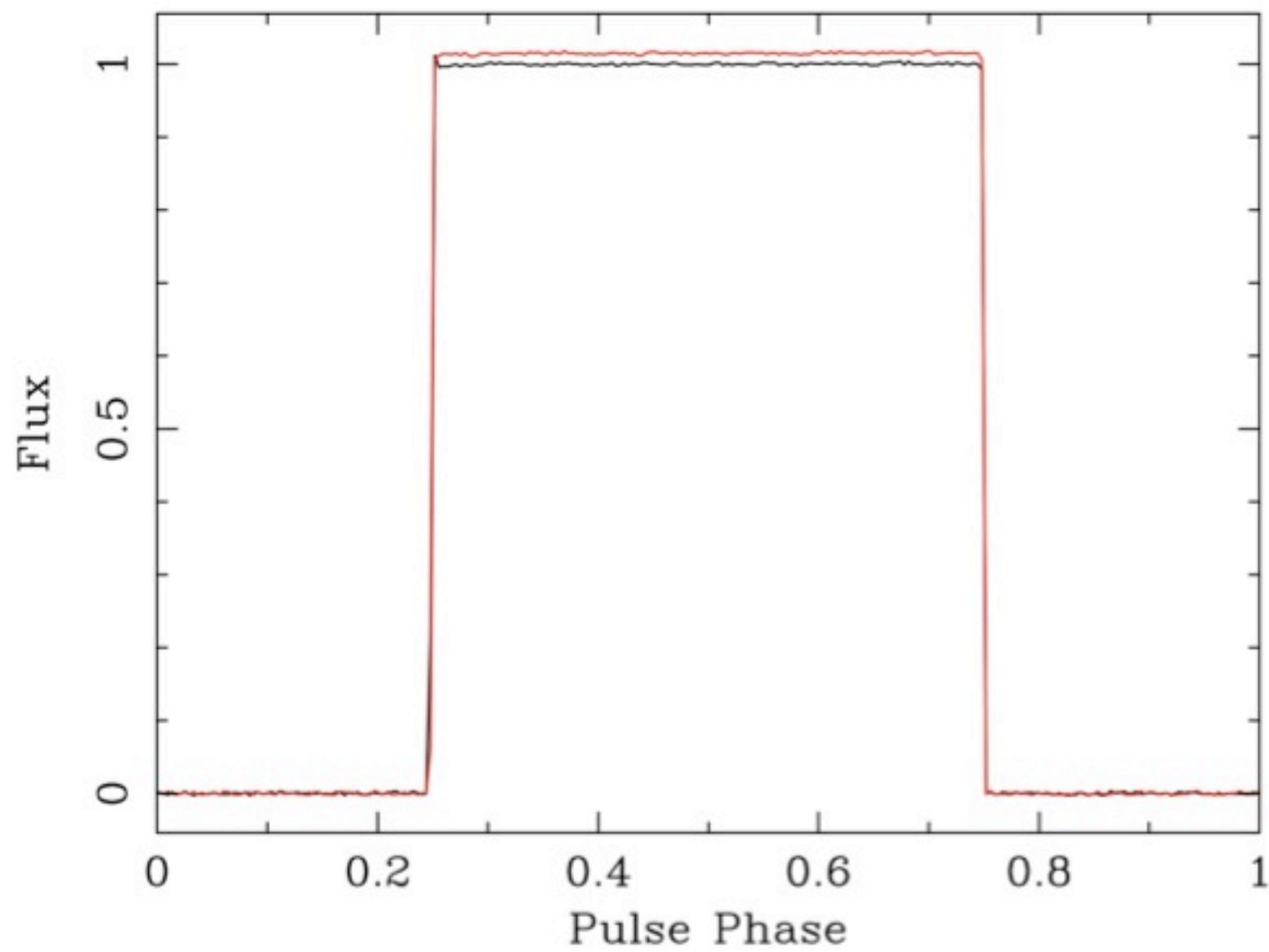
$$\mathbf{U}_v \mathbf{R}_v(\Psi) = \mathbf{R}_v(\Psi) \mathbf{U}_v$$

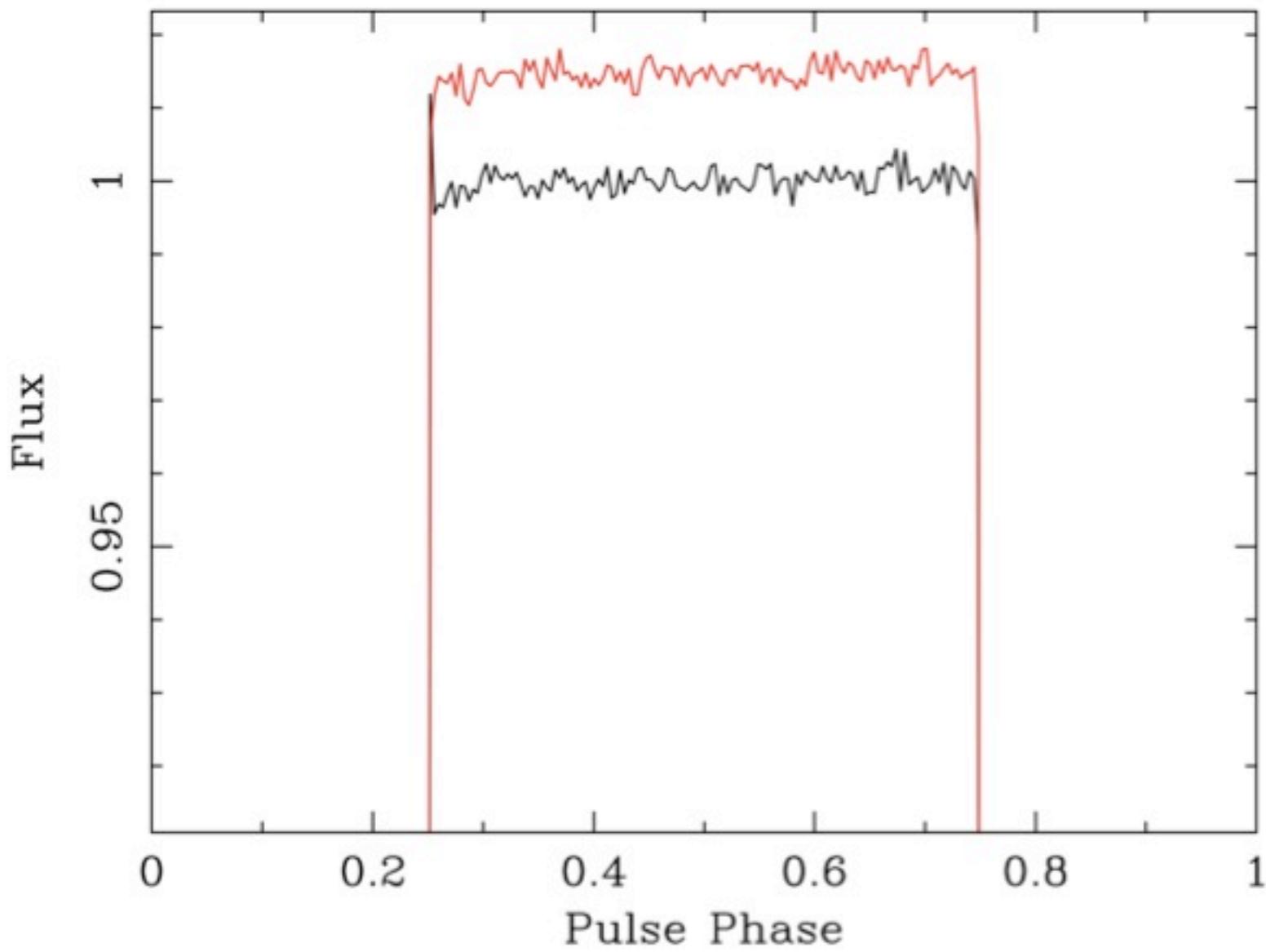


# Future Calibration Challenges

- Phased Arrays,  $\mathbf{J} = \sum e^{i\phi(t)} \mathbf{J}_i$
- Off-axis polarization
- Non-linear effects
  - analog: amplifiers, etc.
  - analog-to-digital: quantization distortion





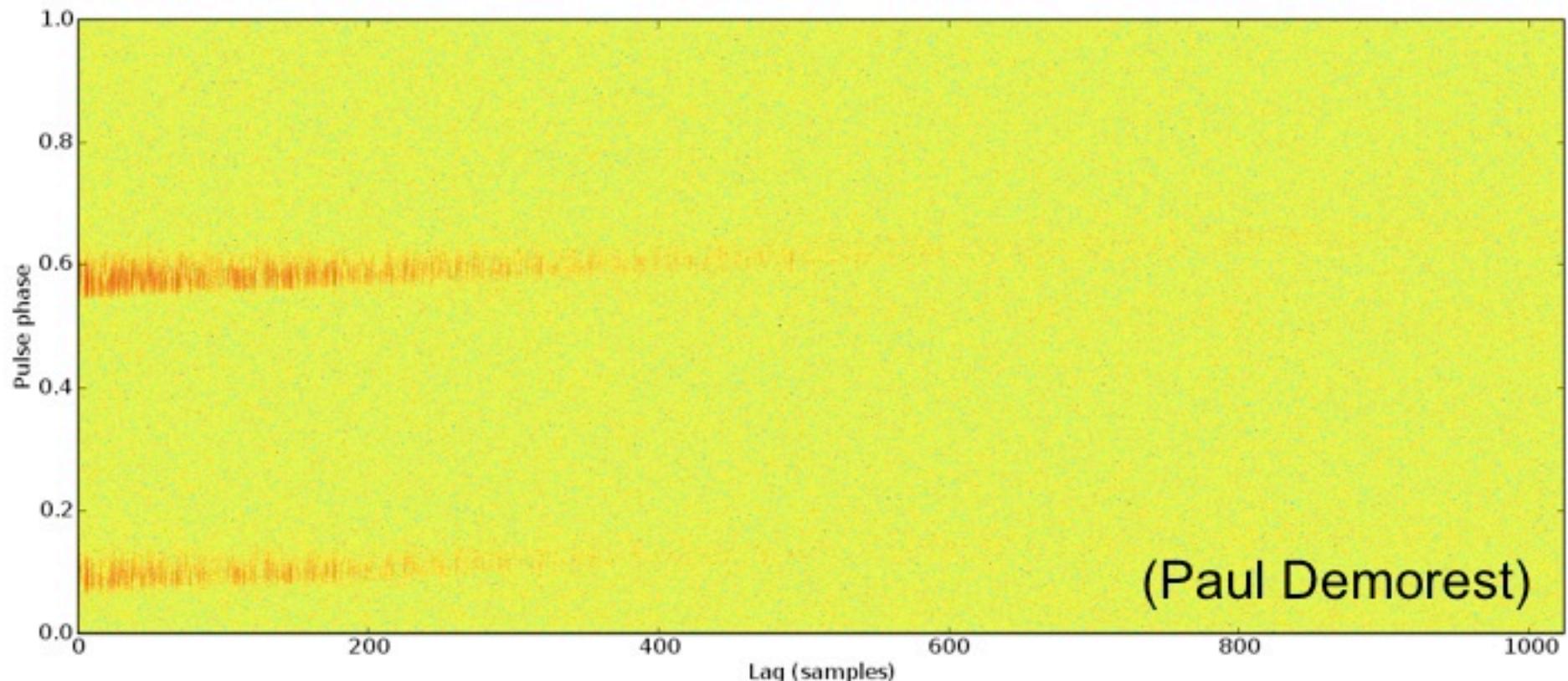


# Future Directions

- Polarisation of transient events
  - high time resolution  $\Rightarrow$  small number statistics
  - spectral coherence
- Scintillation of polarised radiation
  - vector diffraction theory
  - differential Faraday rotation
  - cyclostationary coherency matrix

# Periodic coherency

$$\rho(\phi, \tau) = \langle e(t_\phi + \tau/2) e^\dagger(t_\phi - \tau/2) \rangle$$



Thank you!

Questions?