

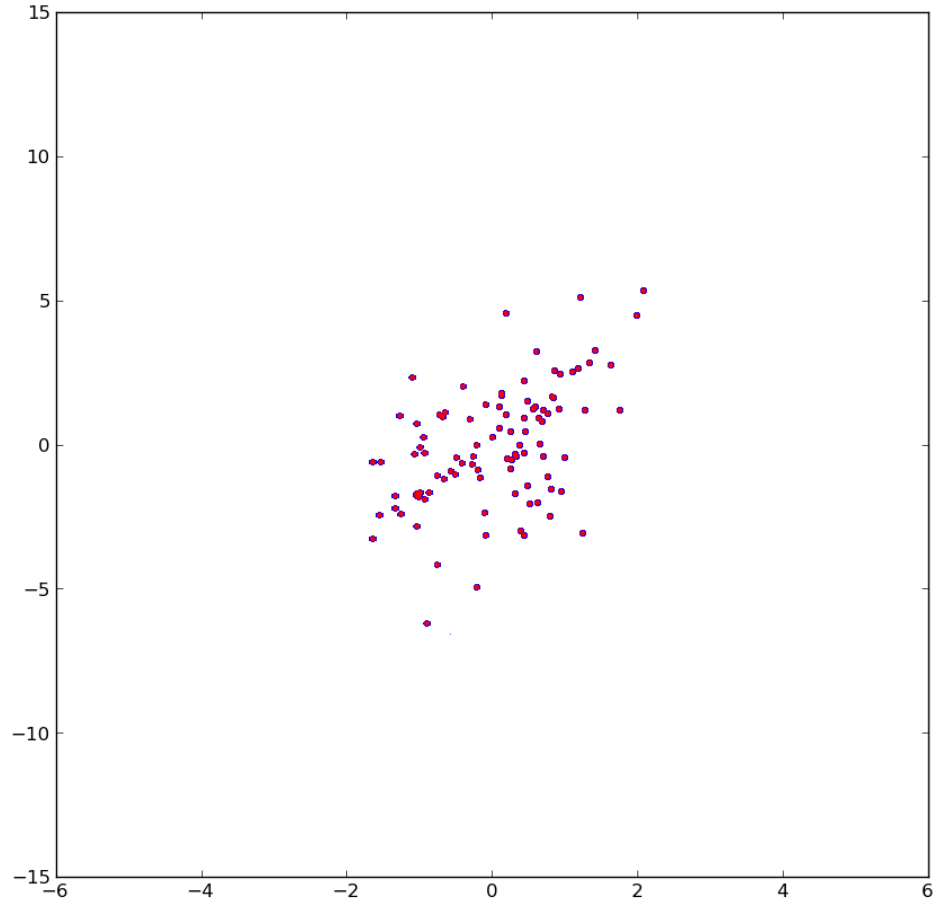
MULTIPLE EXPOSURES IN LARGE SURVEYS

12/12/2013

Tamás Budavári / Johns Hopkins University

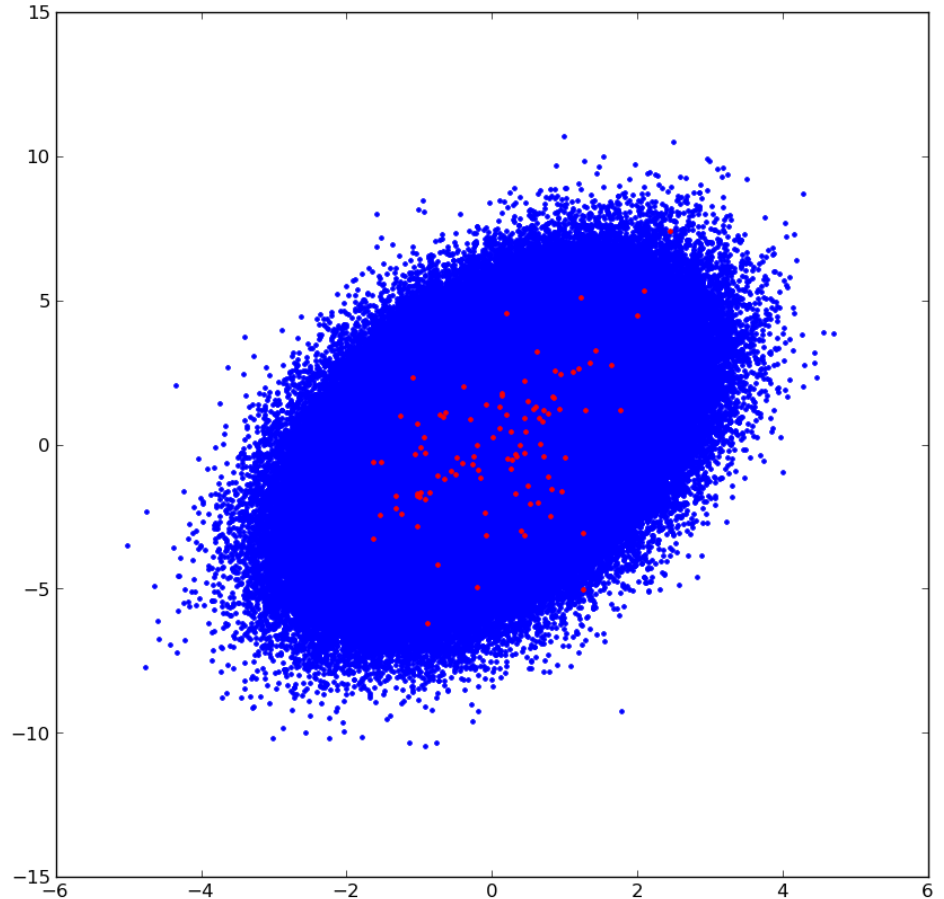
Big Data?

- Noisy
- Skewed
- Artifacts



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- Skewed
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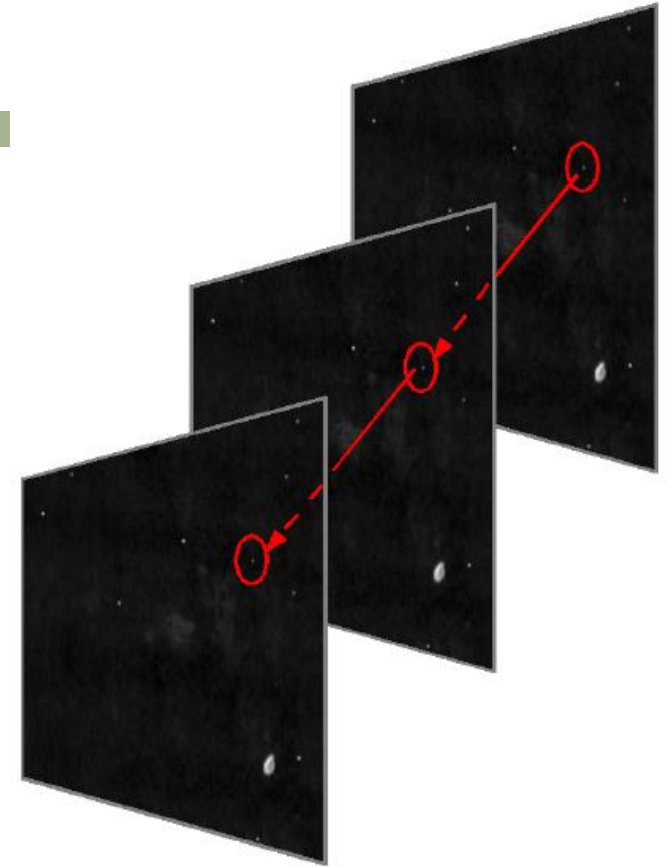
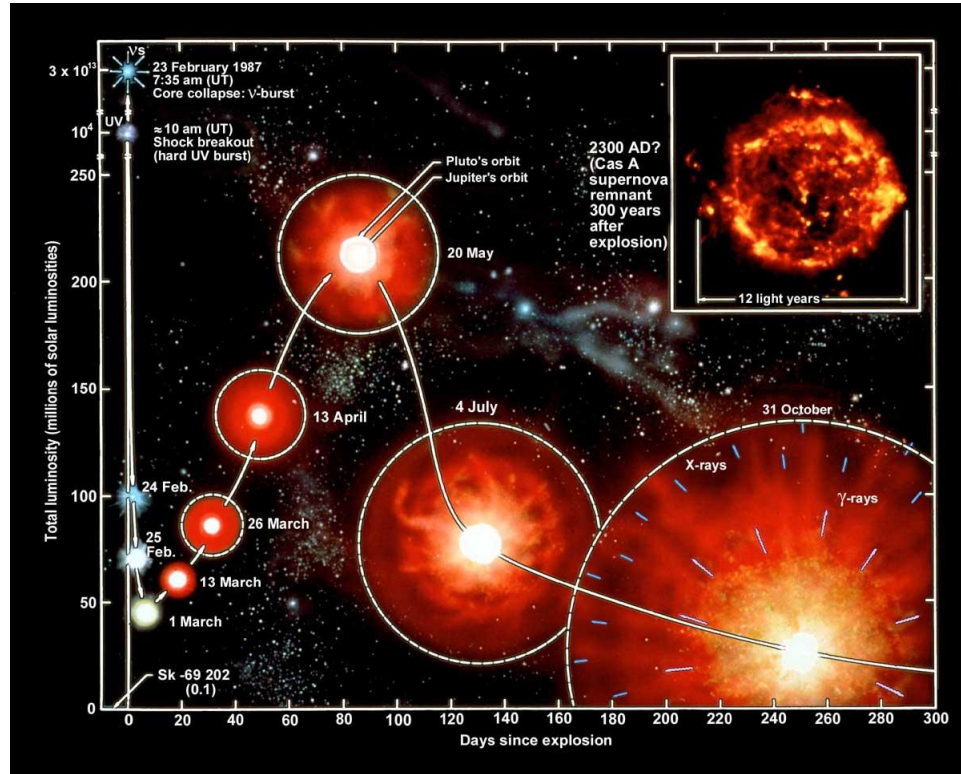


Serious Issues

- Significant fraction of catalogs is junk
 - GALEX ~50%
 - PS1 3PI 50-80%
 - PS1 MDS >95%

- Textbook methods often fail due to artifacts
 - What are the good techniques?

Time Domain



Time Series of Faint Sources?

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- Co-add images and do forced photometry
 - Ideal if we have all observations but we never do
- Independent catalogs as we go
 - Need to dig in the noise to build good timeseries
- Goal is an incremental strategy to weed out noise
 - Otherwise catalogs are overwhelmed by junk

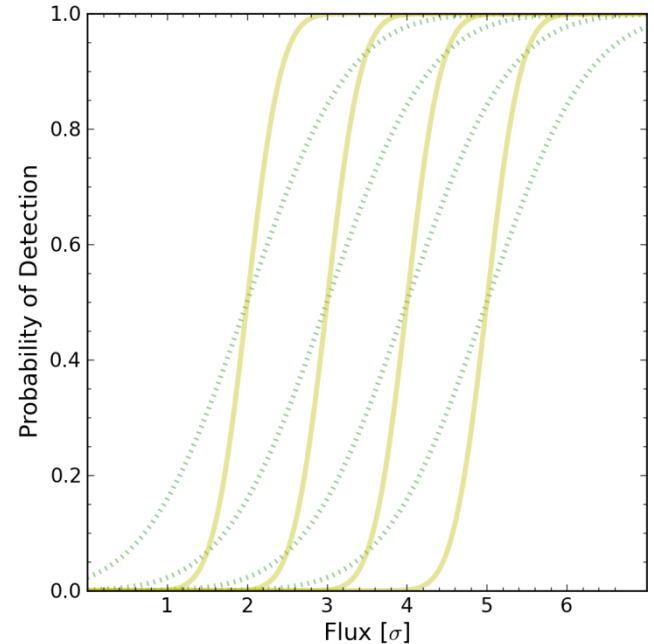
Detection Probability

- Measured flux is true + normal error $f_i = f + \epsilon_i$
- Probability of detection

$$P_f \equiv P(f_i > f_D | f) = \frac{1}{2} \operatorname{erfc} \left(\frac{f_D - f}{\sigma \sqrt{2}} \right)$$

Detection Probability

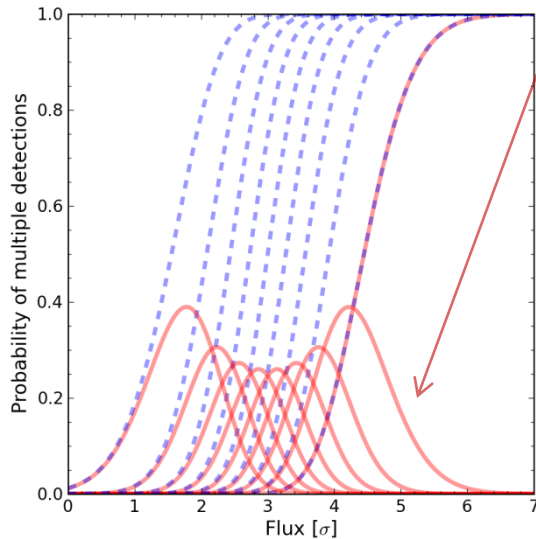
- Measured flux is true + normal error $f_i = f + \epsilon_i$
- Probability of detection
 - As a function of the true flux →
 - Thresholds at 2-, 3-, 4- & 5 σ
 - Sharper for 9-way **stacks**



Detection Probability

Multiple exposures

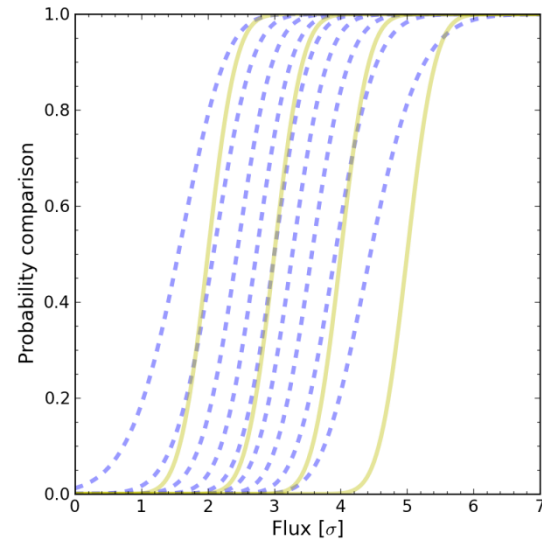
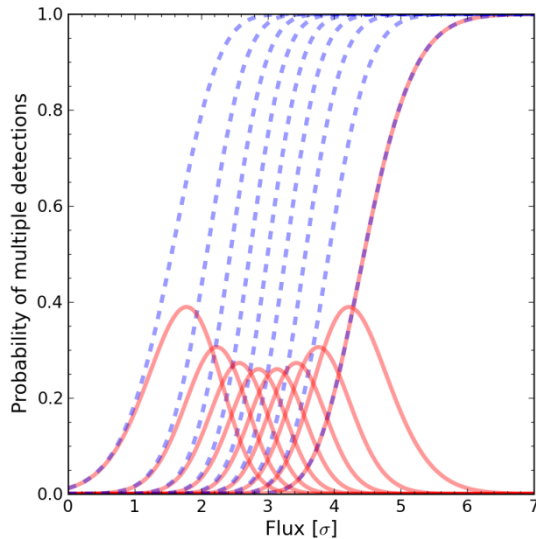
Binomial $P(n|k, f) = \binom{k}{n} P_f^n (1 - P_f)^{k-n}$



Detection Probability

Multiple exposures

Binomial $P(n|k, f) = \binom{k}{n} P_f^n (1 - P_f)^{k-n}$



What is a Real Source?

- Is it “real” or just “noise” ?
 - ▣ Bayesian hypothesis testing

$$B = \frac{L_{\text{real}}}{L_{\text{noise}}}$$

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$$B = \frac{L_{\text{real}}}{L_{\text{noise}}}$$

$$L_{\text{real}} = \int df \pi(f) L(f)$$

$$L(f) = (1 - P_f)^{k-n} \prod_i^n G(f_i; f, \sigma^2)$$

- Out of k observations n detections of f_i fluxes

Apparent Flux Distribution

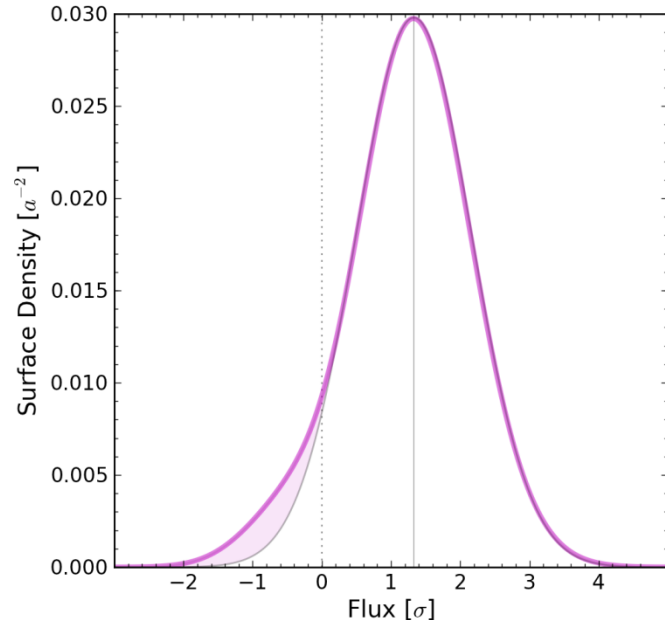
- Galaxy number-counts as fn of magnitude
 - ▣ Empirical relation approximately shows

$$dN \propto 10^{0.4m} dm \propto \frac{df}{f^2}$$

- More and more fainter and fainter sources!
 - ▣ But there is a limit, cf. Olbers' paradox

Distribution of Noise Peaks

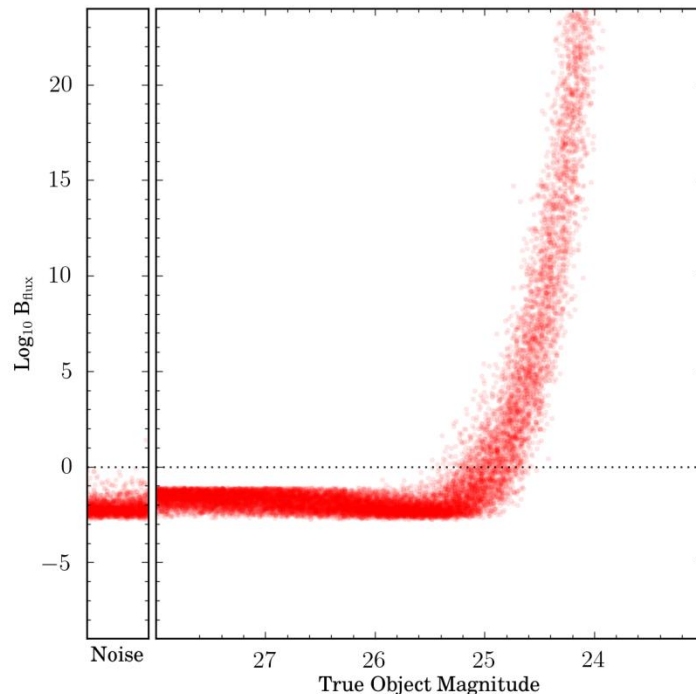
- Local maxima of continuous Gaussian random field
 - ▣ Cf., $P(\mathbf{k})$ by Barden, Bond, Kaiser, Szalay (BBKS; 1986)
 - ▣ Now in 2D:



Something Like LSST

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- Simulation
 - ▣ Sky at 5σ is 24 mag
 - ▣ Object limit is at 28
- Bayes factor
 - ▣ Considering only fluxes

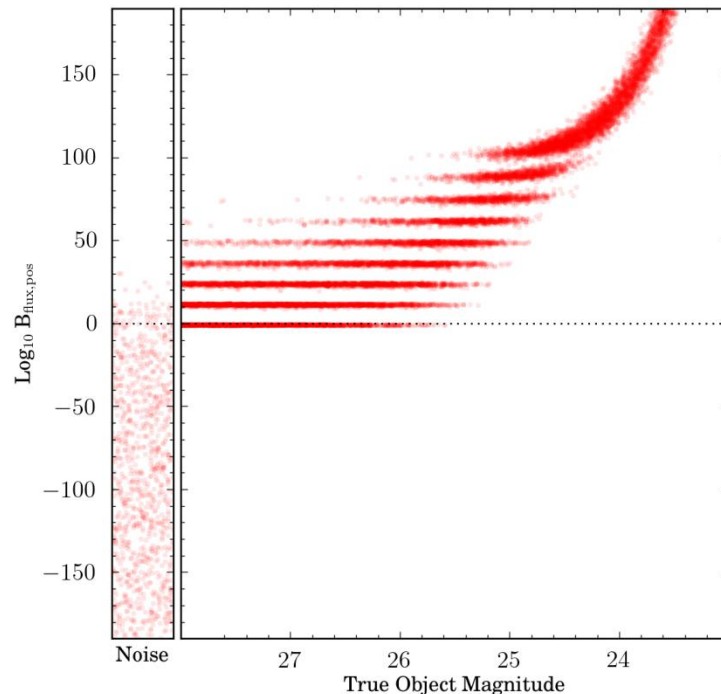


Adding Directions

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- Bayes factor from cross-id
 - ▣ As TB & Szalay (2008)
 - ▣ Faint sources can be distinguished based on their celestial coordinates

Always at “same” place!



Cross-Identification

- Hard problem
 - ▣ Computationally, Scientifically & Statistically
 - ▣ Need symmetric n -way solution
 - ▣ Need reliable quality measure

- Same or not?
 - ▣ Distance threshold? Maximum likelihood?



Same or Not?

OR □ The Bayes factor

$$B(H, K|D) = \frac{p(D|H)}{p(D|K)}$$

SAME □ H : all observations of the same object

NOT □ K : might be from separate objects

Same or Not?

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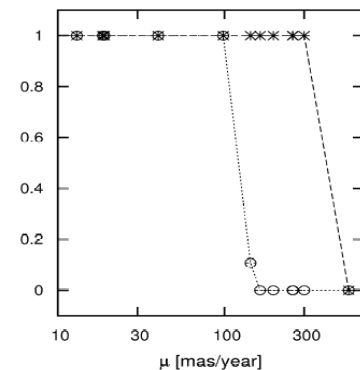
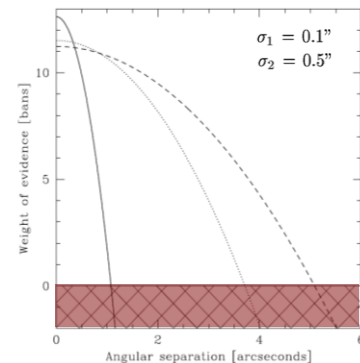
- Same properties, e.g., coordinates, brightness

NOT □ K : might be from separate objects

- Properties could be different

Works in General

- Analytic results for Gaussian errors
 - ▣ Incremental n -way strategy
- We can find moving stars
 - ▣ With unknown velocities
- Matching events in time
 - ▣ E.g., supernovae



SkyQuery – the new generation!

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- Dynamic federation of astronomy databases
 - Query the collection as if they were one
- The 3rd generation tool coming in December
 - Cluster of machines running partitioned jobs
 - Proper probabilistic exec with variable errors

SkyQuery – the new generation!

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□ Dynamic

■ Query

□ The 3rd

■ Cluster

■ Proper

The screenshot shows the SkyQuery web interface. At the top, the username 'budavari' is displayed with a lock icon, and there are links for 'account' and 'sign out'. Below the navigation bar, there are buttons for 'home', 'schema', 'query', 'jobs', 'my db', and 'docs'. The main area contains a 'syntax check' button, a 'quick execute' button, and an 'execute' button. To the right of the 'execute' button, there is a text input field for 'Output table:' containing 'xmatch1' and a 'Comments:' field. Below these elements is a text area containing a SQL query:

```
1 SELECT s.ObjID, g.ObjID, t.ObjID, ...,
2     x.RA, x.Dec, x.LogBF
3 FROM SDSS:PhotoObjAll AS s
4     CROSS JOIN GALEX:PhotoObjAll AS g
5     CROSS JOIN TwoMASS:PhotoXSC AS t
6 XMATCH BAYESFACTOR AS x
7     EXIST s ON POINT(s.Cx, s.Cy, s.Cz), 0.1
8     EXIST g ON POINT(g.RA, g.Dec), 0.2
9     MAY t ON POINT(t.RA, t.Dec), 0.5
10    HAVING LIMIT 1e6
11 WHERE s.Galaxy = 1
```

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Only the first steps...

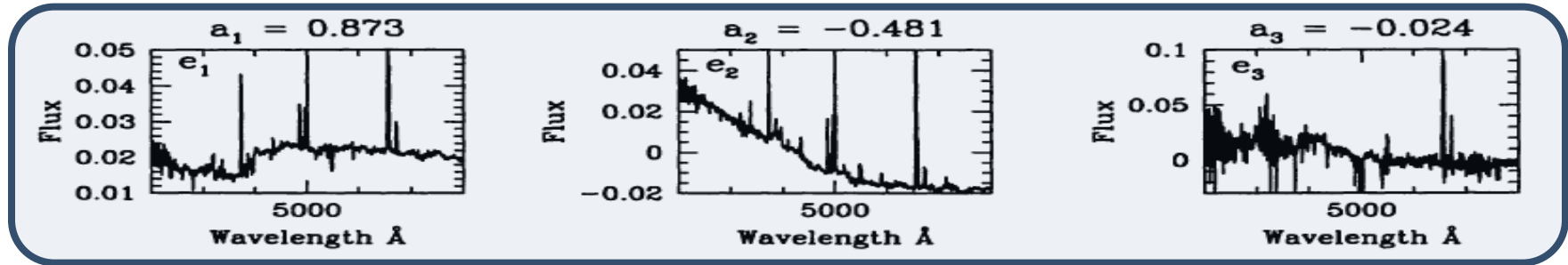
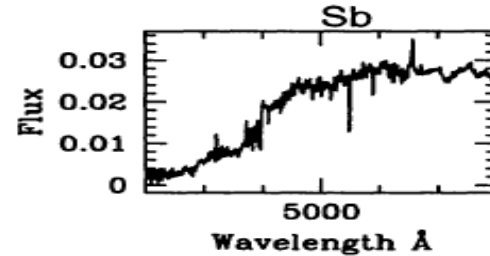
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- Resolved shapes: radio morphology (*Fan, TB+ 2014*)
- Colors to augment matches (*Marquez, TB, Sarro 2014*)

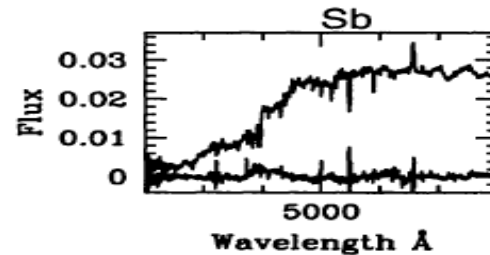


Galaxy Light ~ Linear Combination

- Principal Components Analysis (PCA)



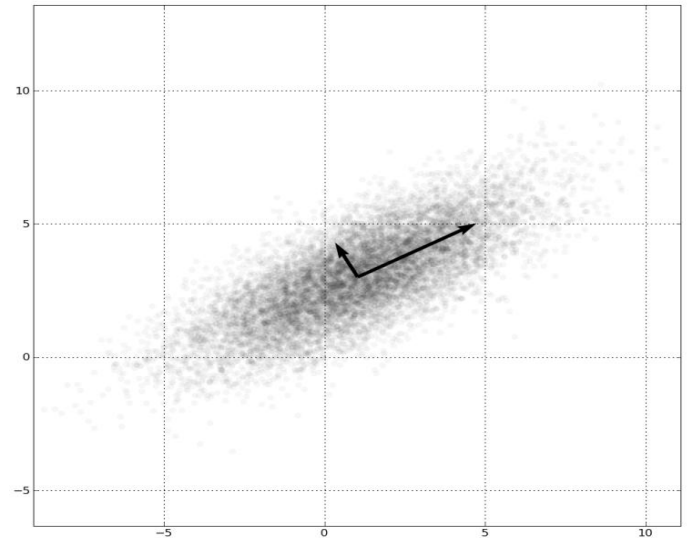
- SDSS galaxy type
 - On a big memory machine



Principal Component Analysis

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- Principal directions
 - Directions of largest variations
 - Eigenproblem of covariances
 - Singular Value Decomposition
- Problems
 - Needs lots of memory
 - Only need largest ones
 - Very sensitive to outliers



Science is Interactive

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“Too much to be accurate”

By the time you do the calculations,
the answer may have changed...



Streams of Data

□ Mean

$$\mu = \frac{1}{N} \sum_{n=1}^N x_n$$

$$\mu_n = \frac{n-1}{n} \mu_{n-1} + \frac{1}{n} x_n$$

$$\mu = \gamma \mu_{\text{prev}} + (1 - \gamma)x$$

Streams of Data

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$$\mu = \gamma \mu_{\text{prev}} + (1 - \gamma)x$$

□ Covariance

$$C = \gamma C_{\text{prev}} + (1 - \gamma) y y^T$$

$$y = x - \mu_{\text{prev}}$$

Iterative evaluation!

Streaming PCA

□ Initialization

- Eigensystem of a small, random subset
- Truncate at p largest eigenvalues

$$C \approx E_p \Lambda_p E_p^T$$

□ Incremental updates

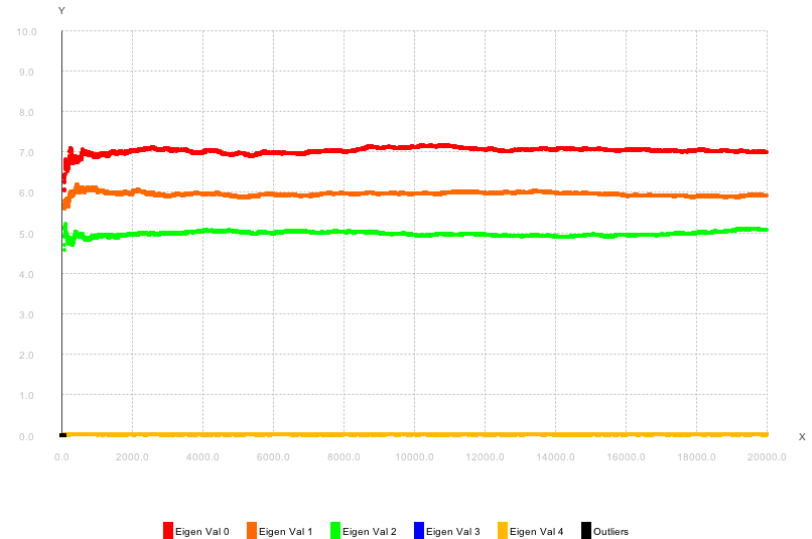
- Mean and the low-rank A matrix
- SVD of A yields new eigensystem

$$\begin{aligned} C &\approx \gamma E_p \Lambda_p E_p^T + (1 - \gamma) y y^T \\ &\approx A A^T \end{aligned}$$

□ Randomized algorithm!

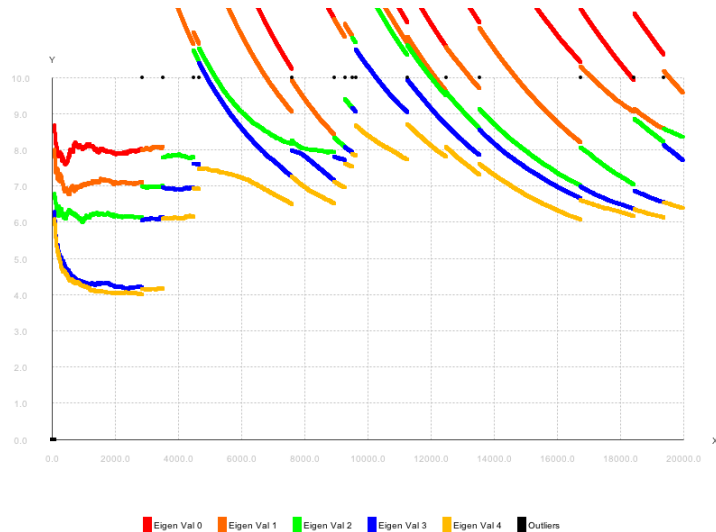
Streaming PCA

- 3D Gaussian rotated into 50D
 - Stretches: 7, 6, 5
 - Total Var = 110



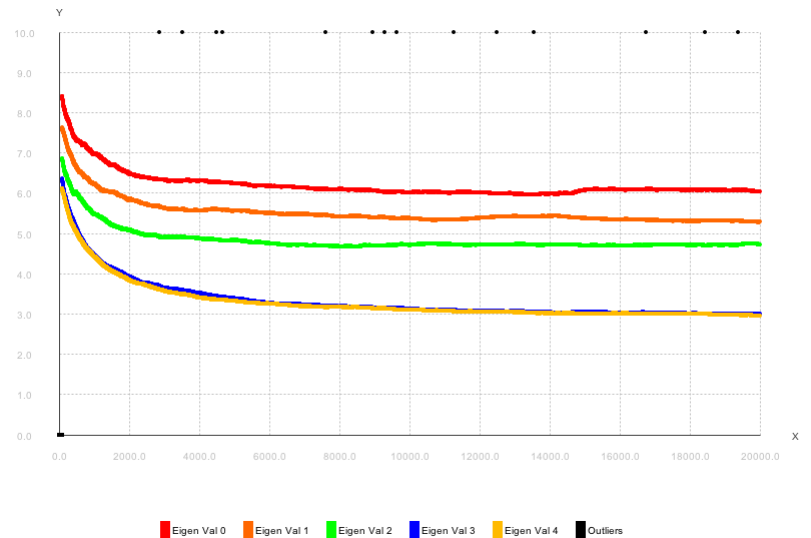
With Outliers

- Adding 0.1% outliers
 - ▣ $\sigma = 100$ in each bin
- Outliers take over the PCs
 - ▣ Instability, no convergence



Robust Algorithm

- Outliers under control
 - ▣ Marked on top
- Initialized with SVD
 - ▣ On a set of 100 vectors



Summary

- Plan for the junk
 - Proper statistics save money and gain speed
- Incremental randomized strategies scale
 - Crossmatching, embeddings, ML, etc.
- Not there, yet
 - Need new methods and tools