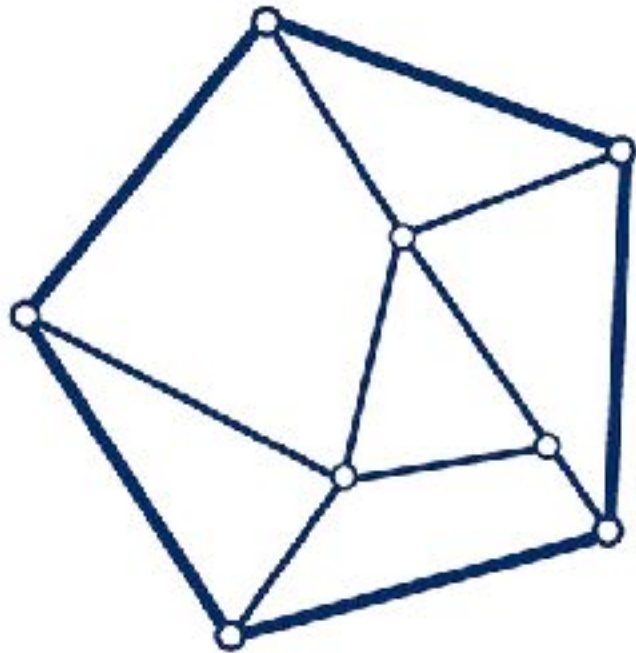




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THE UNIVERSITY OF  
SYDNEY



$v$   
 $v$   
Error Recognition 

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*University of Sydney / CAASTRO*

[www.caastro.org](http://www.caastro.org)

CASS Radio Astronomy School 2017

Based on lectures given previously by Ron Ekers and Steven Tingay



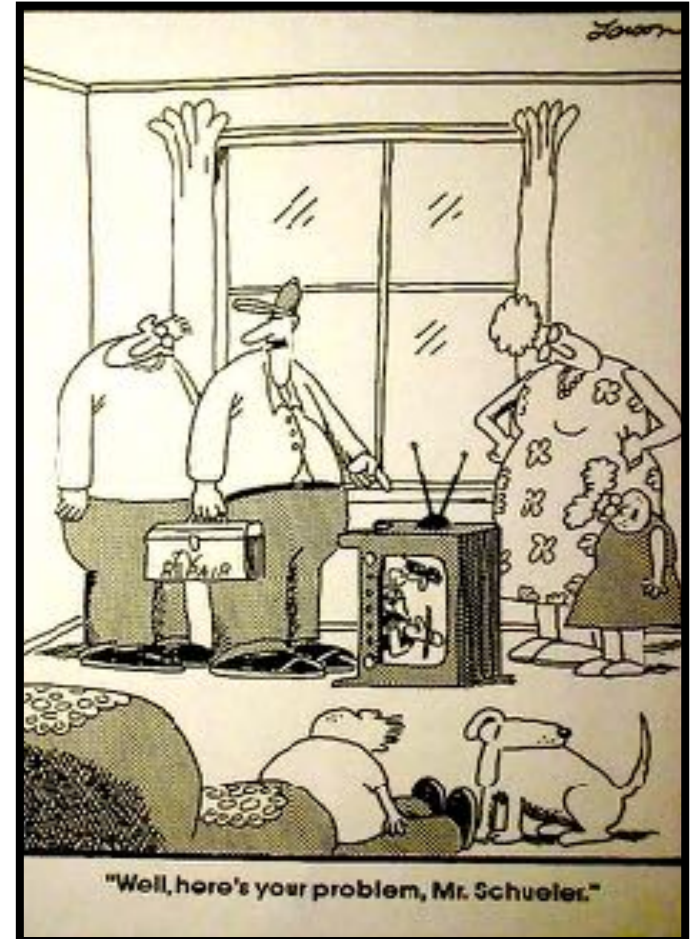


# Error Recognition

Some errors are easy to recognise



Some are hard to fix



Some are easy to fix

# Where do errors occur?

- › Most errors and defects occur in the  $(u,v)$  plane
  - Measurement errors (imperfect calibration – see Calibration talk).
  - Approximations made in the  $(u,v)$  plane.
  - Approximations made in the transform to the image plane.
- › Some are due to manipulations in the image plane.
  - Deconvolution (see Deconvolution talk).
- › What we usually care about are effects in the image plane (not always e.g. spectral line).
- › The relative contribution of certain errors will vary depending on the nature of the observation.

# Image or $uv$ plane?

- › We need to work between the  $uv$  plane and the image plane.
  - Different types of errors may be more obvious in one plane than the other.
  - A good understanding of the relationship between both planes.
- › Errors obey Fourier transform relations.
  - Narrow features transform to wide features and vice versa.
  - Symmetries important – real/imaginary, odd/even, point/line/ring.
  - The transform of a serious error may not be serious!
  - Some effects are diluted by the number of other samples.

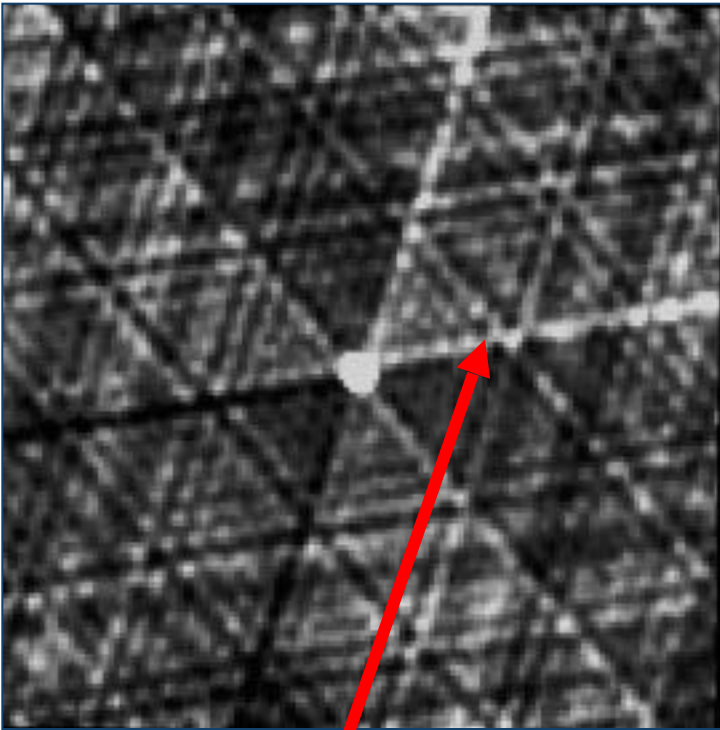
- › Additive errors (out-of-field sources, RFI, cross-talk, baseline-based errors, noise)
  - $V + \varepsilon \rightarrow I + F[\varepsilon]$
- › Multiplicative errors (uv-coverage effects, gain errors, atmospheric effects)
  - $V \bullet \varepsilon \rightarrow I \star F[\varepsilon]$
- › Convolutional errors (primary beam effect, convolutional gridding)
  - $V \star \varepsilon \rightarrow I \bullet F[\varepsilon]$
- › Other errors
  - Bandwidth and time average smearing.
  - Non-coplanar effects (see Wide Field Imaging talk by Tim Cornwell)
  - Deconvolutional errors (see Deconvolution talk by Mark Wieringa)
  - Software!!! (see everyone!)

- › If  $\varepsilon$  is pure real, then the form of the error in the  $(u,v)$  plane is a real and even function i.e.  $F[\varepsilon]$  will be symmetric.
  - **Such errors are often due to amplitude calibration errors.**
- › If  $\varepsilon$  has an imaginary component, then the form of the error in the  $uv$  plane is complex and odd i.e.  $F[\varepsilon]$  will be asymmetric.
  - **Such errors are often due to phase calibration errors.**
- › Short duration errors
  - Localized in  $(u,v)$  plane but distributed in image plane.
  - Narrow features in  $(u,v)$  are extended in orthogonal direction in image.
- › Long timescale errors
  - Ridge in  $(u,v)$  plane causes corrugations in image plane
  - Ring in  $(u,v)$  plane causes concentric “Bessel” rings in image plane



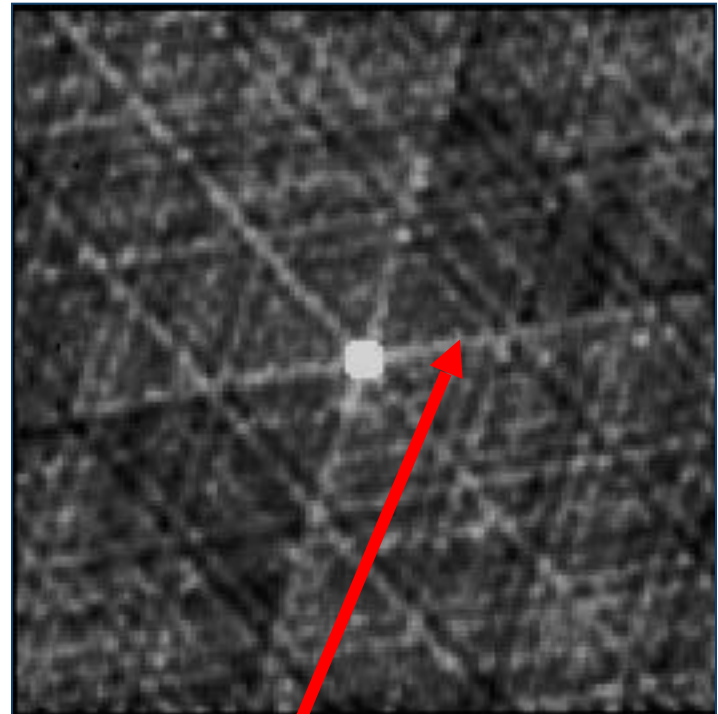
# Gain Errors

10 deg phase error



anti-symmetric ridges

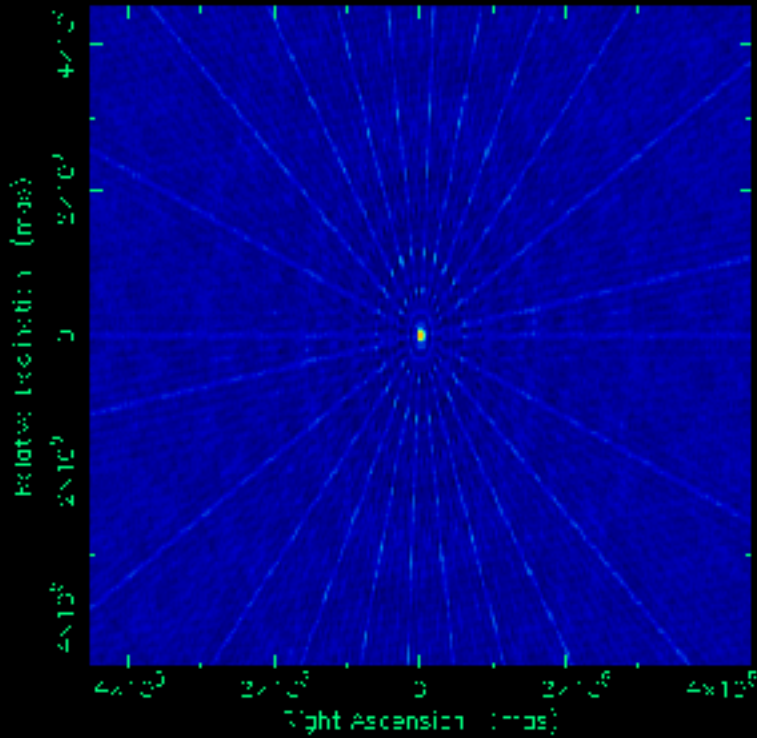
20% amp error



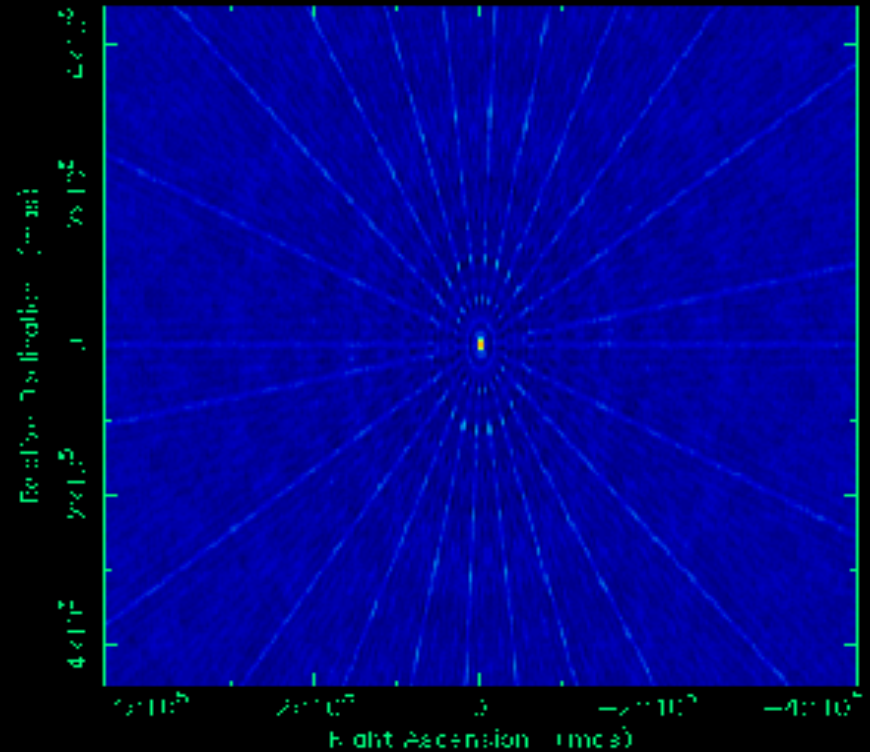
symmetric ridges



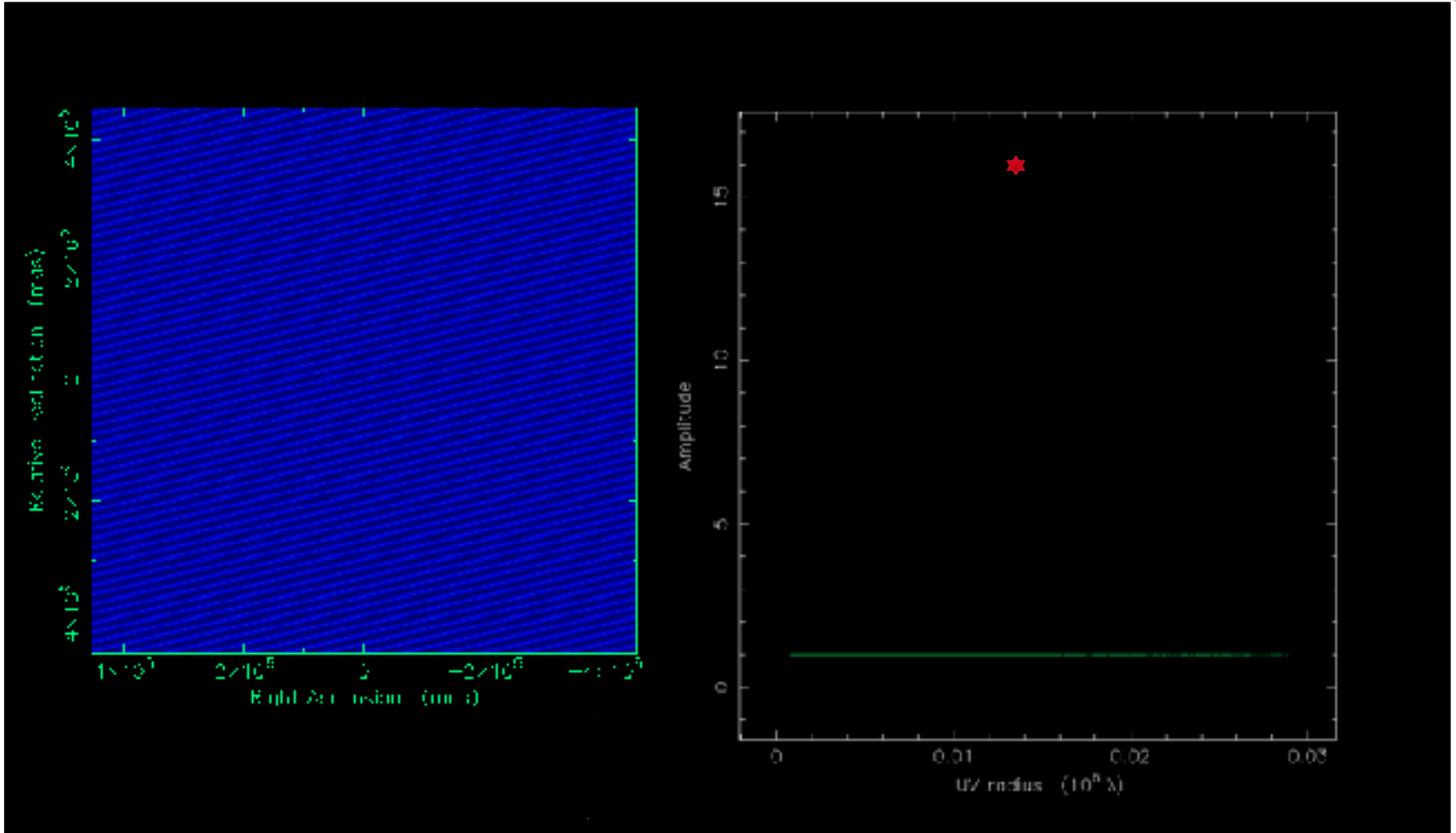
## Dirty Map



## PSF



Observation of 1 Jy source

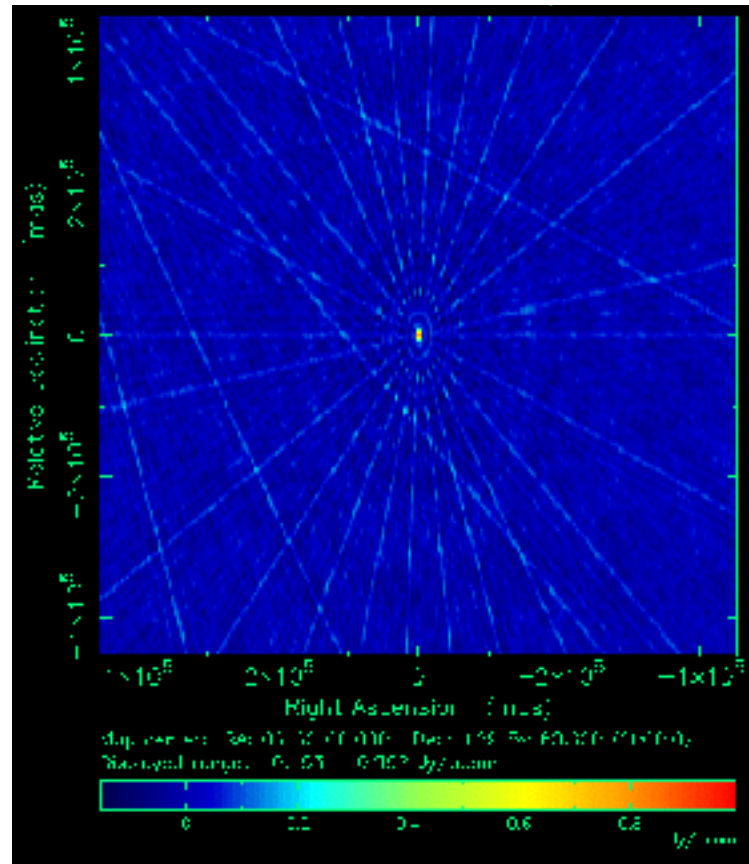


Observation of 1 Jy source

See Mark's talk for more on removing RFI.

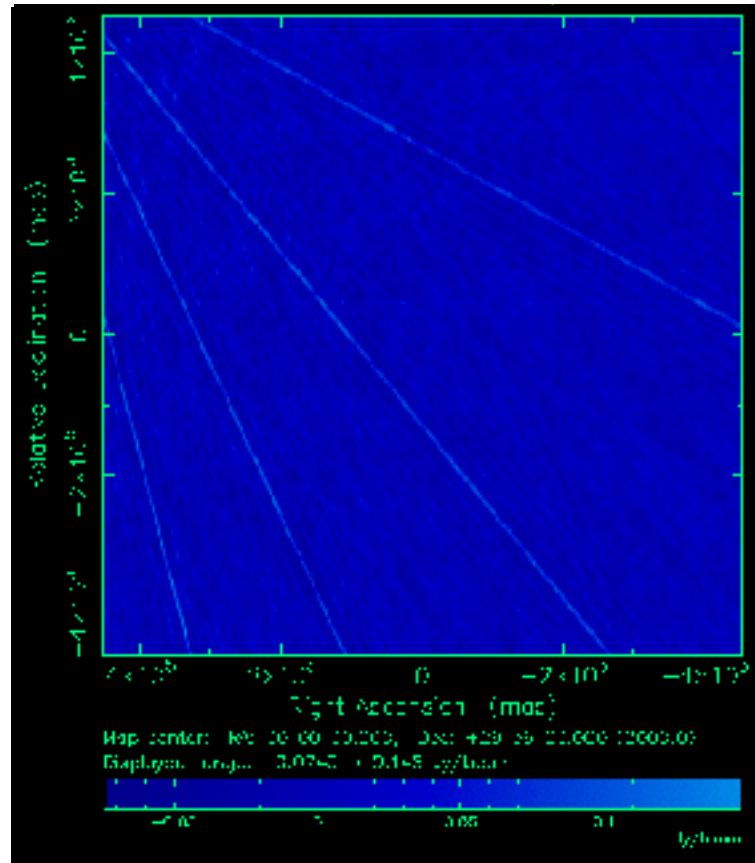


# The Bigger Picture



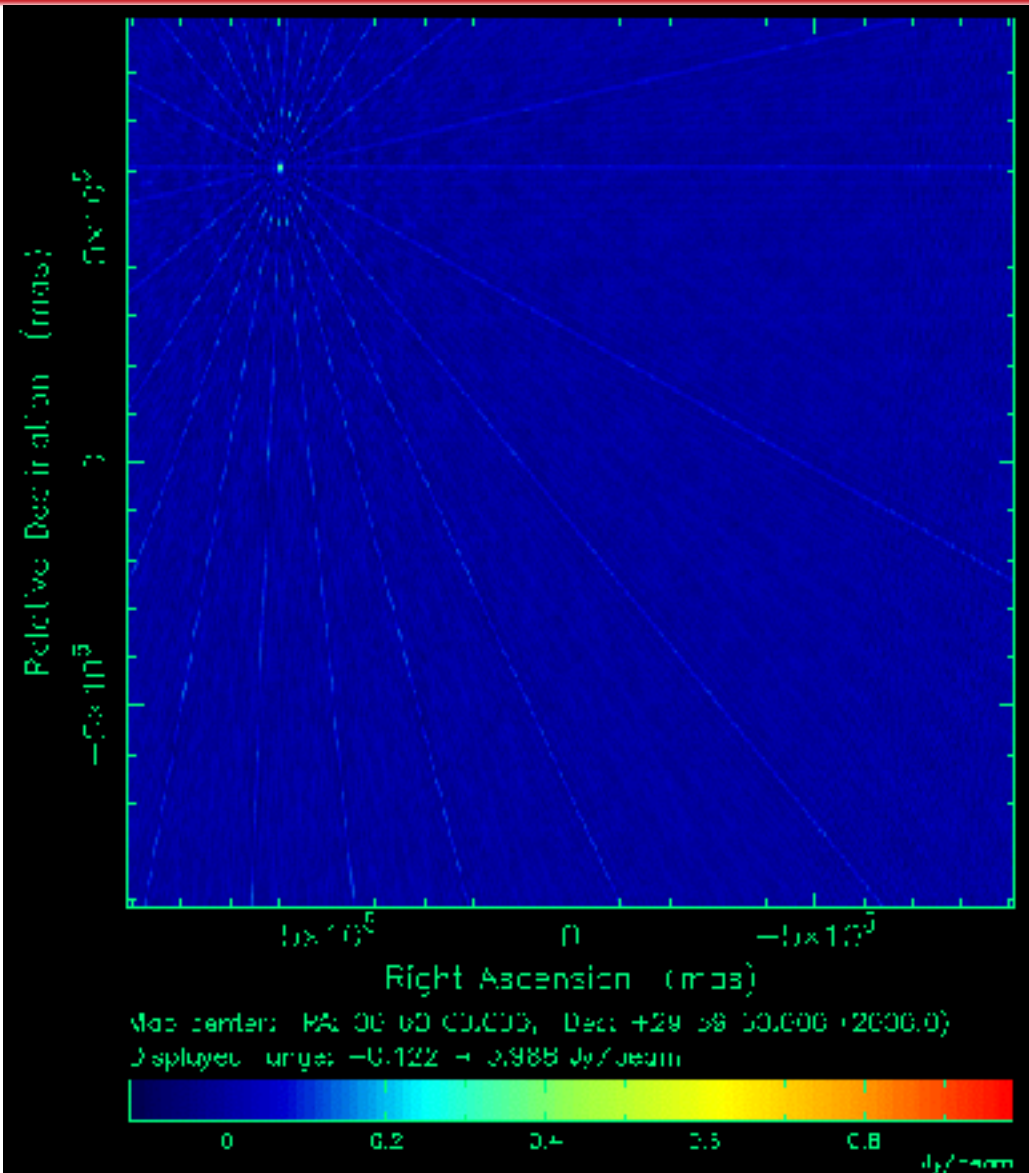


# The Bigger Picture





# The Bigger Picture

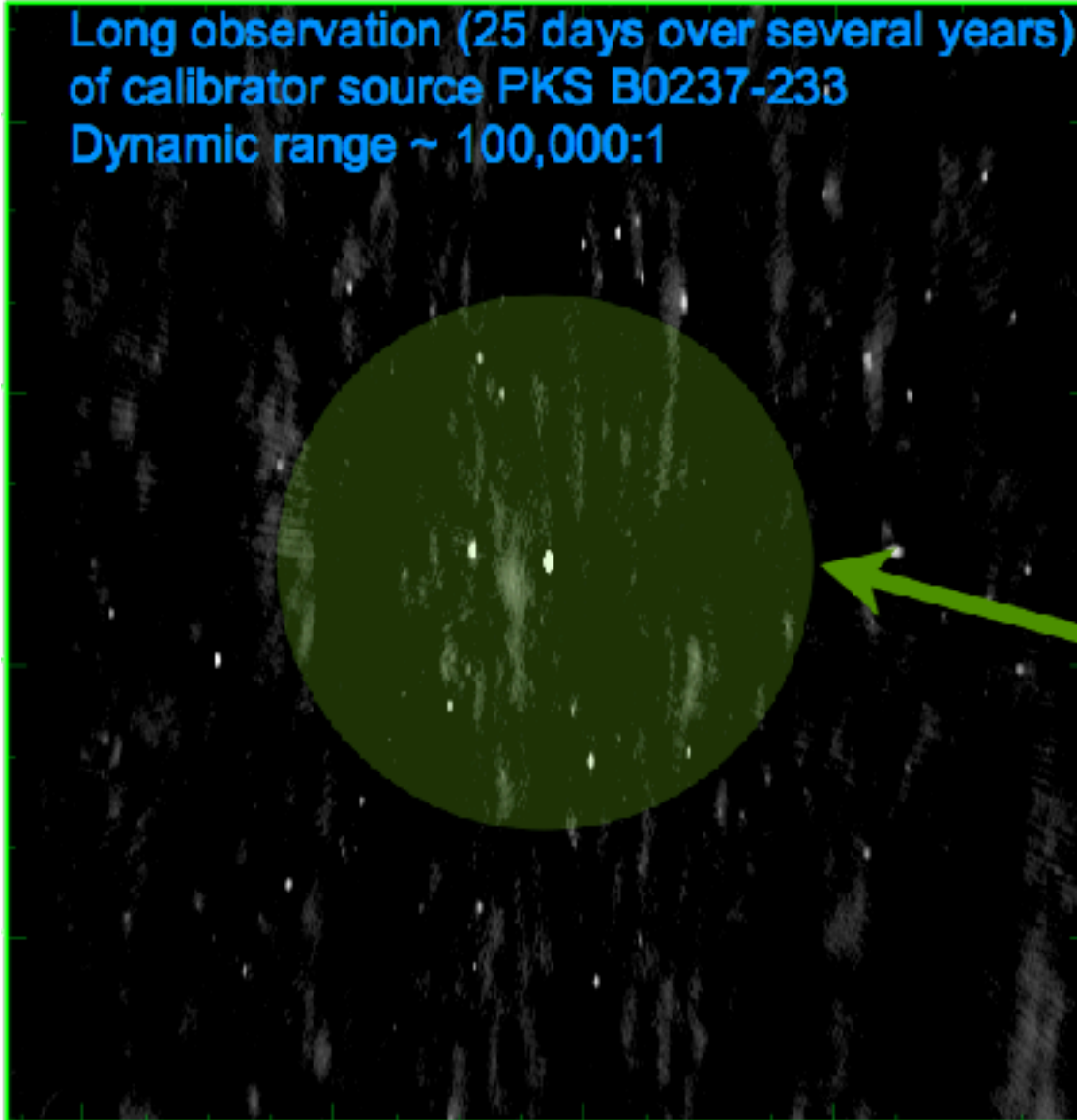




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# The Bigger Picture

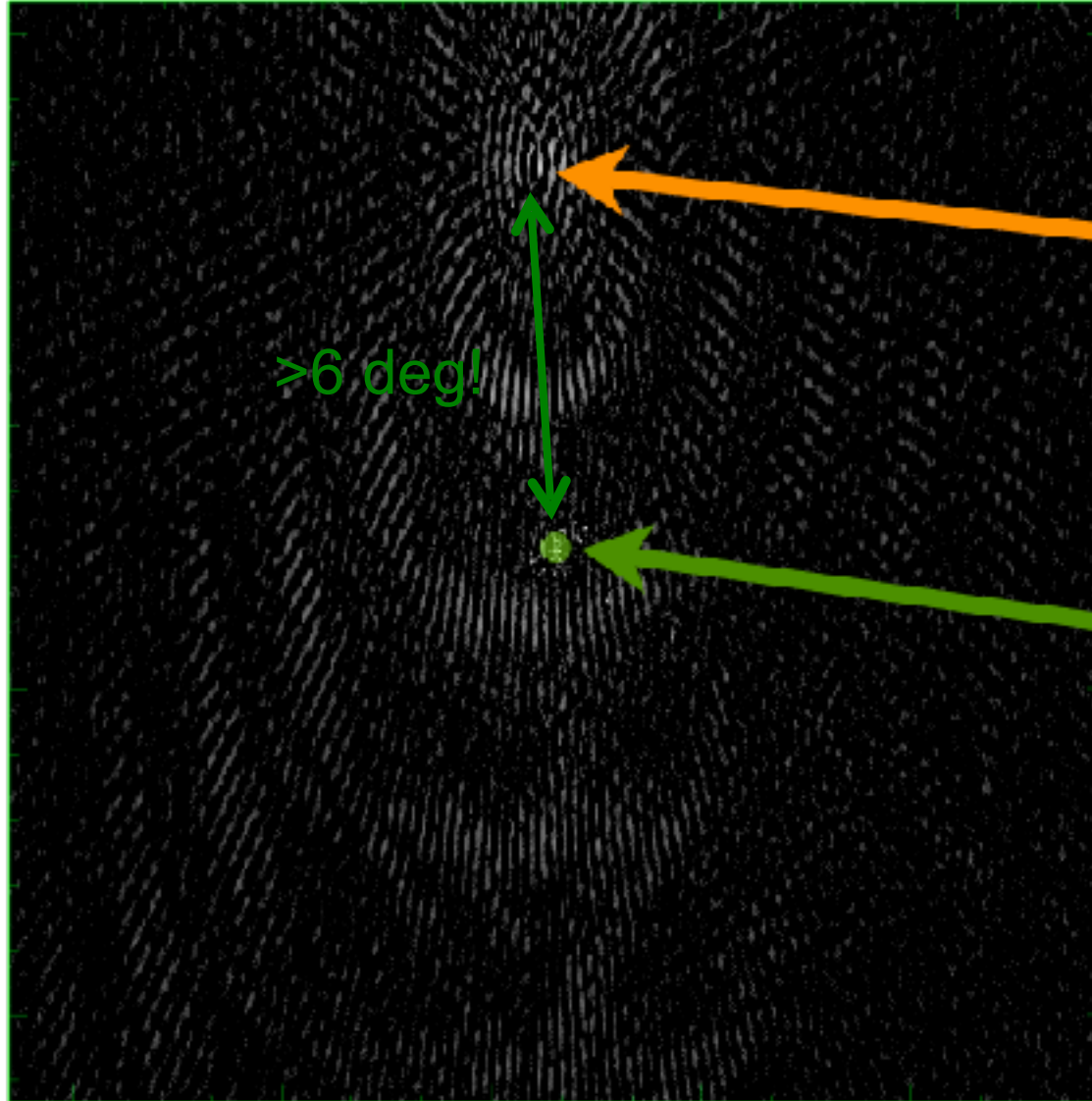
Long observation (25 days over several years)  
of calibrator source PKS B0237-233  
Dynamic range ~ 100,000:1



Primary Beam  
FWHM



# The Bigger Picture



**The Sun was  
“near” the  
calibrator during  
one of the  
observing days.**

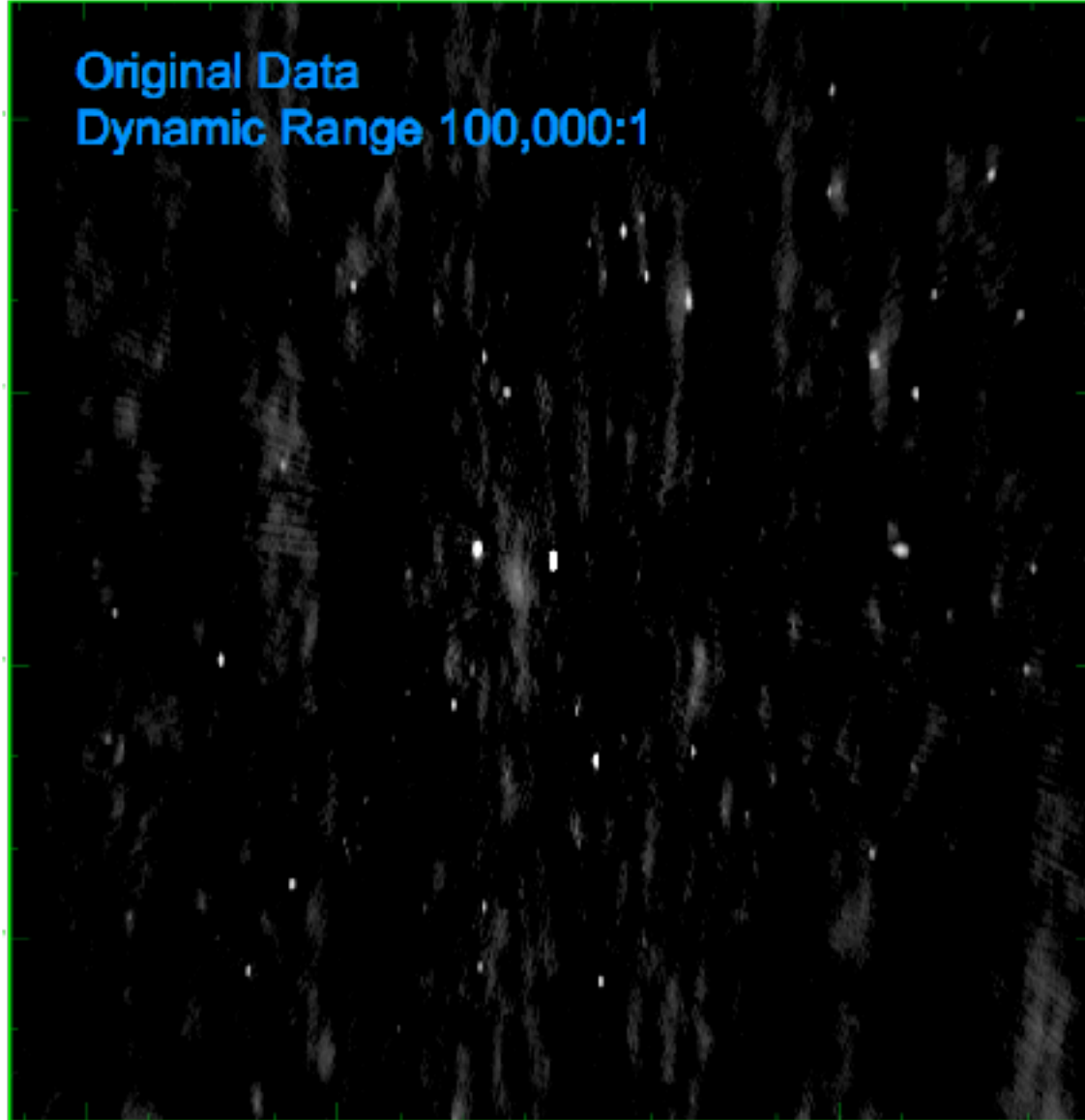
**Primary Beam  
FWHM**



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# The Bigger Picture

Original Data  
Dynamic Range 100,000:1





# The Bigger Picture

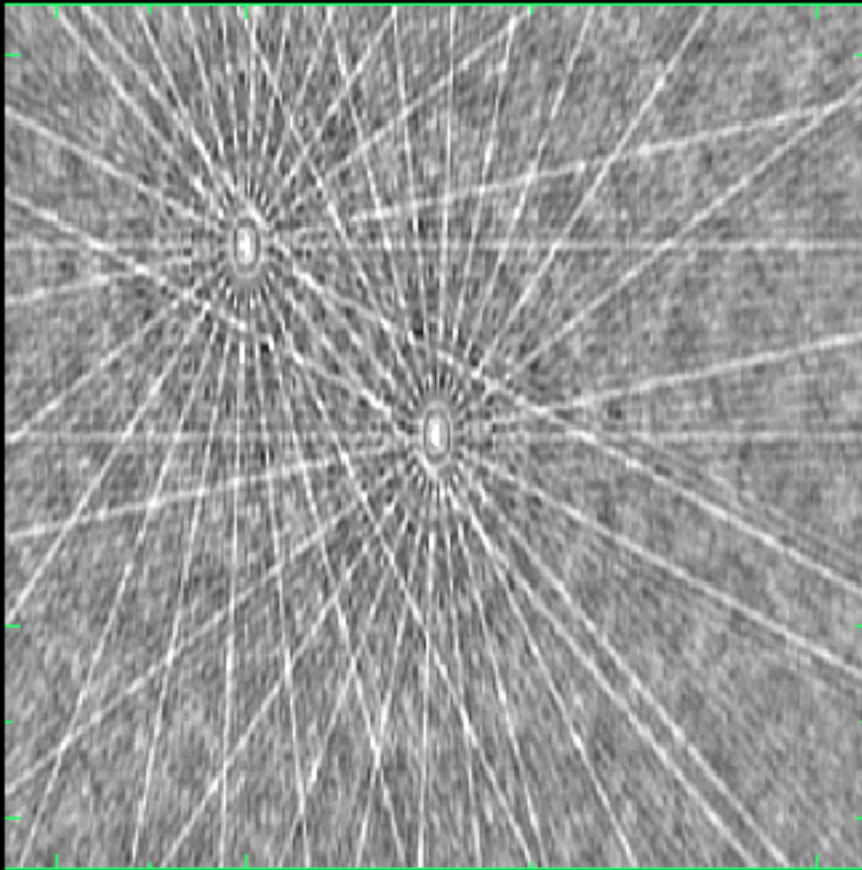
Original data with one day flagged  
Dynamic range 140,000:1



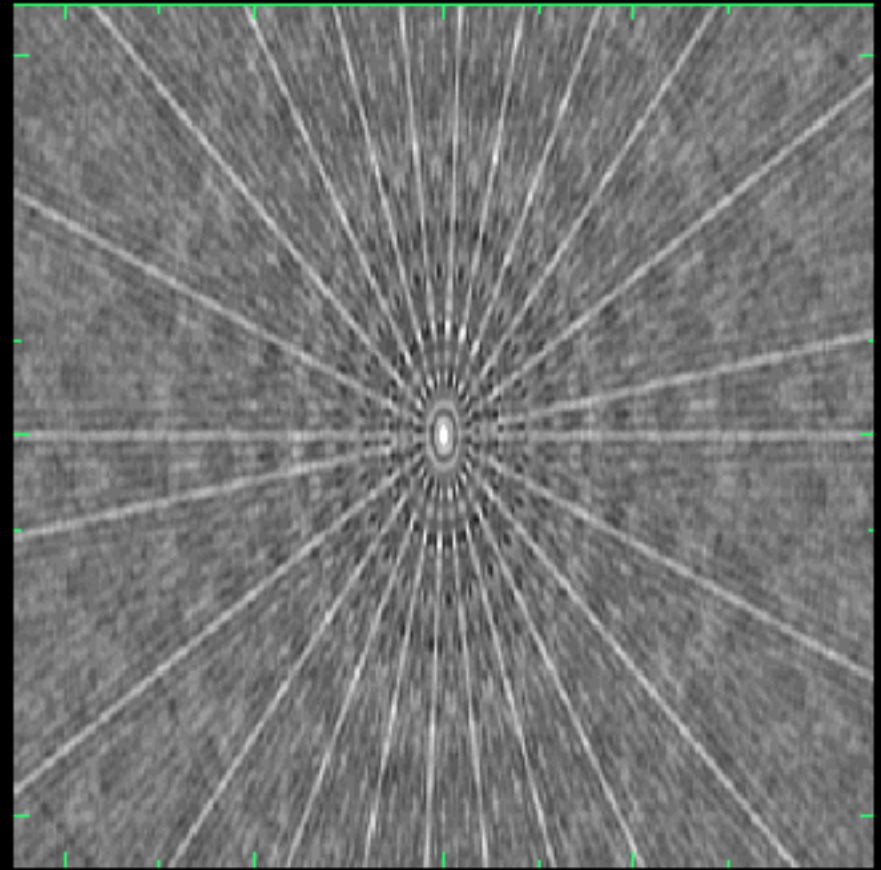


# Multiplicative Errors

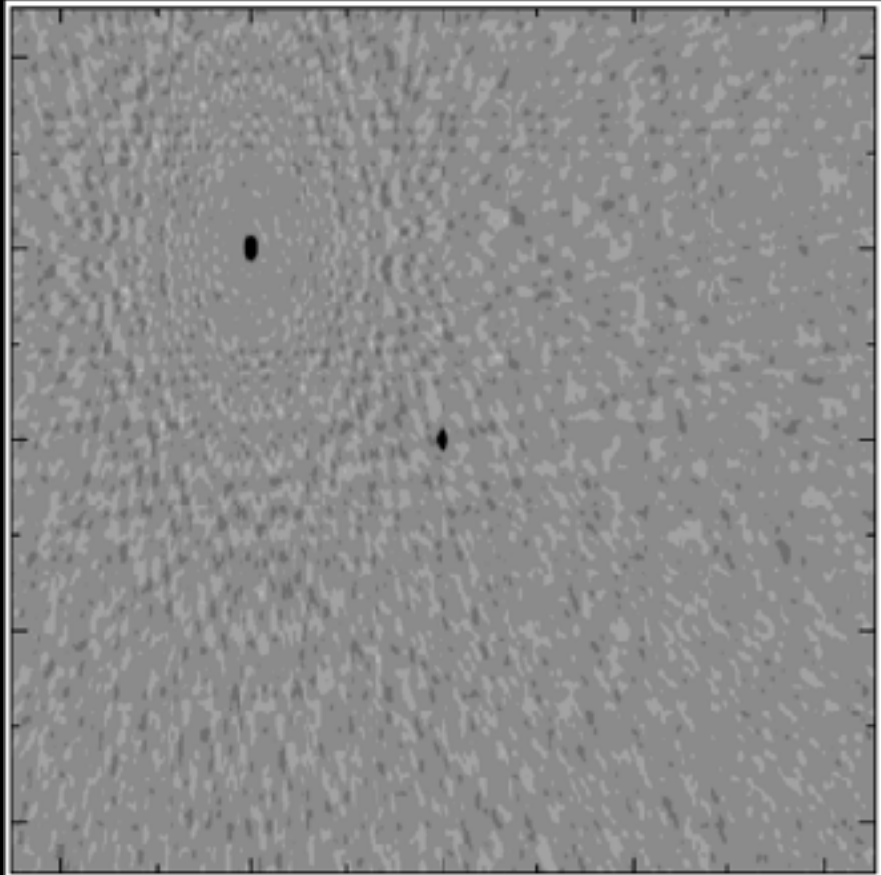
Dirty Map



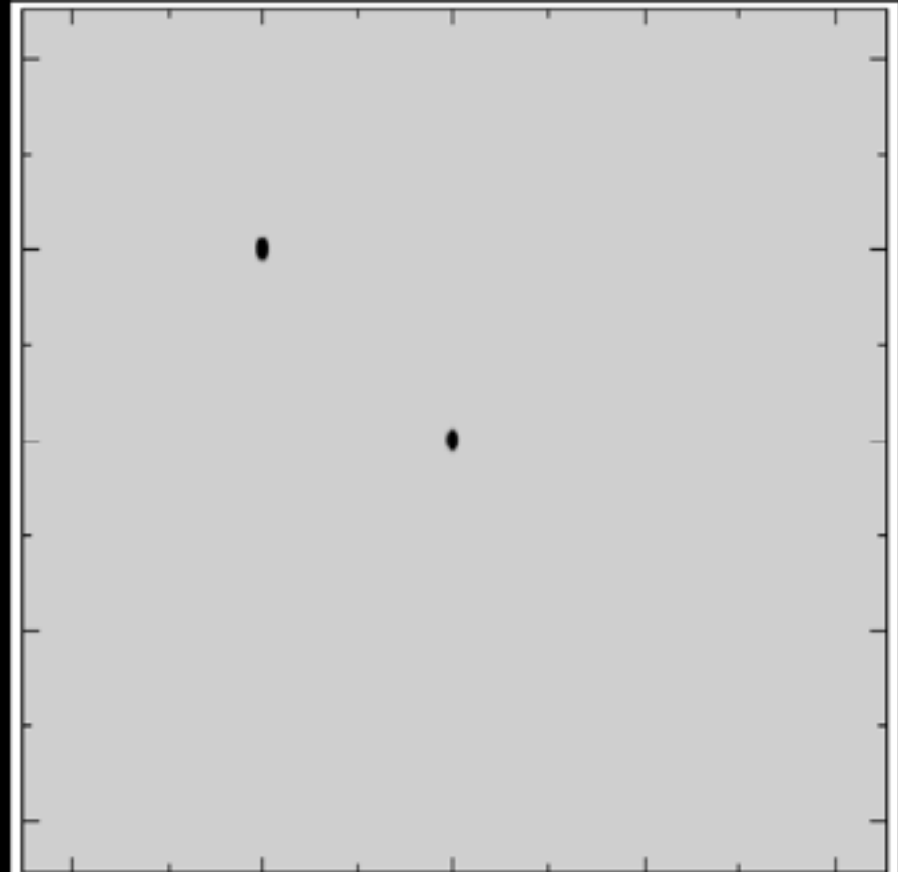
PSF



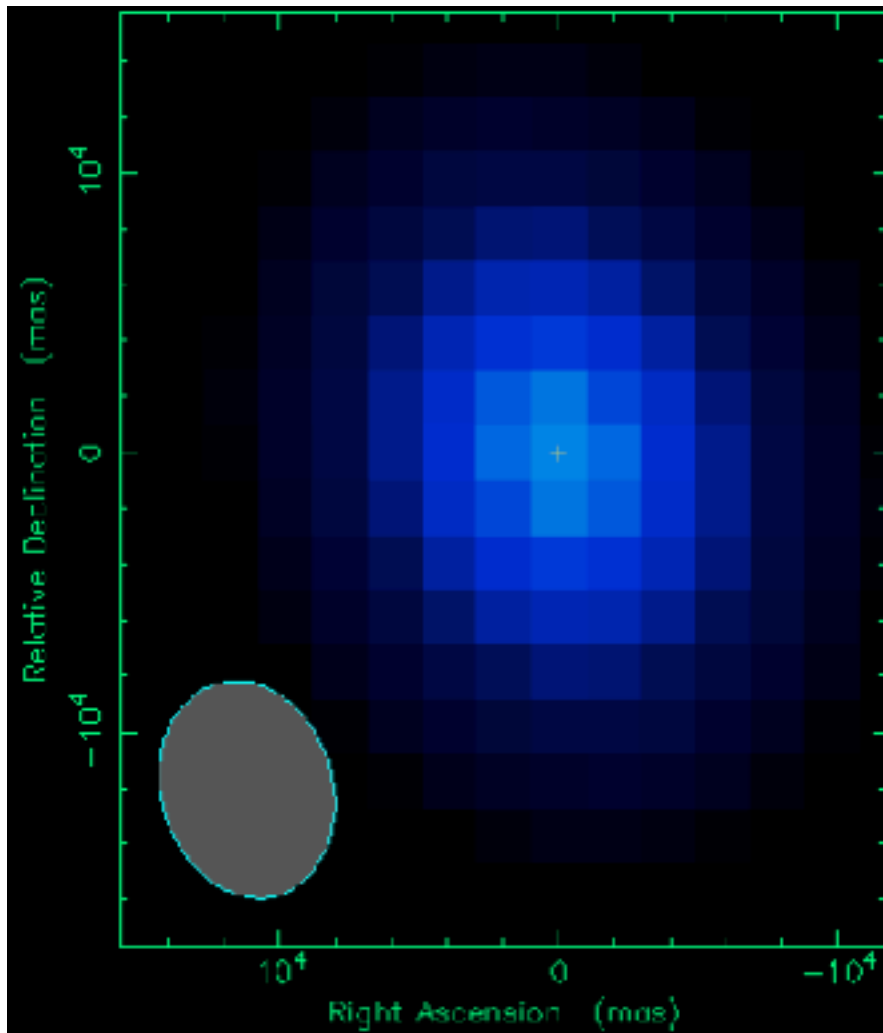
Deconvolved



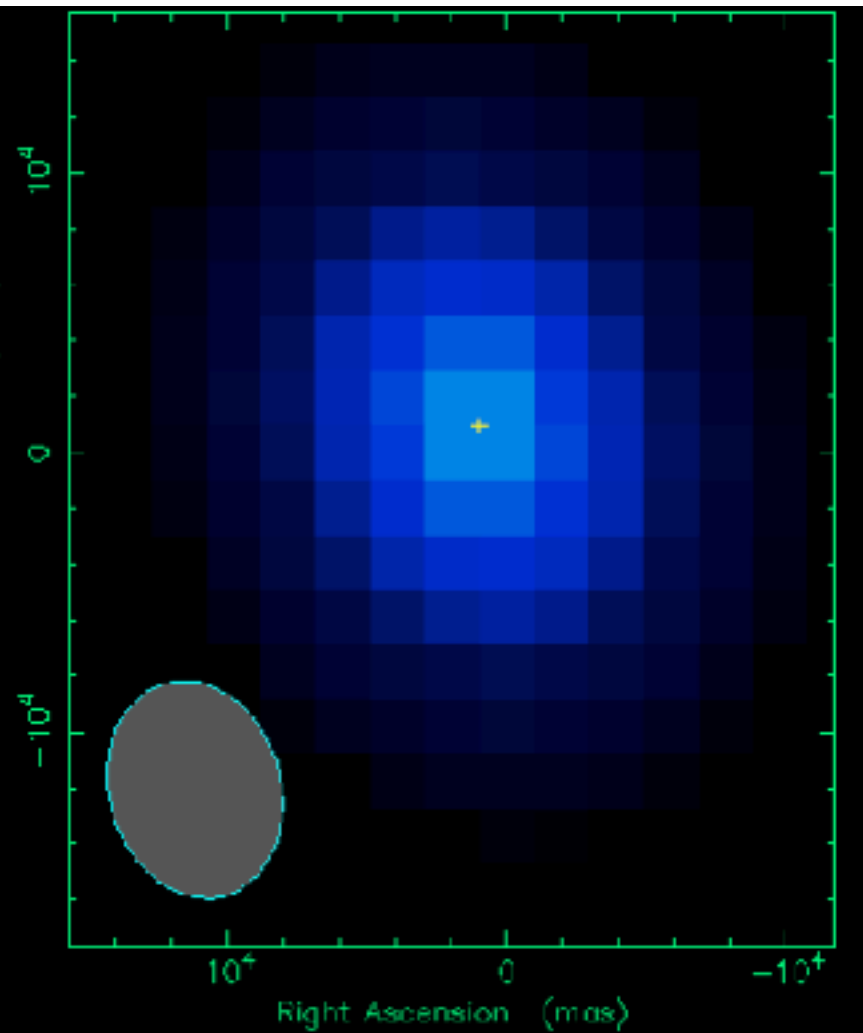
Peeled



Peeling applicable to transient and variable sources too.



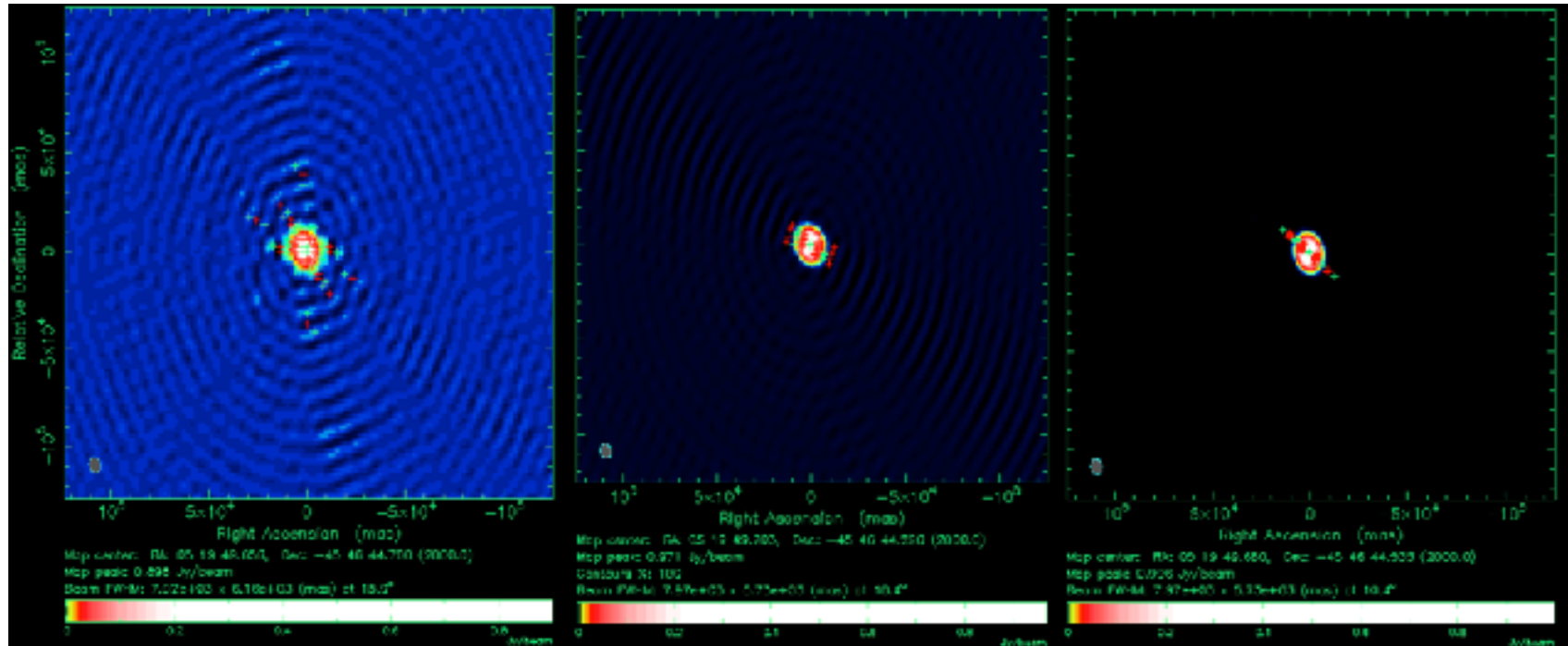
Pixel centred



Pixel not centred



# Point Deconvolution Errors



Cell size = beam/3

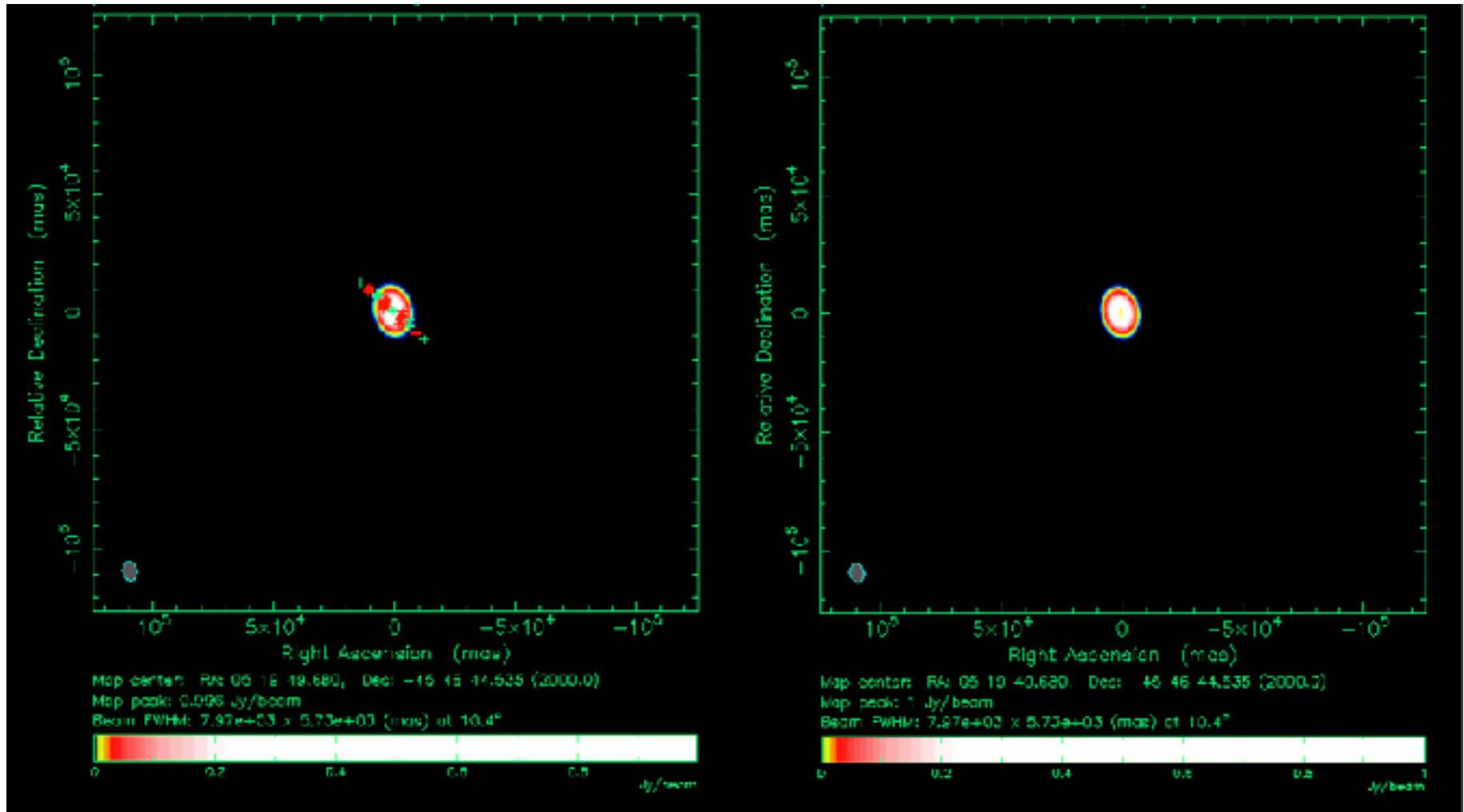
Cell size = beam/6

Cell size = beam/12

Effect of CLEAN performed on a single 1 Jy source that is not pixel-centred using different cell sizes.

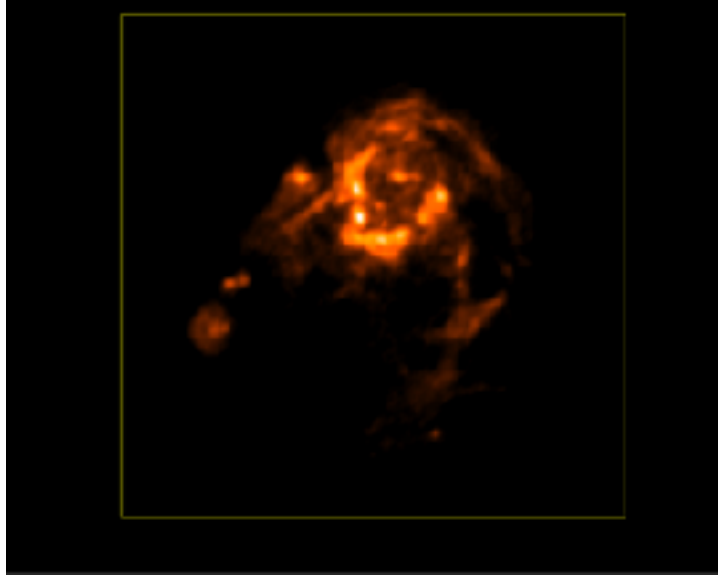


# Point Deconvolution Errors

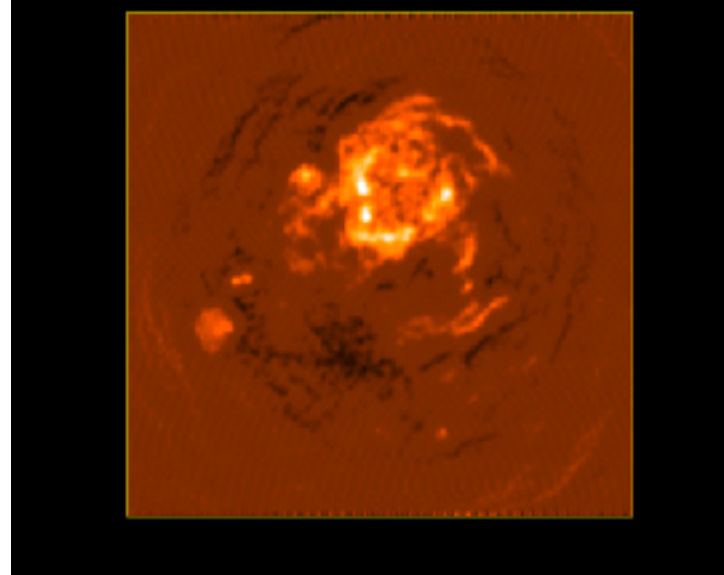


CLEAN : Cell size = beam/12

Single uv-delta model component

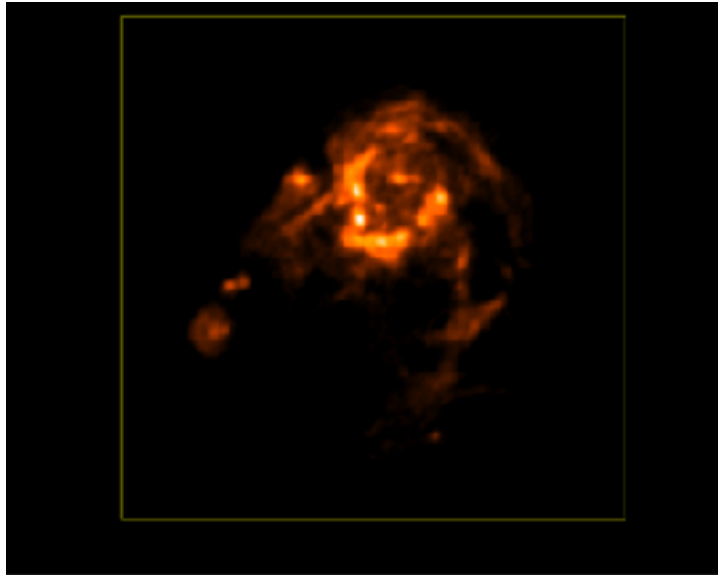


True sky

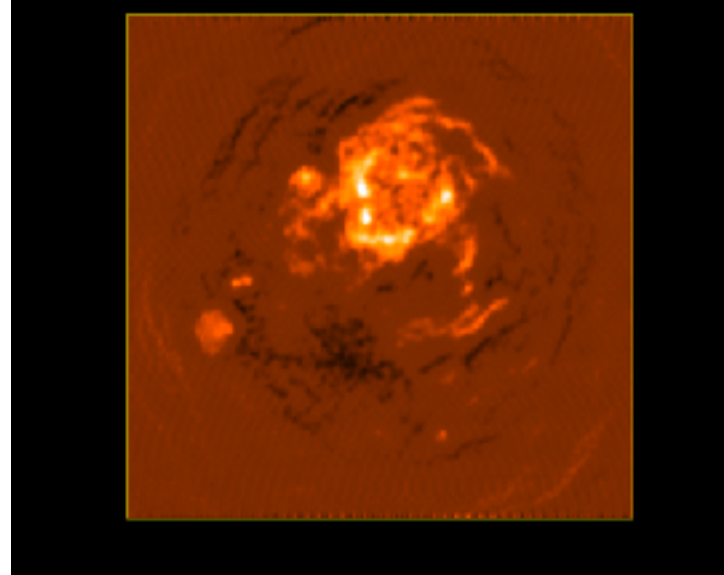


Standard CLEAN

Standard CLEAN does not handle large-scale structure well – results in negative bowls. More modern algorithms such as Multi-scale CLEAN are necessary to minimise deconvolution errors.



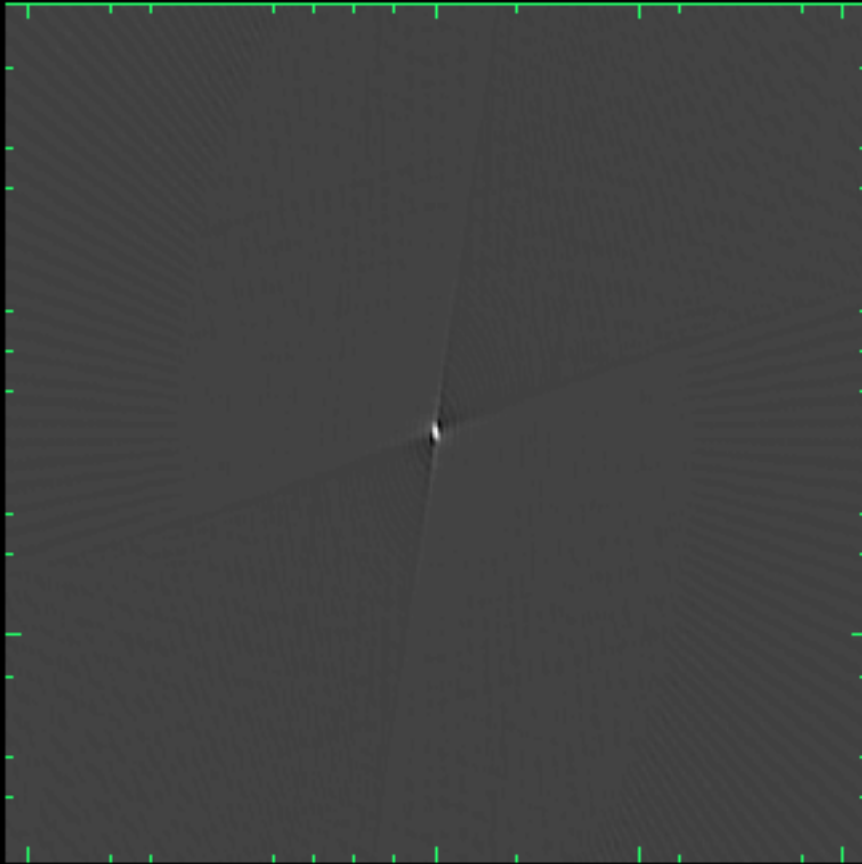
True sky



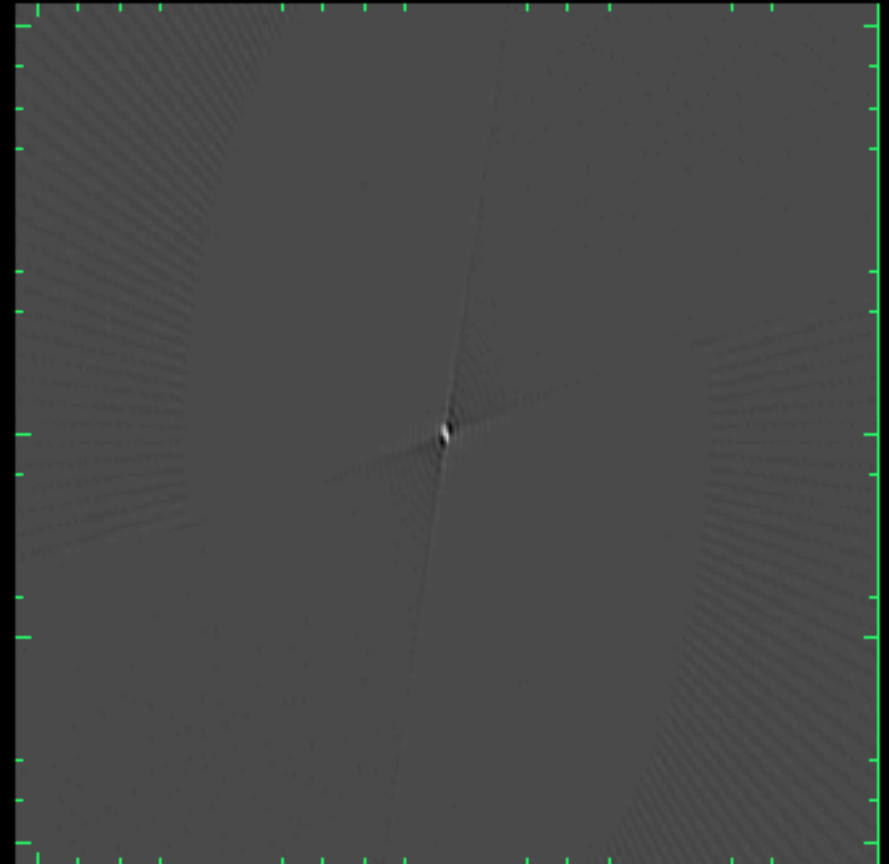
Standard CLEAN

Standard CLEAN does not handle large-scale structure well – results in negative bowls. More modern algorithms such as Multi-scale CLEAN are necessary to minimise deconvolution errors.

Dirty Image (2.1 GHz CABB Obs)

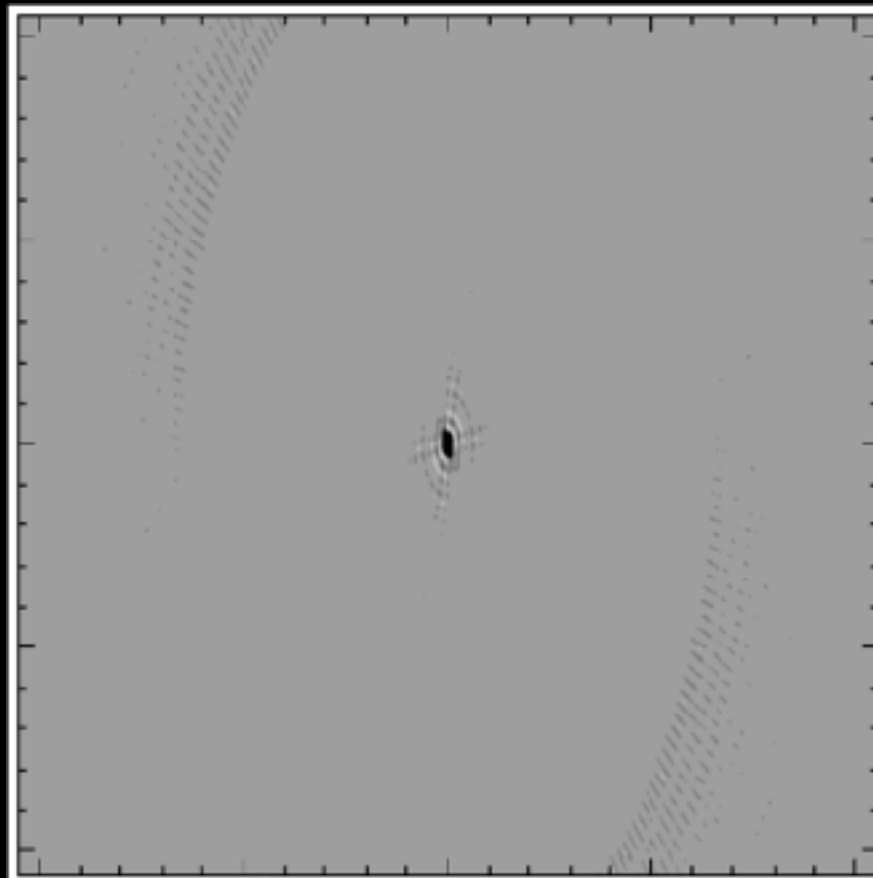


PSF





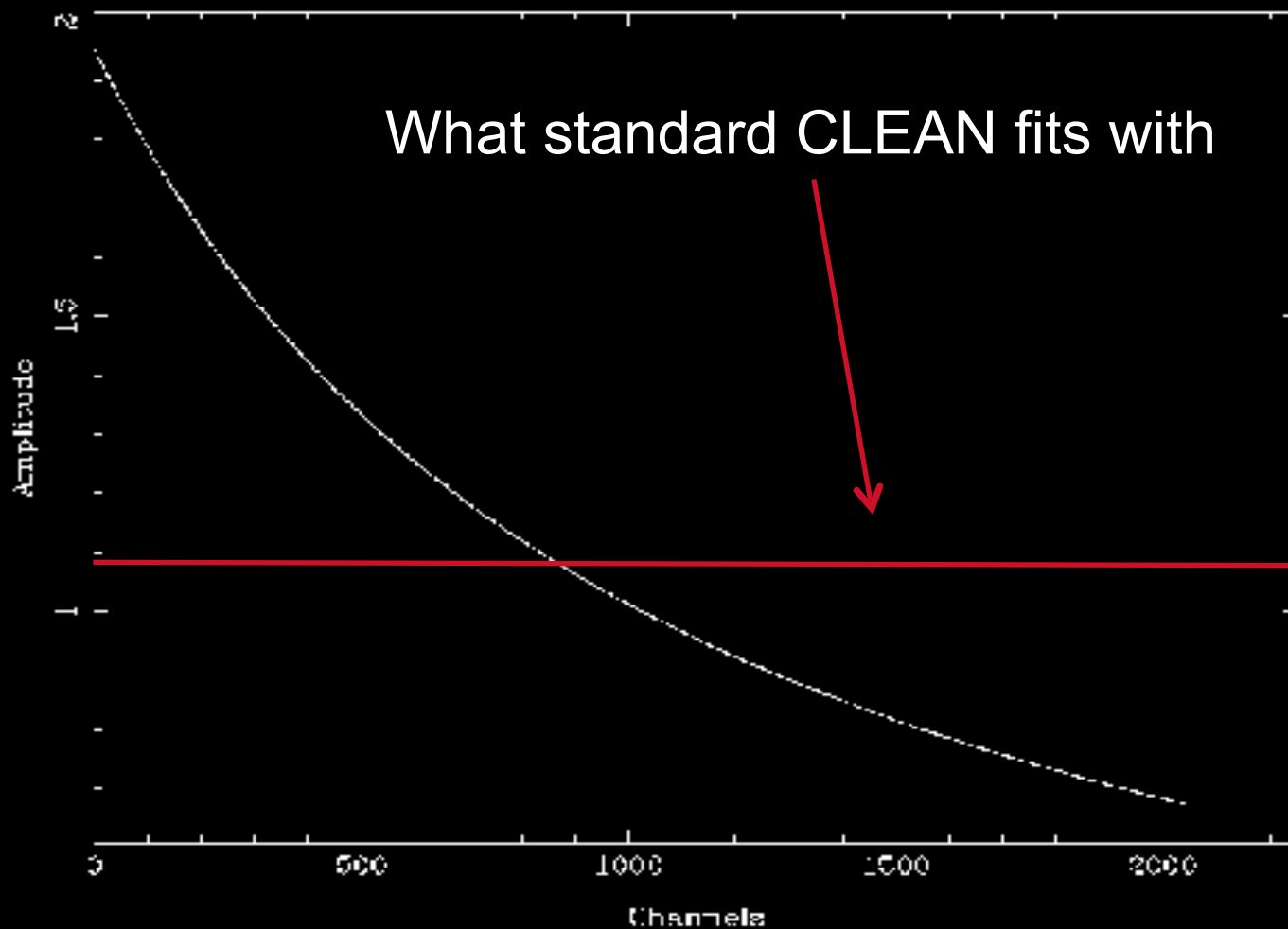
Deconvolved Image



Standard CLEAN

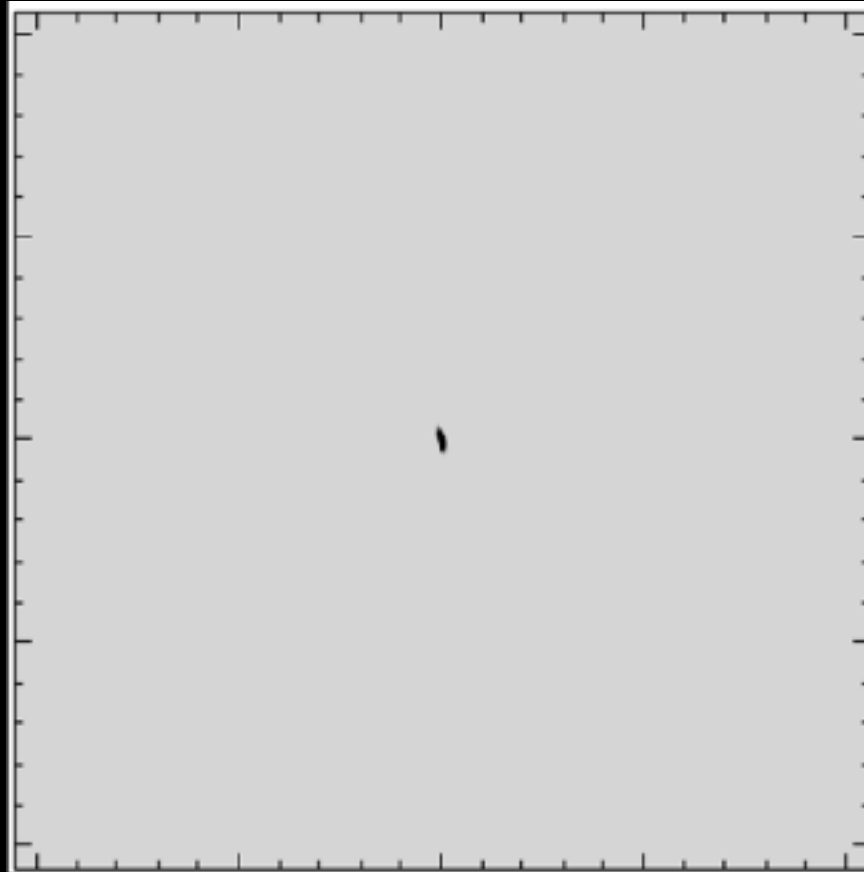


## Source SED





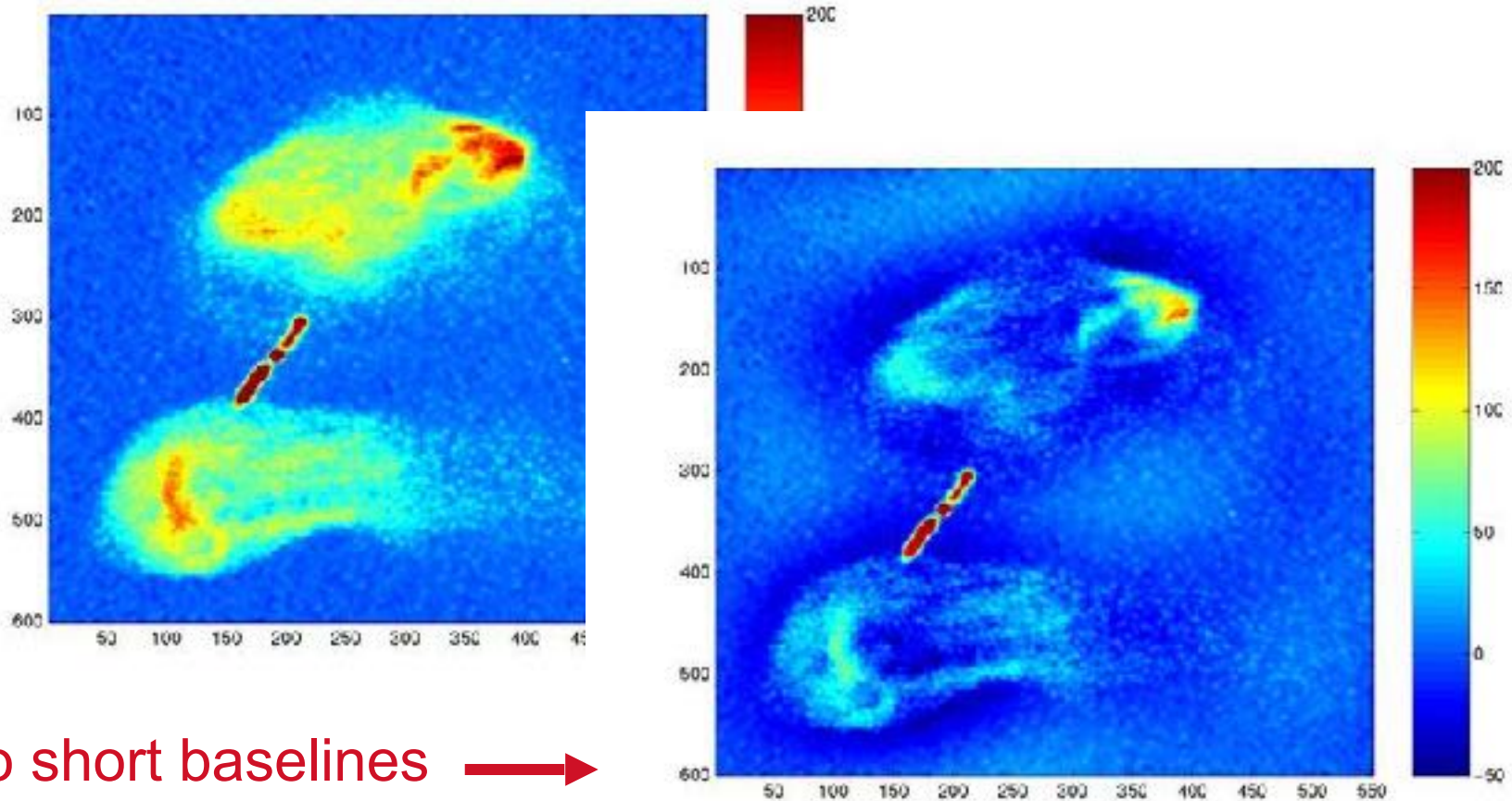
Deconvolved Image



Multi-frequency CLEAN



# Missing short baselines



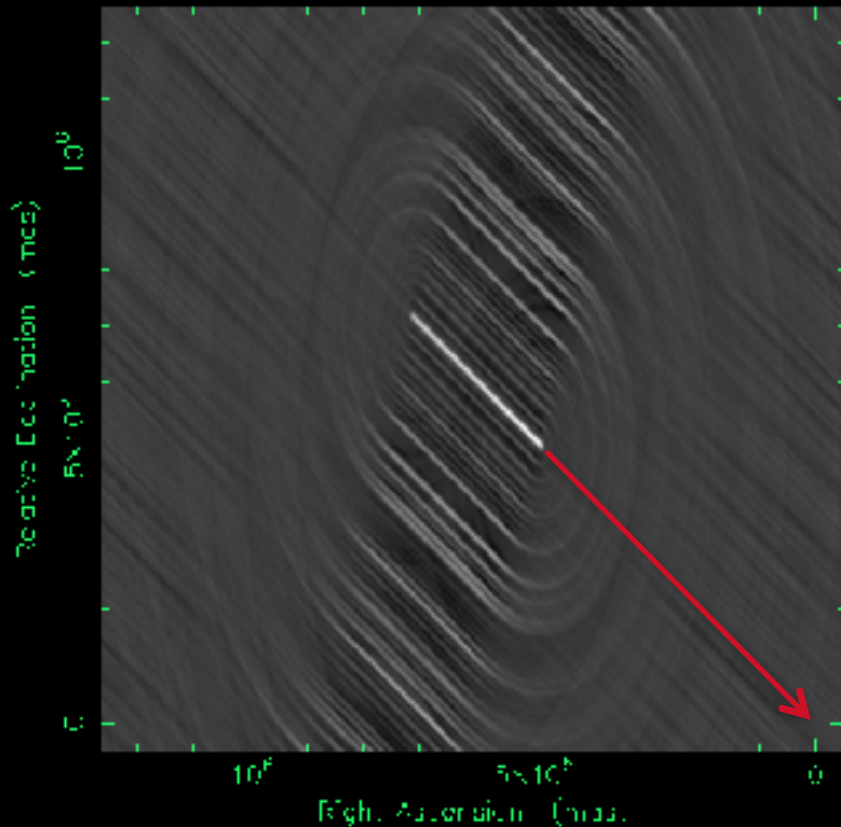
No short baselines →

Can only be fixed with additional data.  
See Shari's talk on observing strategies.

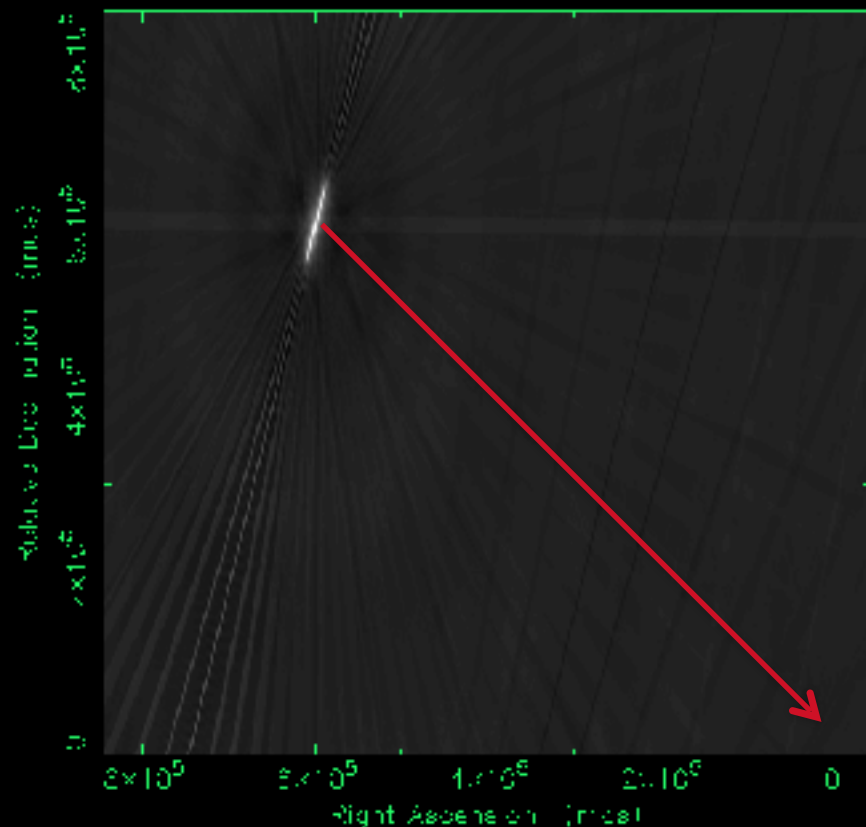
Paul Rayner 2001



# Smearing Errors



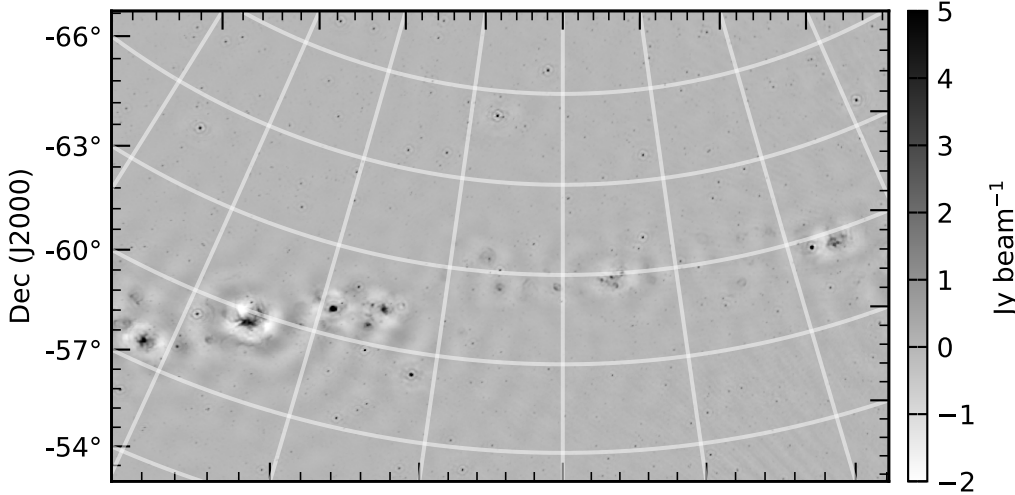
Bandwidth average  
smearing  
Average 512x1MHz band



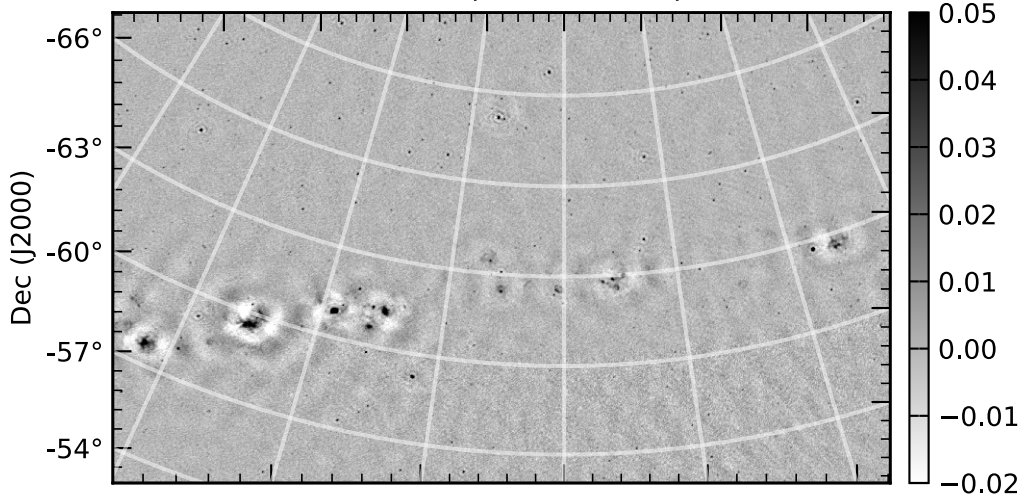
Time-average smearing  
Averaging 1000s

# Reality check

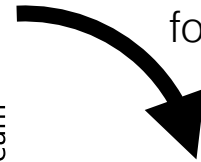
Stokes I



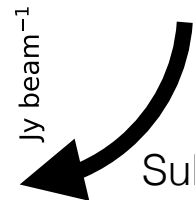
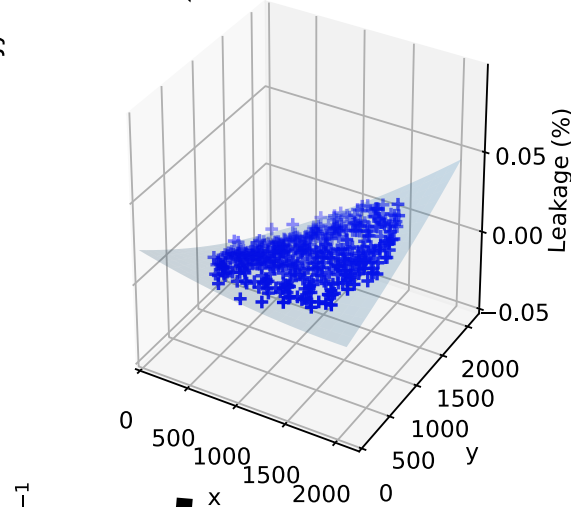
Stokes V (uncorrected)



Model Stokes I to Stokes V leakage  
for each beam-former setting



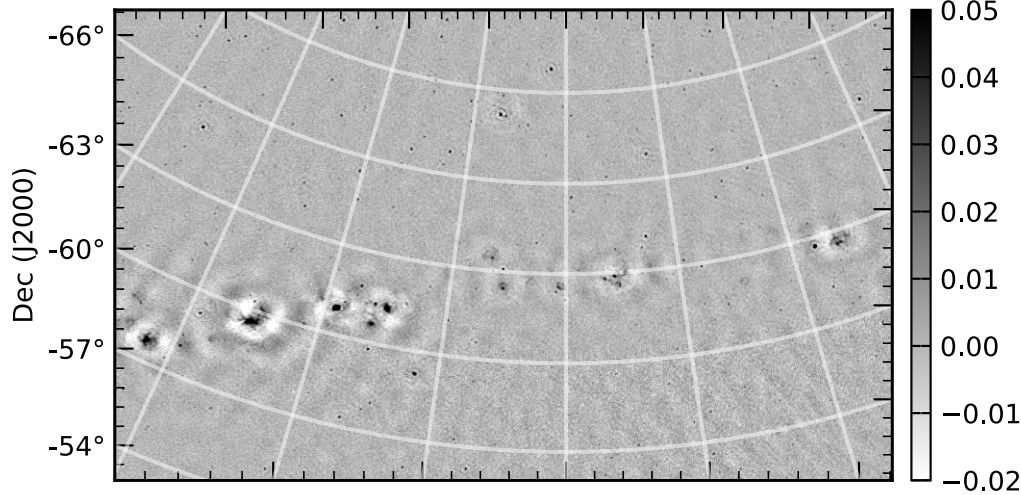
Stokes V



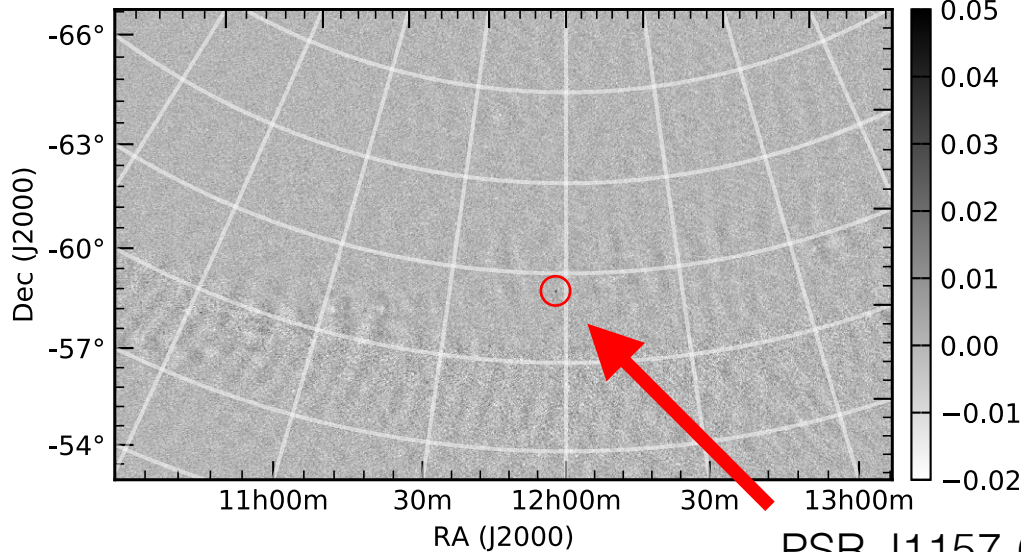
Subtract modelled component of  
leakage from Stokes V.

# Reality check

Stokes V (uncorrected)

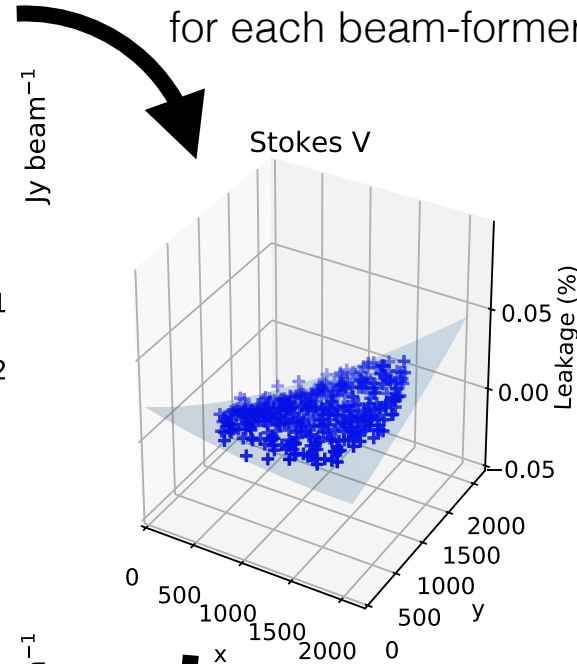


Stokes V (corrected)



PSR J1157-6224

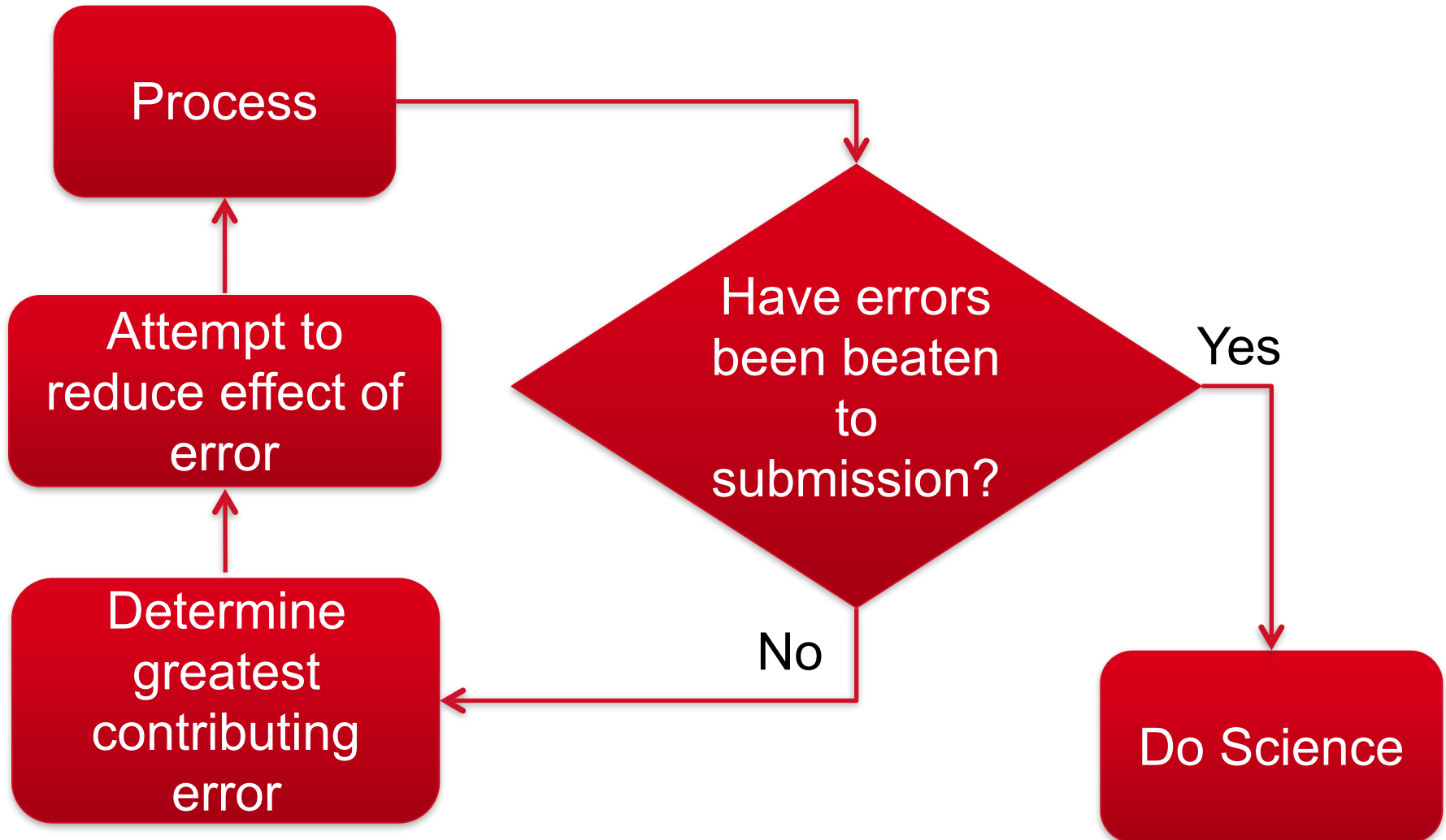
Model Stokes I to Stokes V leakage  
for each beam-former setting



Subtract modelled component of  
leakage from Stokes V.



- › Avoid sausage factory processing (at least initially)
  - Try to understand each processing step.
  - Look closely at the data after each step, check and image calibrators.
  - Does the data look plausible.
- › Take a different perspective
  - Look at your data in different domains (time, (u,v), image, frequency).
  - Plot different combinations of variables in different spaces.
  - Look at residuals, FT your dirty image, FT your beam.
- › Process your data in different ways
  - Try different software, algorithms.
  - Partition and process your data in different ways
  - Try split in time chunks, split up frequency band
  - Different weighting, different uv tapers.

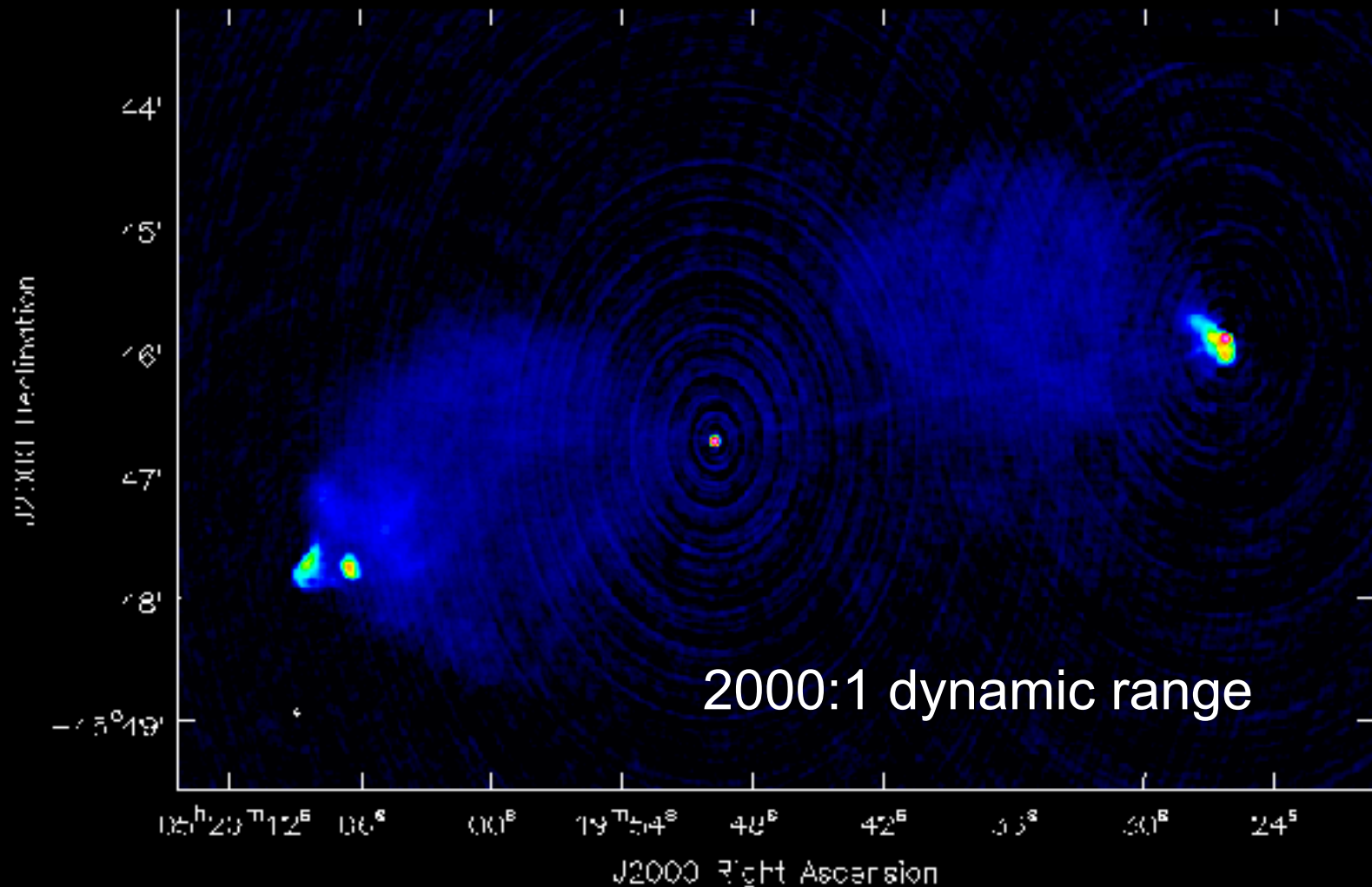




# What's happening?



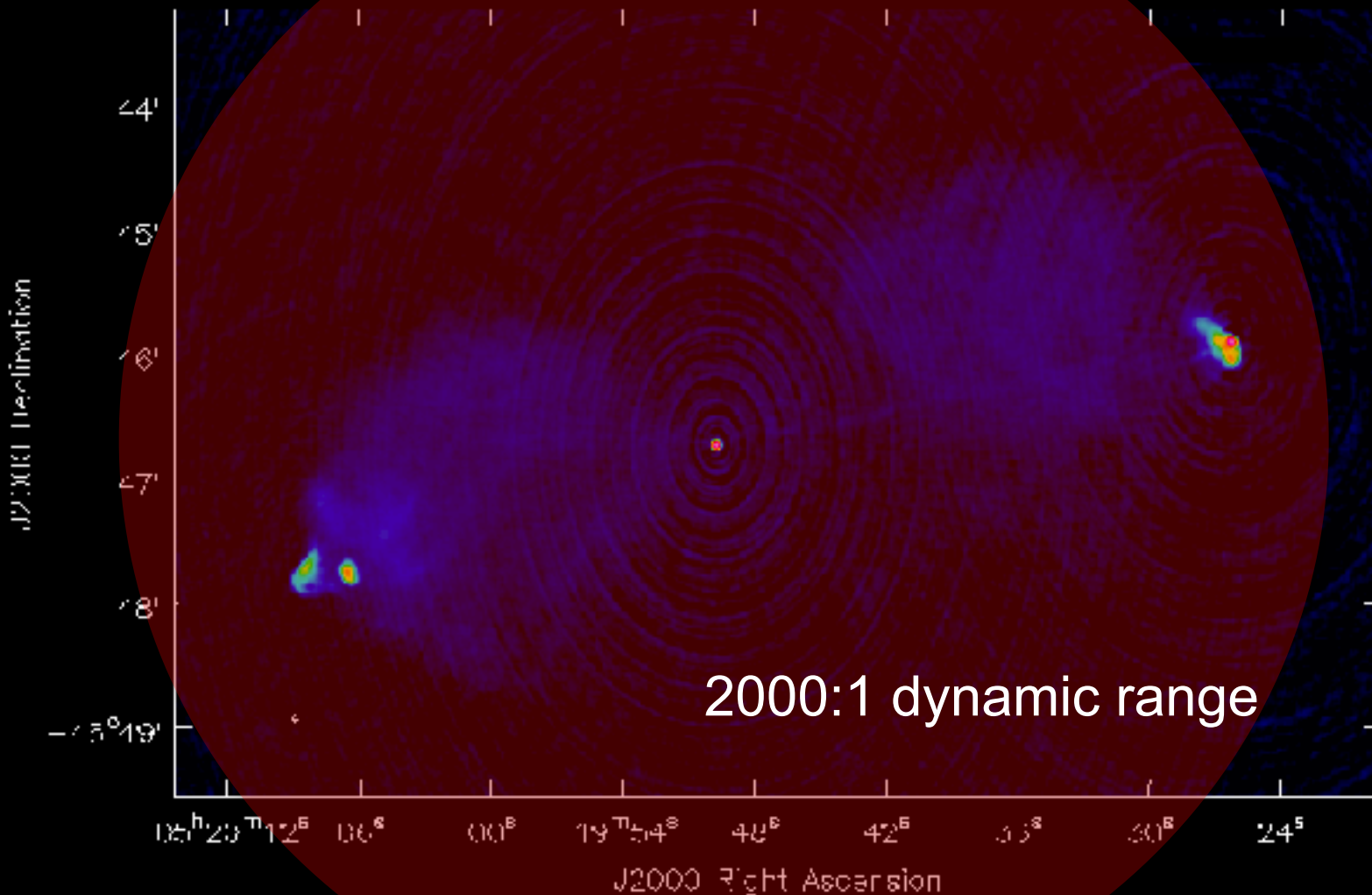
5.5 GHz observation, 3 configurations, 2 GHz bandwidth





# What's happening?

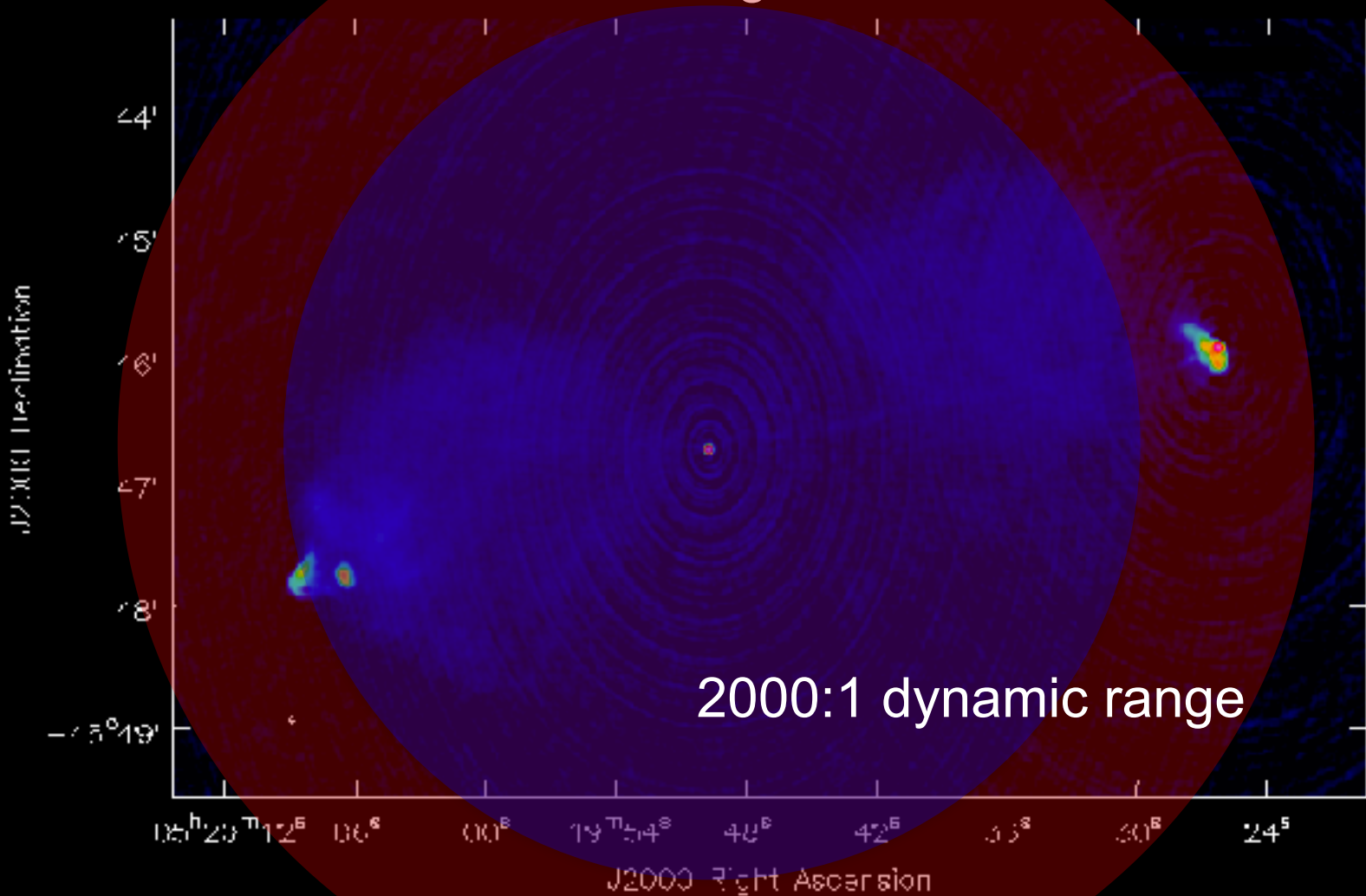
5.5 GHz observation, 3 configurations, 2 GHz bandwidth





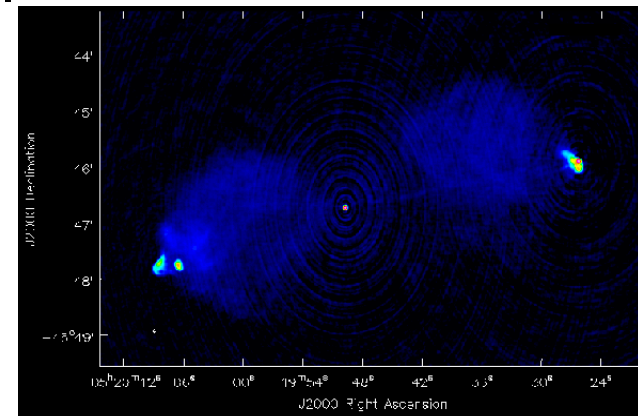
# What's happening?

5.5 GHz observation, 3 configurations, 2 GHz bandwidth



# What's happening

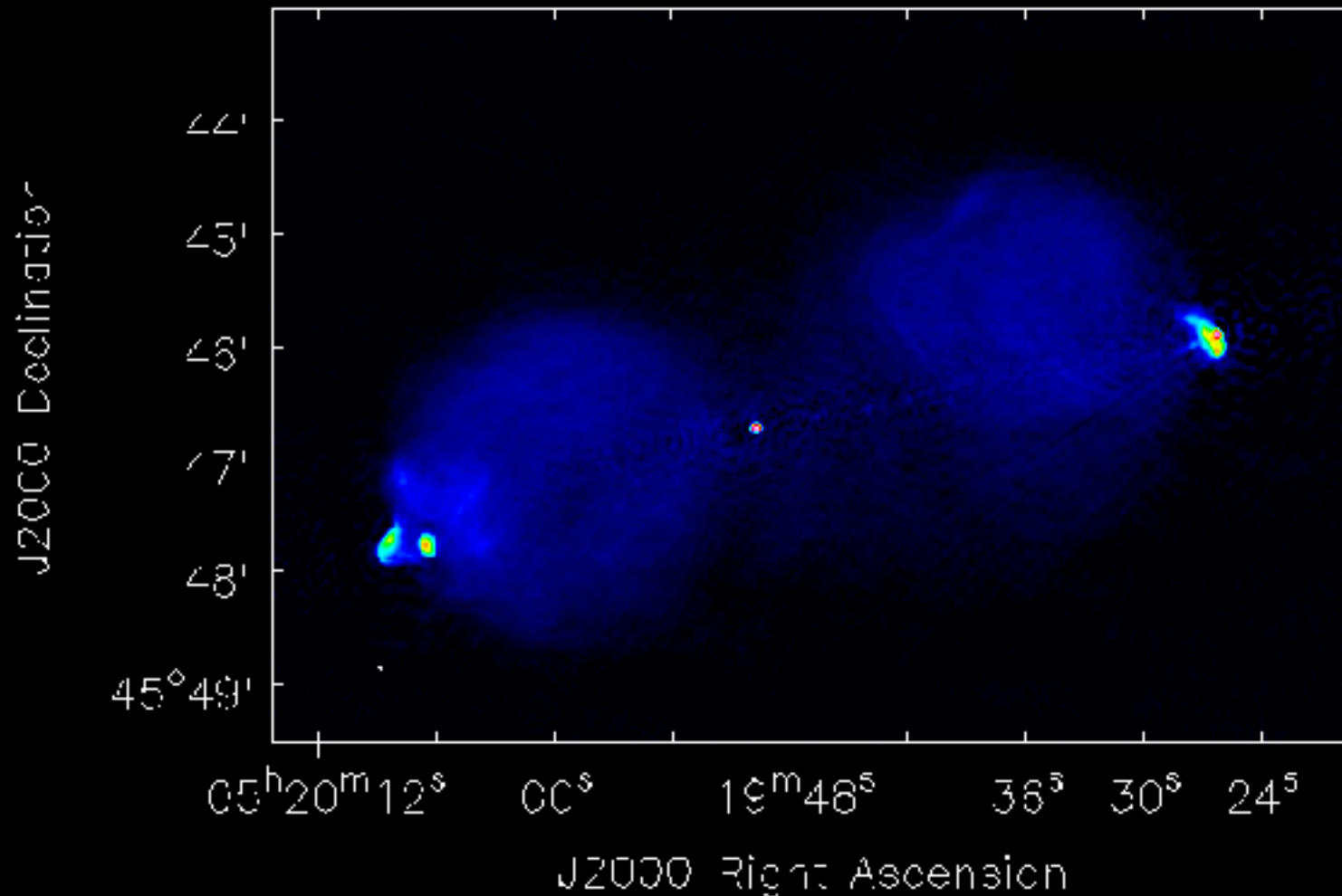
- › Amplitude calibration errors.
- › Hot spot near edge of 4.5 GHz beam (outside 6.5 GHz beam)
  - Causes steepening of source spectra.
  - Causes position dependent effects.
  - Will need to consider peeling techniques.
- › Spectral variation throughout the image (flat and steep)
  - Must use multi-frequency deconvolution.
- › Structures on many different scales.
  - Must use appropriate deconvolution algorithms.
- › North-west hot spot is bright and slightly extended.
  - Difficult to deconvolve accurately.
  - Small cell size or uv-subtract component.





# What's happening?

38,000:1 dynamic range



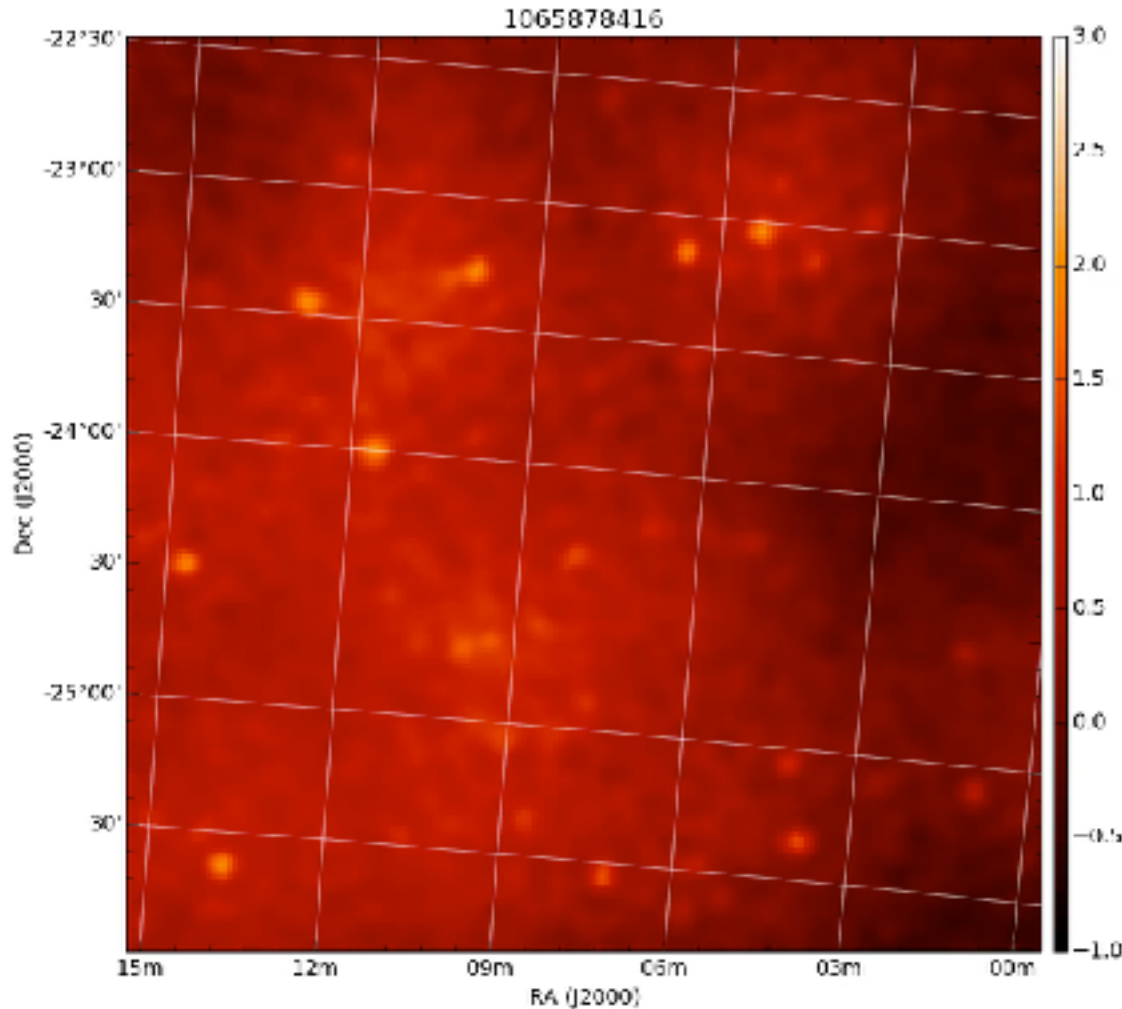


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# 1. Can you deal with something new? What's happening?

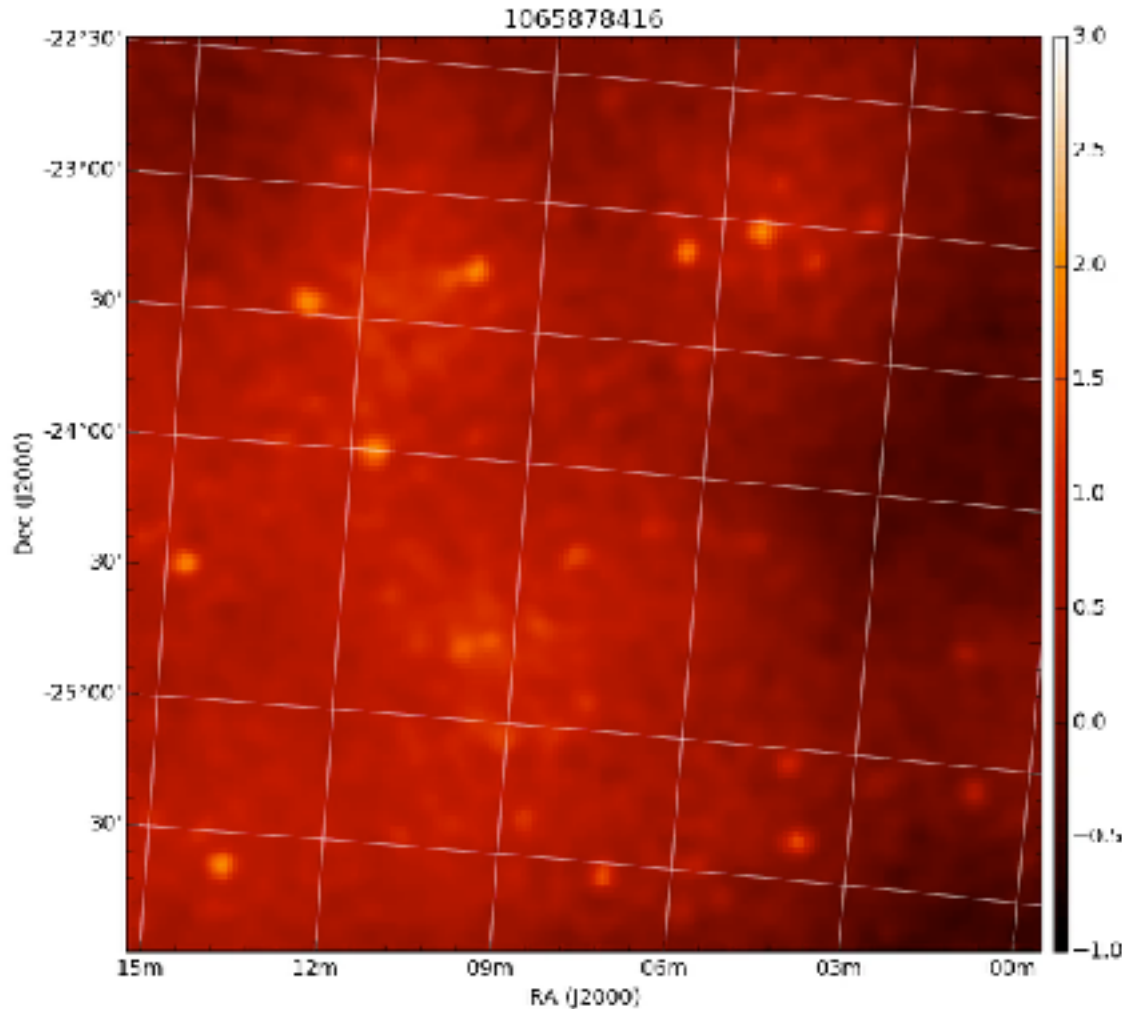


Low frequency MWA obs.

- A. Heat haze
- B. Antenna deformation
- C. Ionosphere
- D. Compression artifacts



# 1. Can you deal with something new? What's happening?

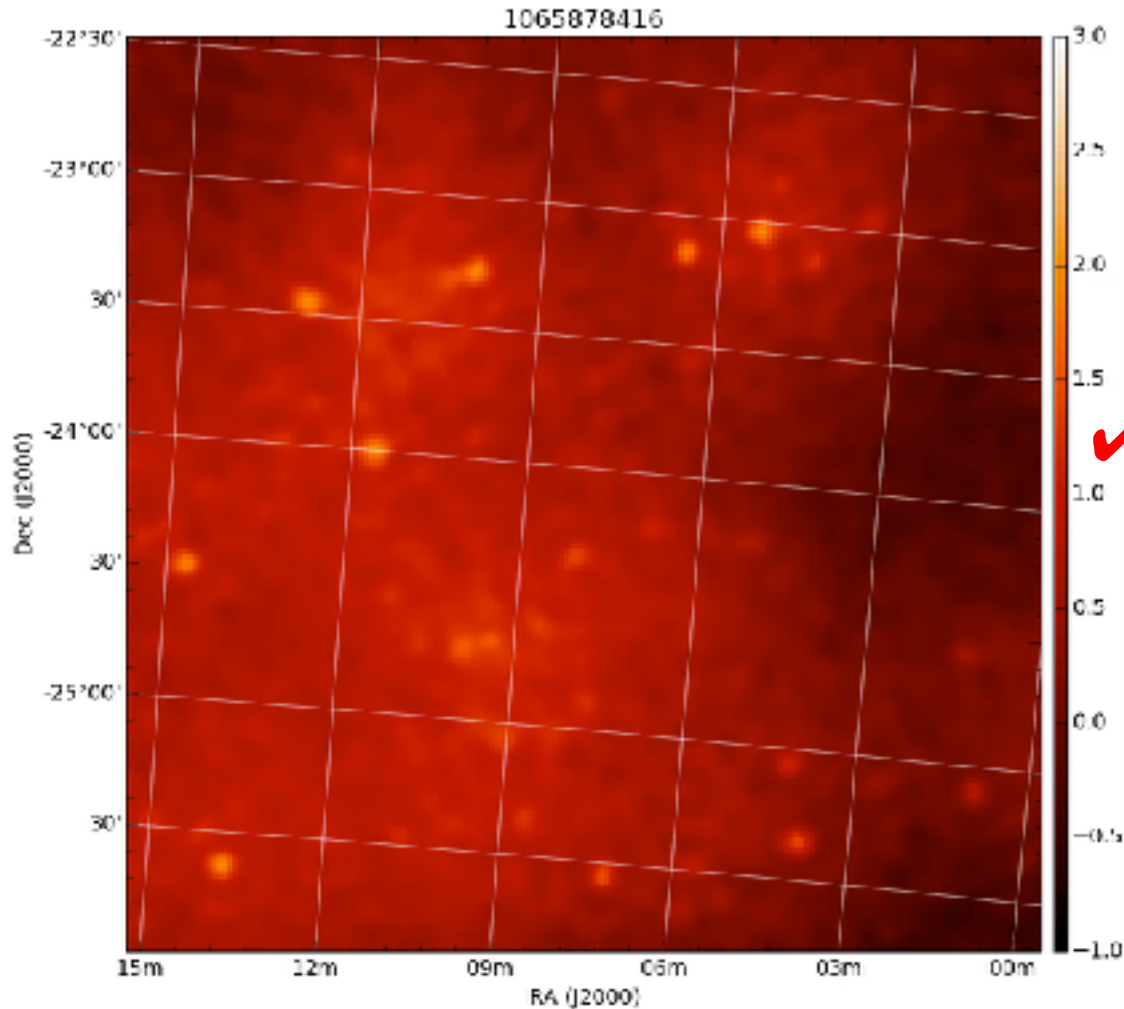


Low frequency MWA obs.

- A. Heat haze
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- C. Ionosphere
- D. Compression artifacts



# 1. Can you deal with something new? What's happening?

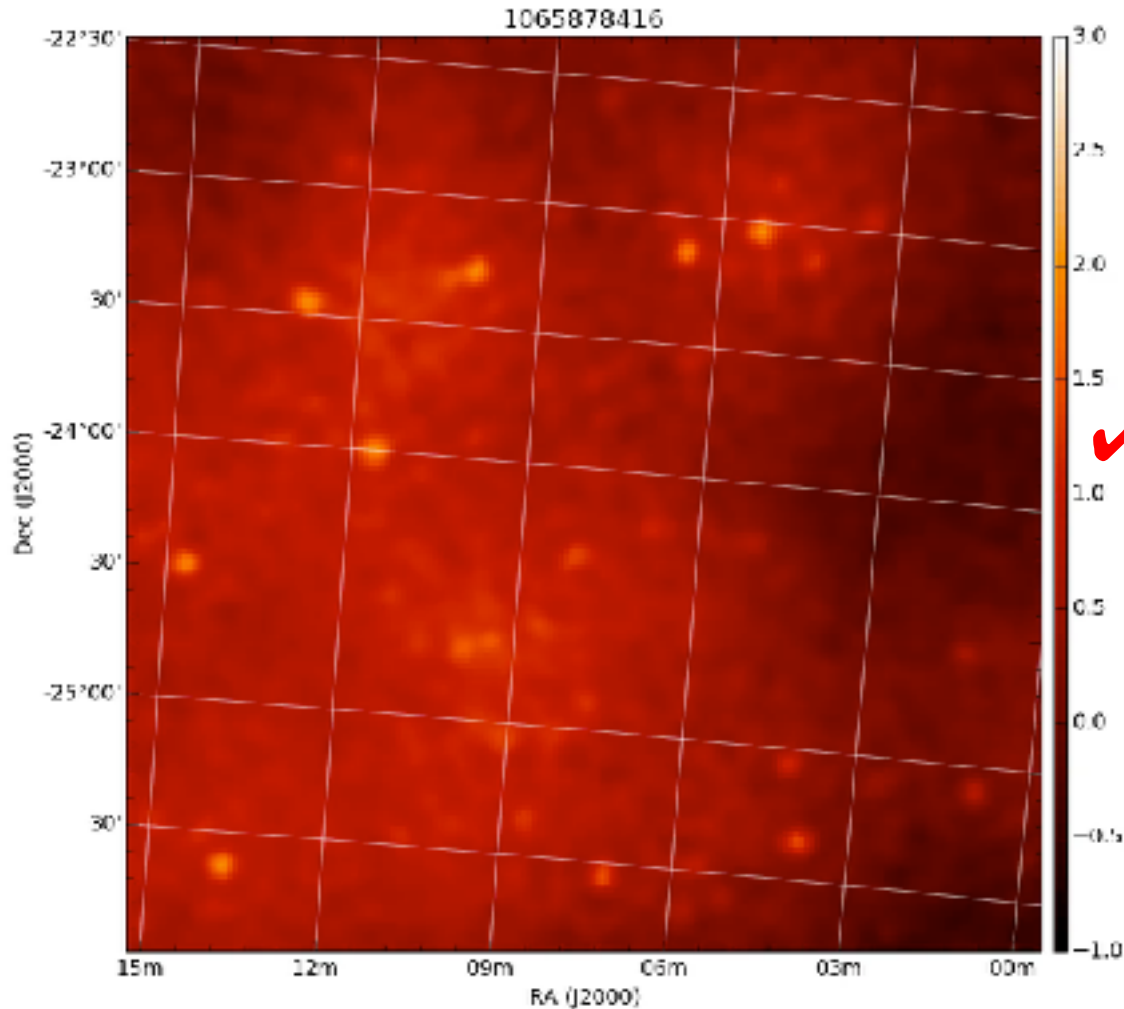


Low frequency MWA obs.

- A. Heat haze
- B. Antenna deformation
- ✓ C. Ionosphere
- D. Compression artifacts



# 1. Can you deal with something new? What's happening?

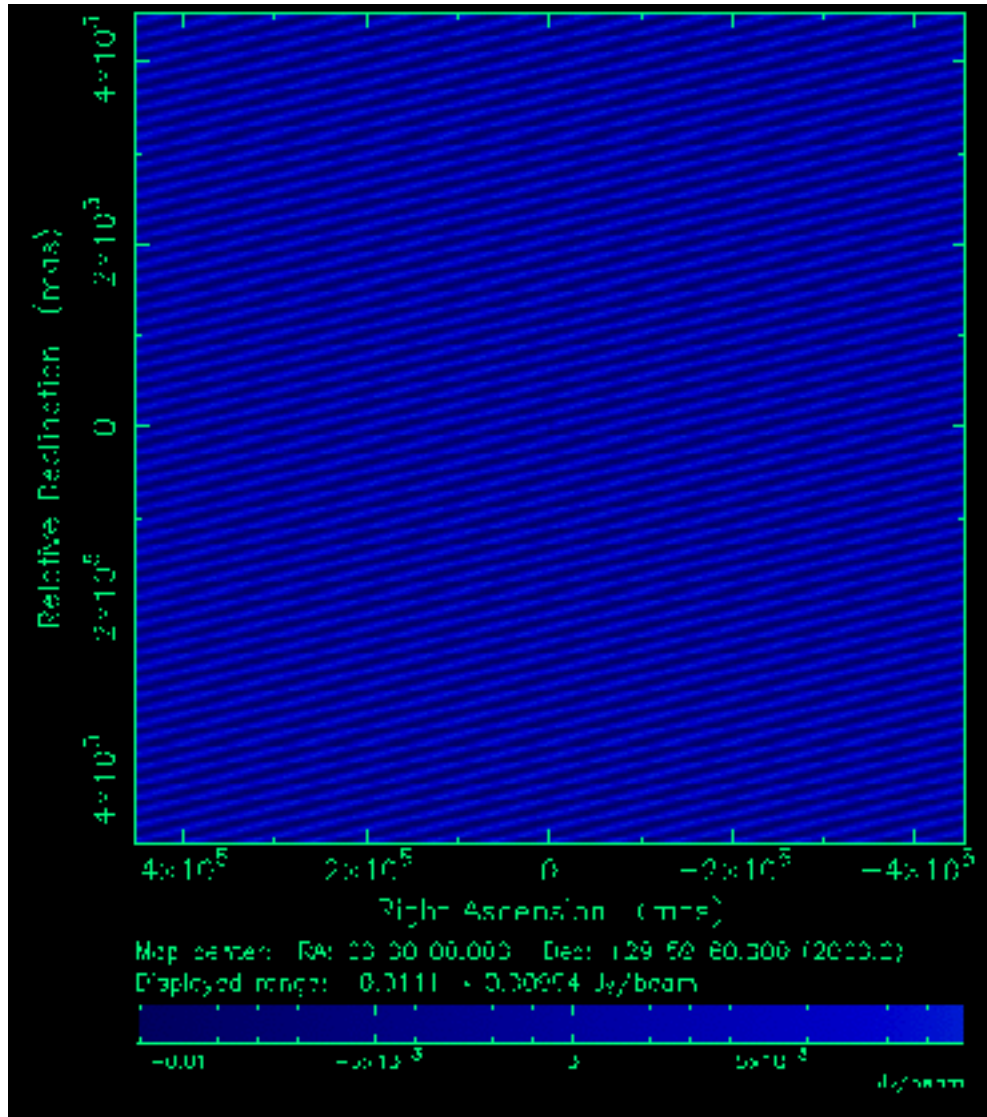


Low frequency MWA obs.

- A. Heat haze
- B. Antenna deformation
- ✓ C. Ionosphere
- D. Compression artifacts



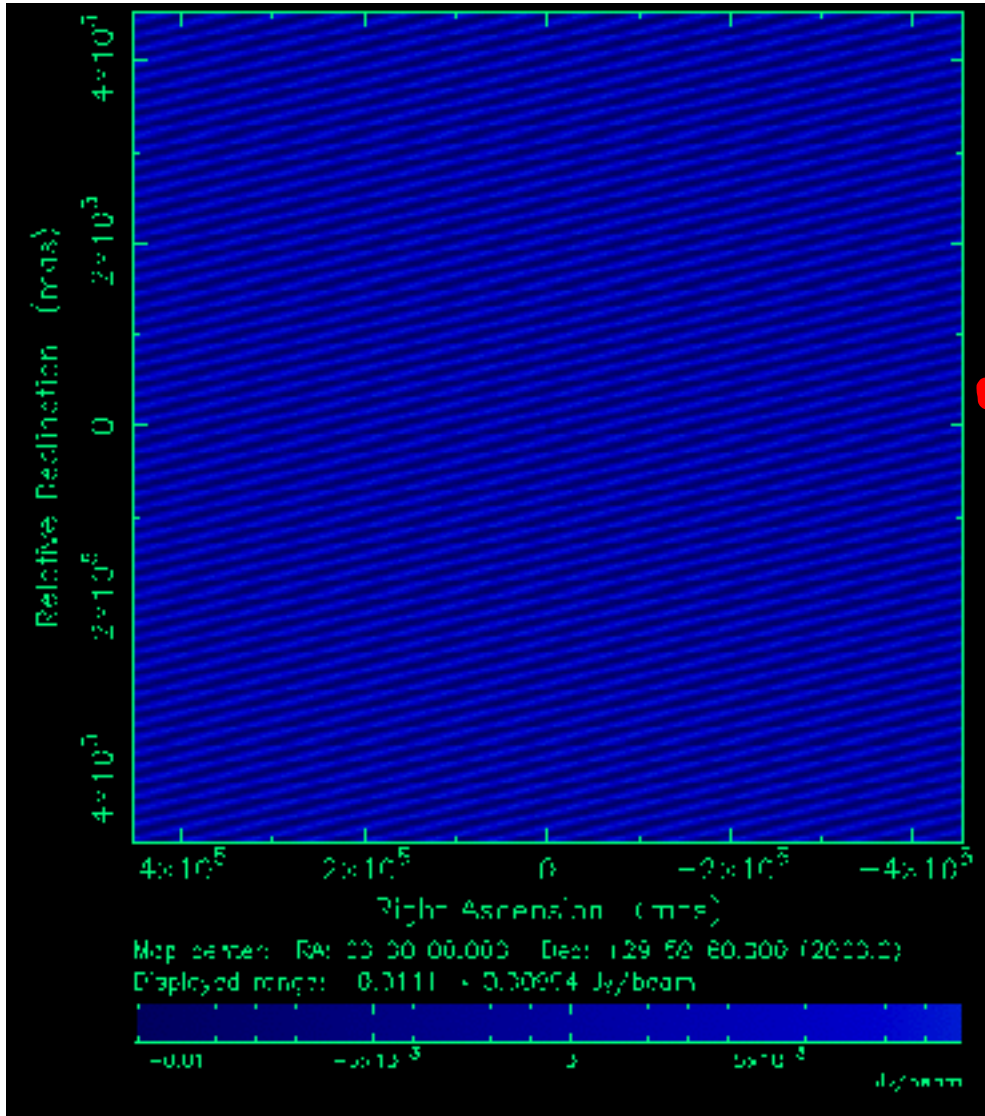
## 2. Be daring in your search What's happening?



- A. Primary Beam error
- B. RFI
- C. Venetian blinds left open
- D. Deconvolution error



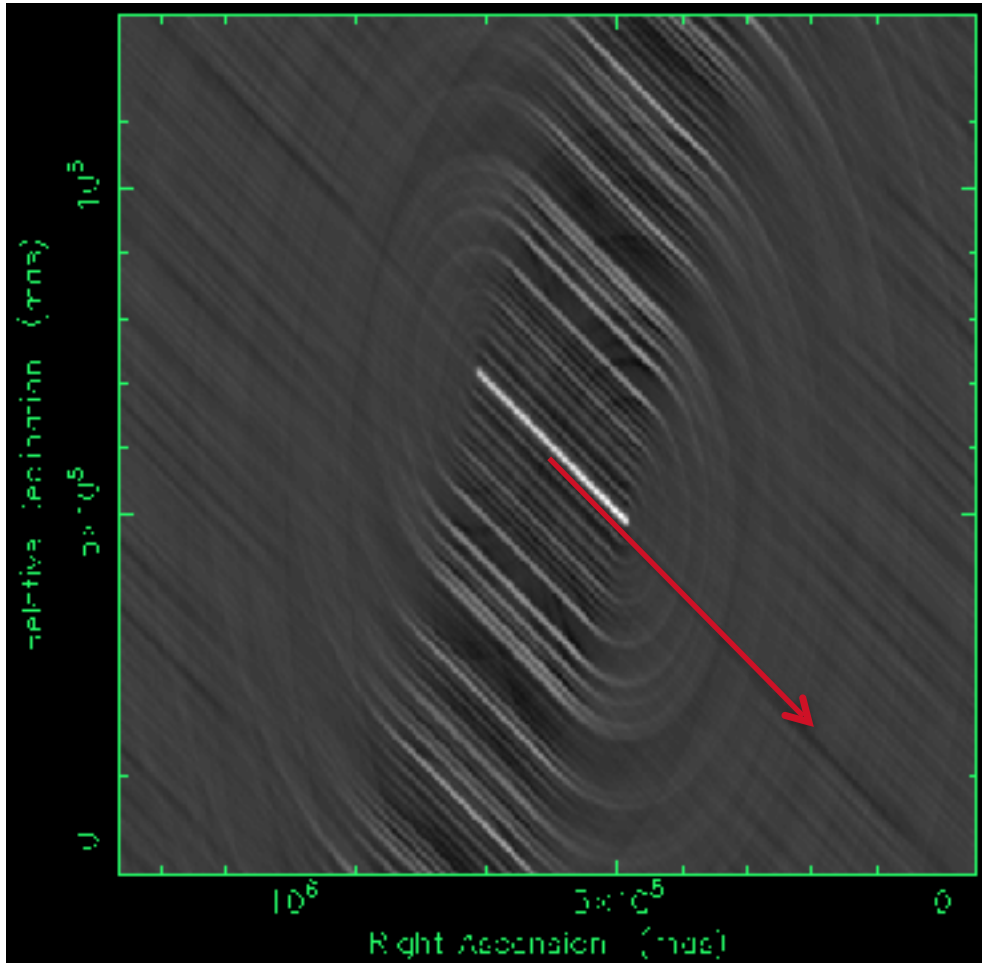
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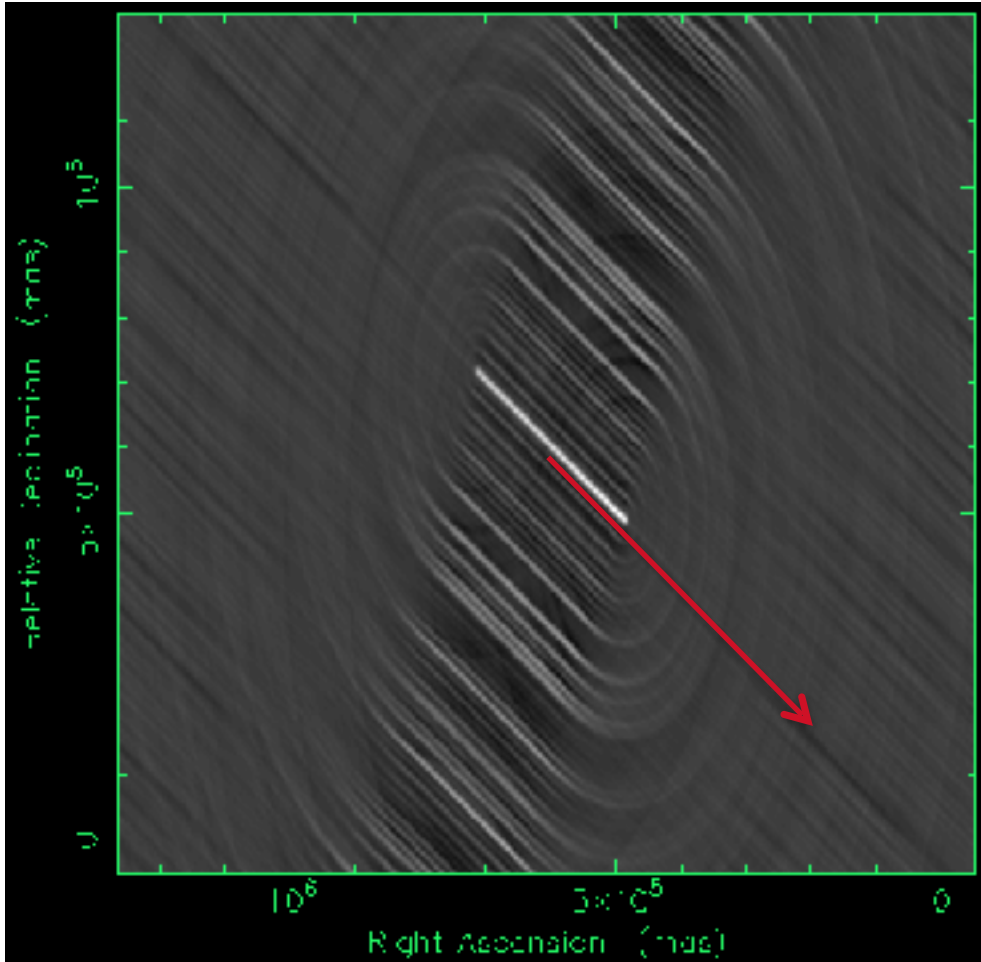
### 3. Can you work this out? What's happening?



- A. Amplitude errors
- B. Cosmic ray
- C. Bandwidth smearing
- D. RFI



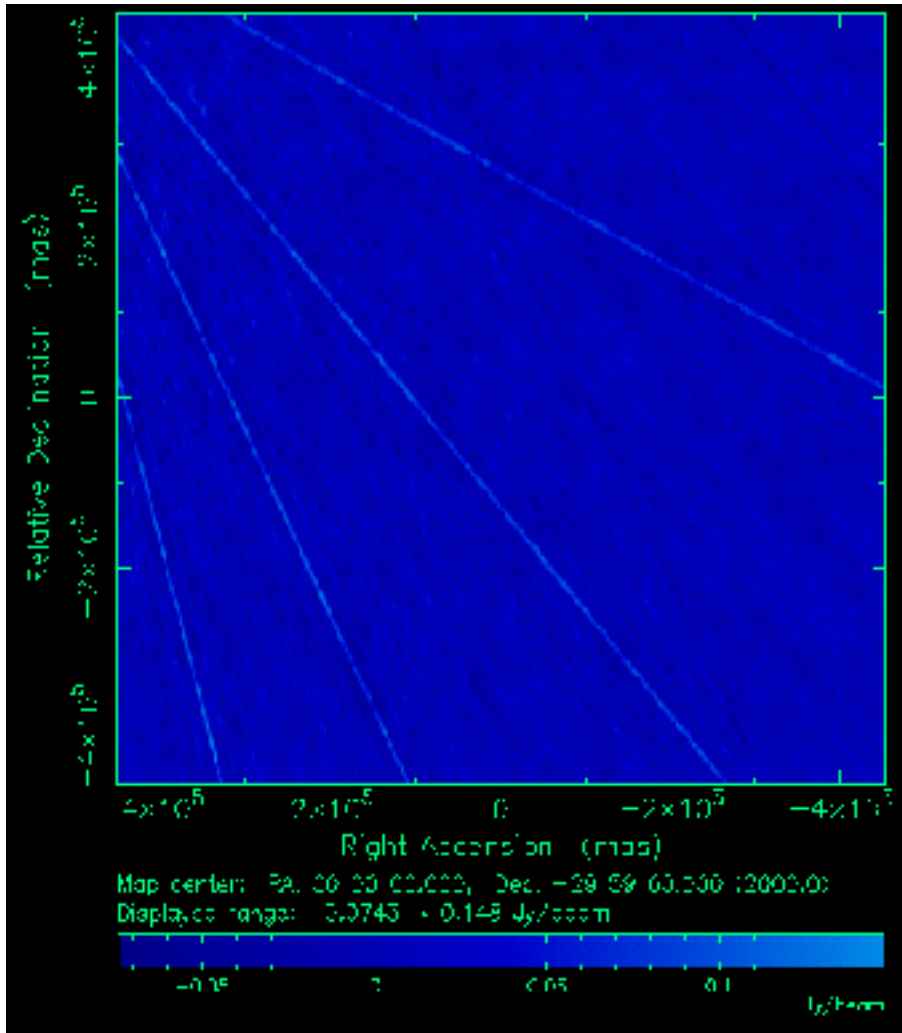
### 3. Can you work this out? What's happening?



- A. Amplitude errors
- B. Cosmic ray
- ✓ C. Bandwidth smearing
- D. RFI



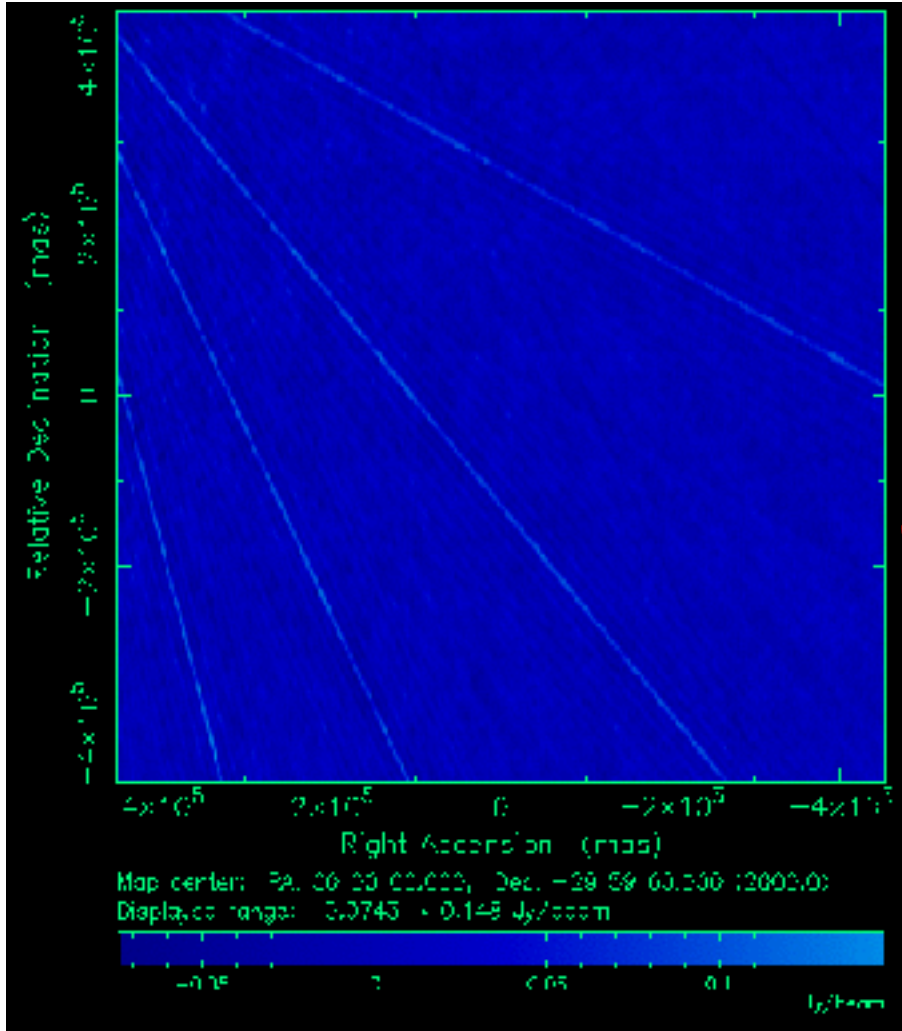
## 4. Dare to solve this! What's happening?



- A. Amplitude errors
- B. Phase of moon incorrect
- C. Position-dependent errors
- D. Source outside imaged field



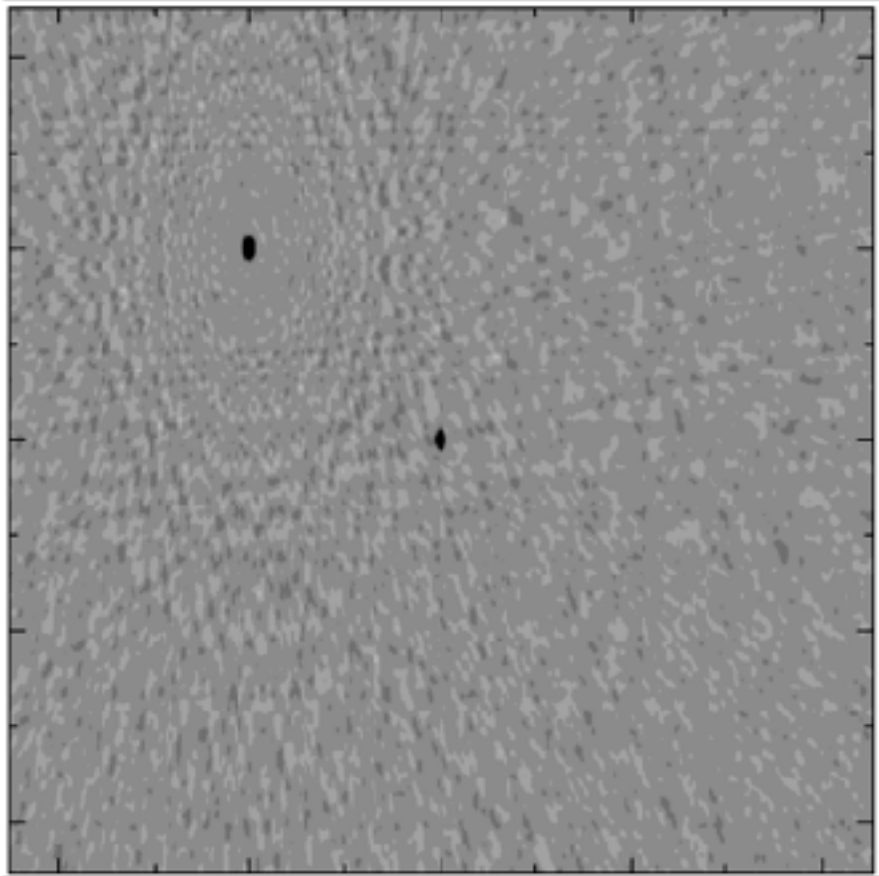
## 4. Dare to solve this! What's happening?



- A. Amplitude errors
- B. Phase of moon incorrect
- C. Position-dependent errors
- ✓ D. Source outside imaged field



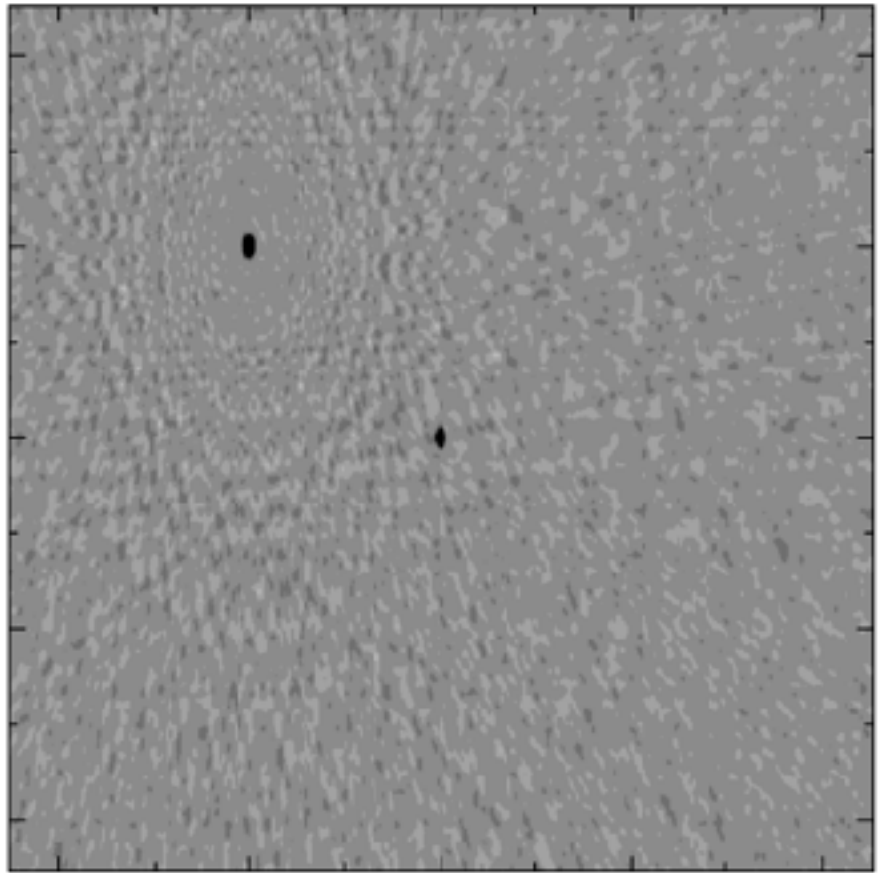
## 5. Don't give up! What's happening?



- A. RFI
- B. Bandwidth smearing
- C. Daylight savings not set
- D. Position-dependent errors



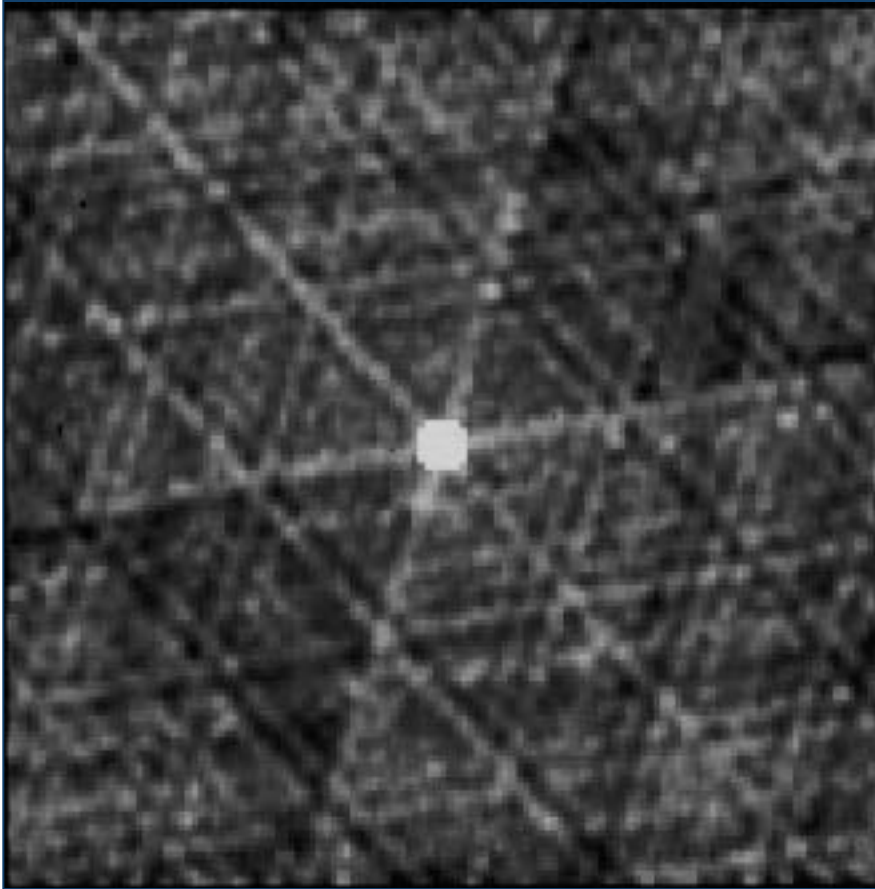
## 5. Don't give up! What's happening?



- A. RFI
- B. Bandwidth smearing
- C. Daylight savings not set
- ✓ D. Position-dependent errors



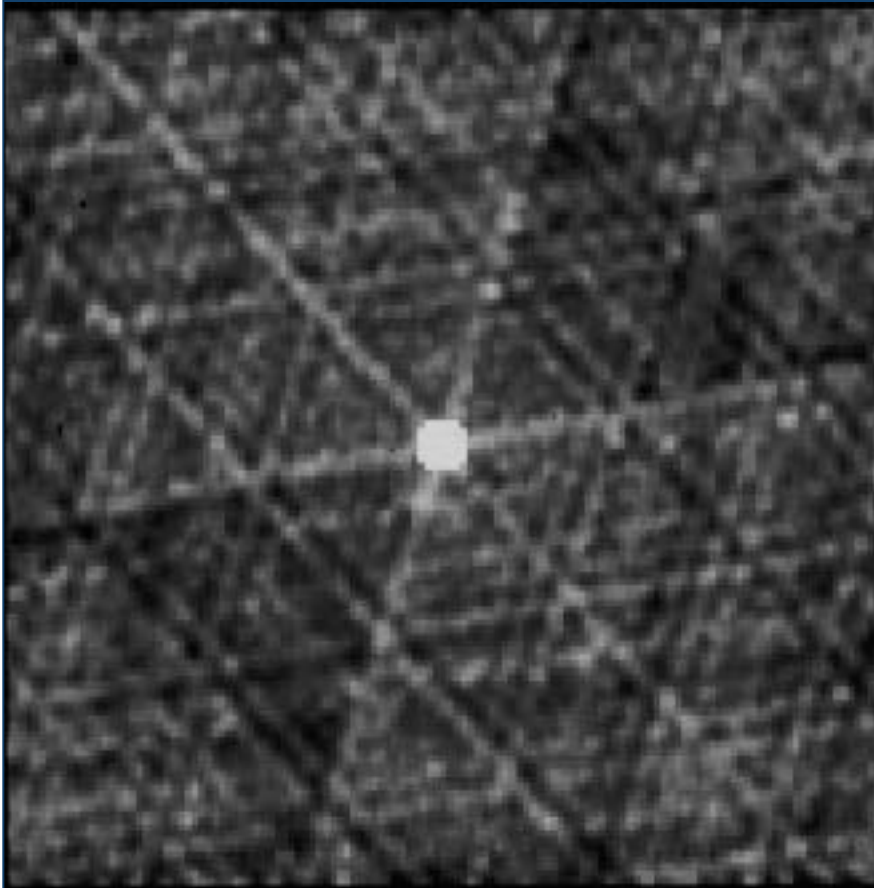
## 6. Are you able to solve this? What's happening?



- A. Amplitude errors
- B. Tartan from wrong clan
- C. Data stored in HEX
- D. Phase errors



## 6. Are you able to solve this? What's happening?

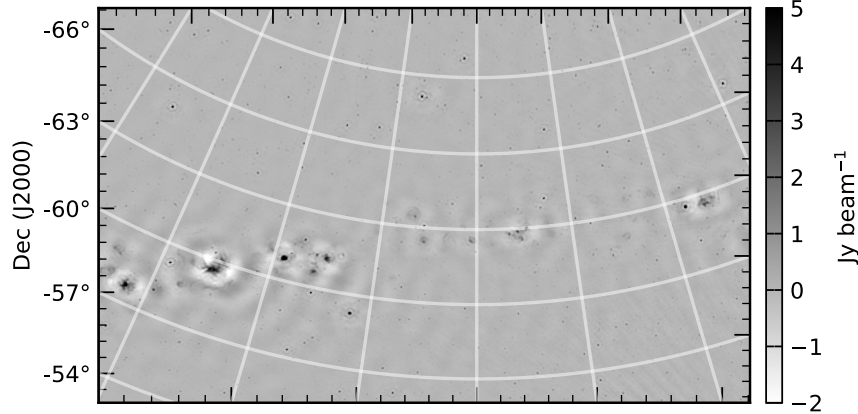


- ✓ A. Amplitude errors
- B. Tartan from wrong clan
- C. Data stored in HEX
- D. Phase errors

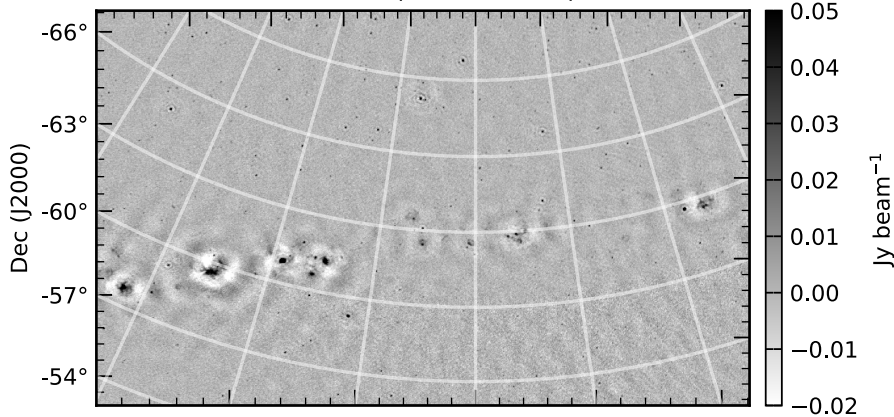


# 7. Can this be real? What's happening?

Stokes I



Stokes V (uncorrected)

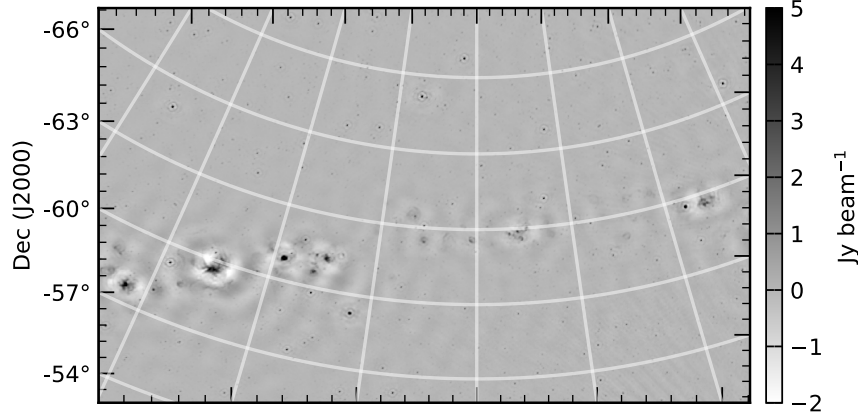


- A. Ionospheric effects
- B. Faraday rotation
- C. Polarisation leakage
- D. Galactic circular polarisation

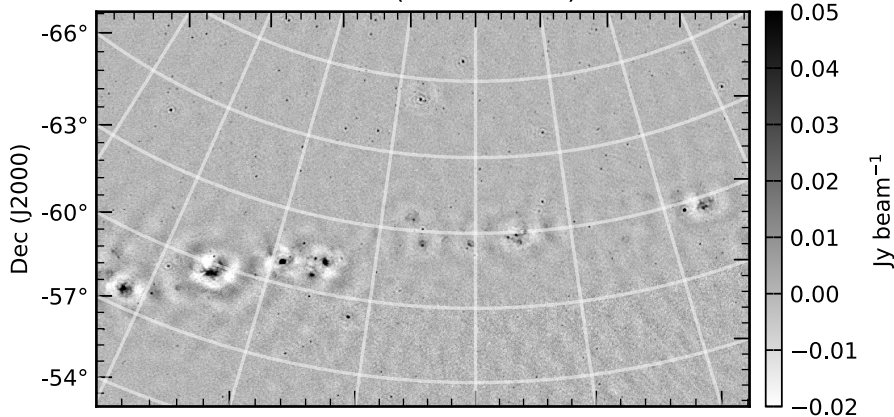


# 7. Can this be real? What's happening?

Stokes I



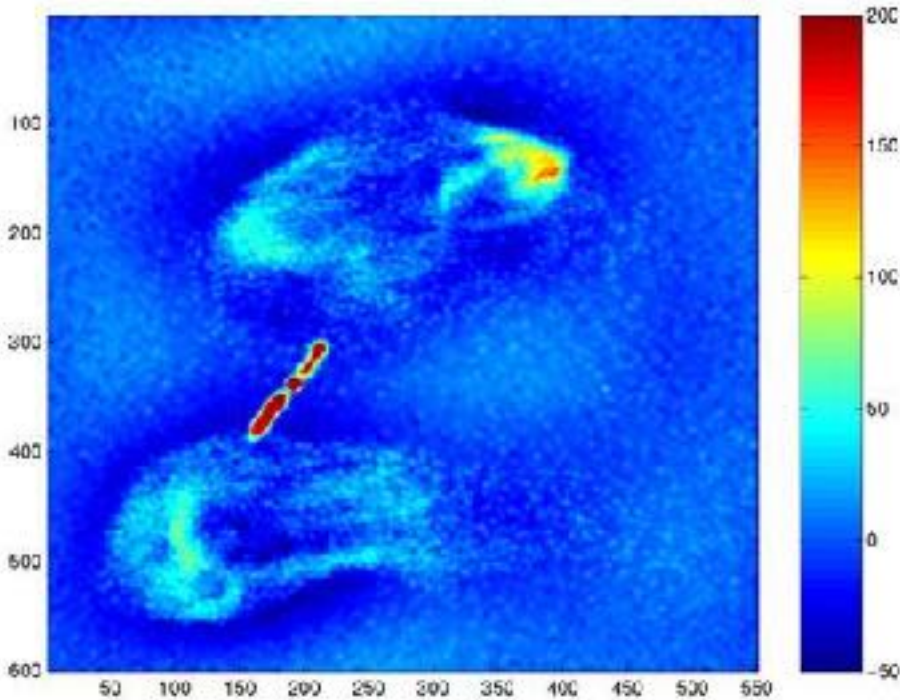
Stokes V (uncorrected)



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- B. Faraday rotation
- ✓ C. Polarisation leakage
- D. Galactic circular polarisation



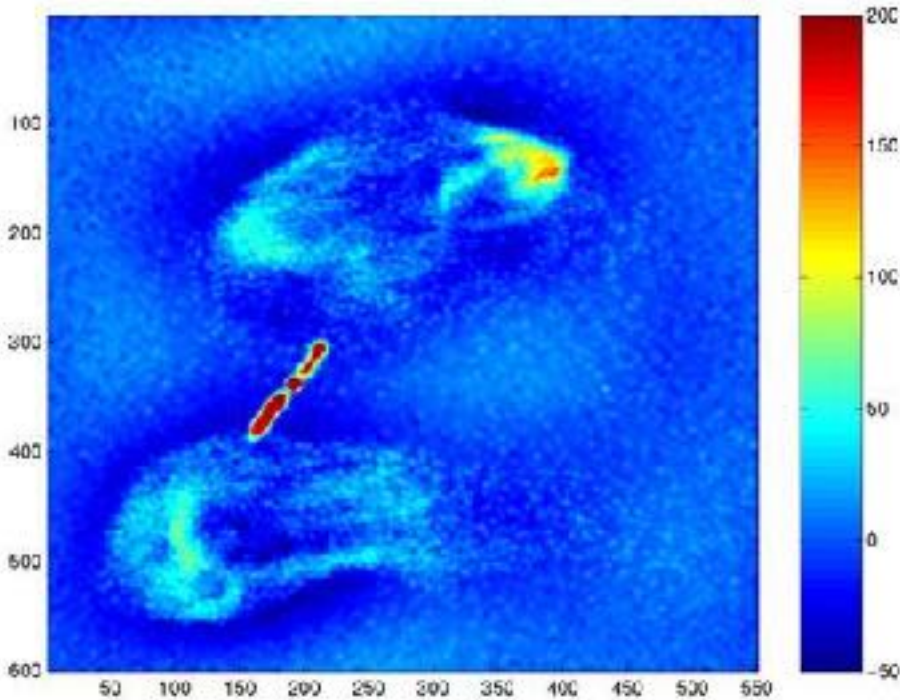
## 8. A tricky problem What's happening?



- A. Missing short baselines
- B. Missing long baselines
- C. Missing astronomer
- D. Alien Resurrection

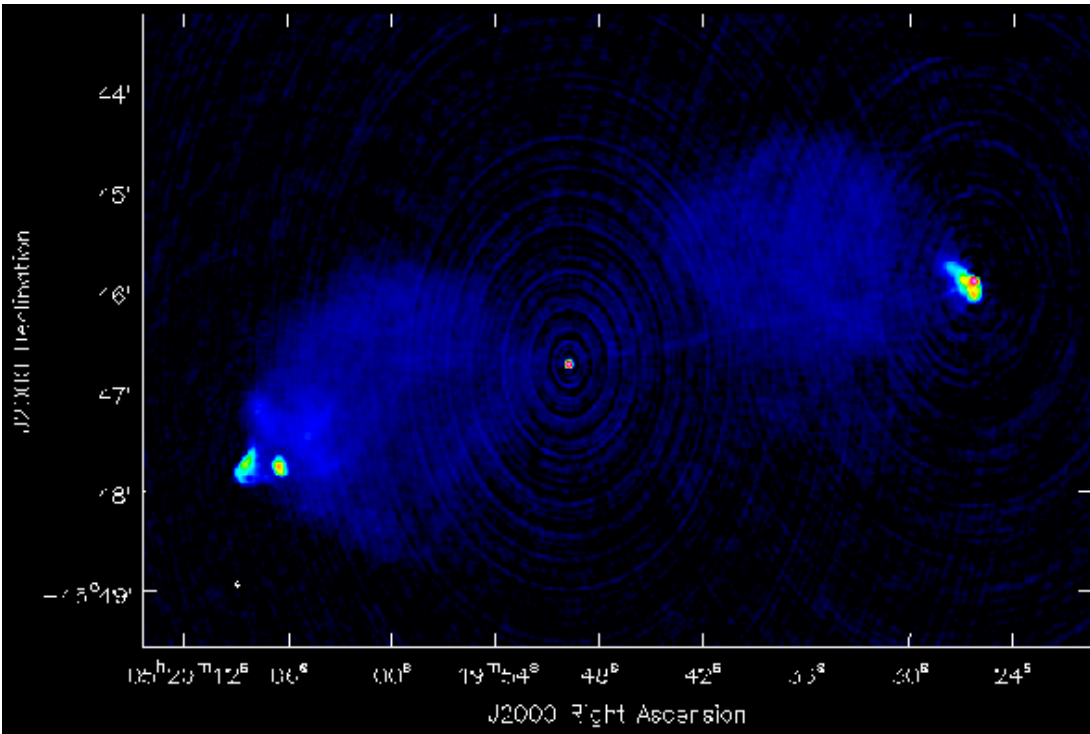


## 8. A tricky problem What's happening?



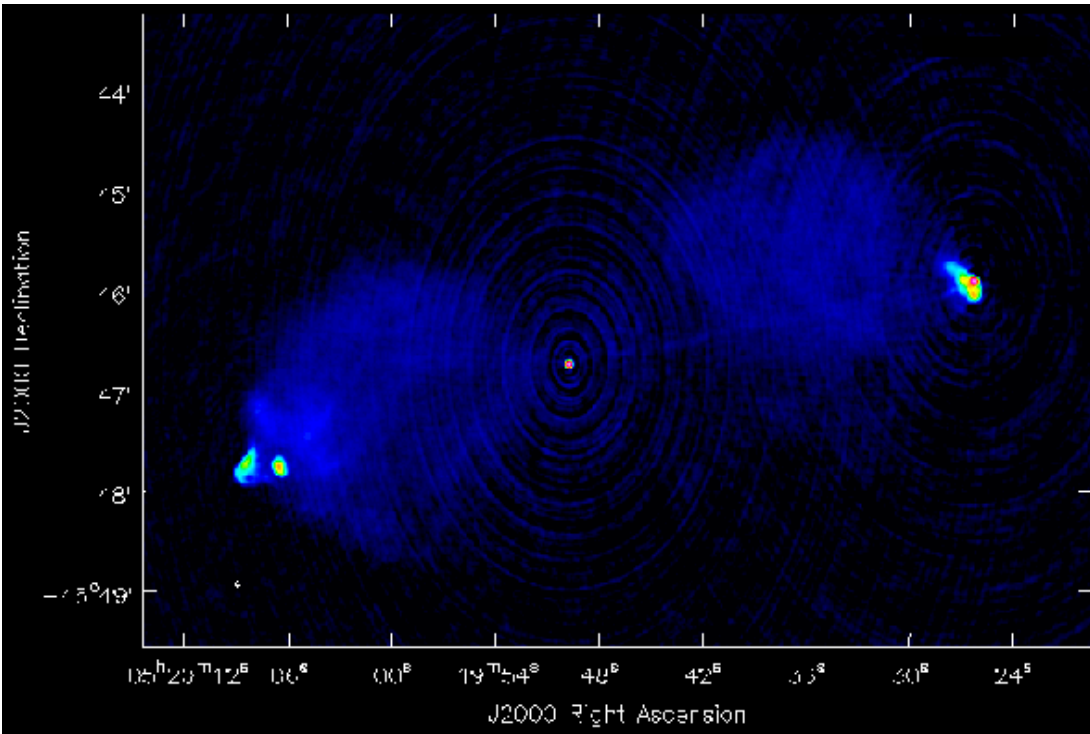
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## 9. End of game question What's happening?



- A. Amplitude errors
- B. Phase errors
- C. Deconvolution errors
- D. Position-dep. errors
- E. Almost everything

## 9. End of game question What's happening?



- A. Amplitude errors
- B. Phase errors
- C. Deconvolution errors
- D. Position-dep. errors
- E. Almost everything

- › This talk is based on talks by:
  - Steven Tingay
  - Ron Ekers
  - ASP Conference Series Vol. 180, p.321 – available online
- › Special thanks to Arin Lenc for running the pop quiz.