CSIRO DIVISION OF RADIOPHYSICS

THE AUSTRALIA TELESCOPE

AT/20.1.1/023

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Report to the 12th Meeting of the AT Advisory Committee

System Overview

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The system design for the compact array is now generally complete. Detailed specification is still however required in some areas. The Long Baseline Array is less well defined mainly because of uncertainties surrounding the clock and the tape recorders. These matters will be the subject of a report by Ray Norris.

In this report I propose only to comment on items that are new or have changed since my report to the 11th Advisory Committee Meeting (October 1985). Important changes to the system were in fact made between the time of that meeting and the time of publication of the minutes. I included those changes in the attachments to those minutes but I will also comment on them further here.

Antennas and Feeds

The problem of separating the wideband linearly polarized signals accepted by the AT feeds now seems to have a solution. There has been doubt up till now whether a small enough polarizer could be built (particularly at L/S band) to be cooled in the receiver dewar. It is hoped that the horse-shoe shaped design now proposed will meet these requirements thus allowing simultaneous observations in L and S bands with high sensitivity and with no cumbersome mechanical changes required when changing bands.

Questions remaining to be answered are the insertion loss of the polarizer and the time required to cool it to 20 K. 70 K operation is only an option in the unlikely event that the loss is very small.

Compact Array Receiving System

This system is summarized in figures 1-6.

Figure 1. The switching waveforms for the 0/180° and 0/90° phase switches and for the noise diodes have now been specified (AT/20.1.1/020). The added noise will be about 5% of T., and will be modulated on and off with a 500 Hz square wave. The transitions at different antennas will be timed to be in phase at the array tying point. The combined noise from the 6 antennas can then be used for tied array calibration. The 0/180°

switching waveforms will be square waves of frequencies 0, 250, 500, 1000, 2000, and 4000 Hz. These waveforms are all orthogonal, independent of lag. The 0/90° switching waveforms will also be square waves but with much longer periods. The switching frequencies will be 0, $1/\tau$, $2/\tau$, $4/\tau$. $8/\tau$ and $16/\tau$ where τ , the integration time is an integral multiple of 8 m sec. The time of a given switch transition can be controlled to within a microsecond but the periods will be precise to tens of nanosecond.

The $0/90^{\circ}$ demodulation will probably be done at the 1.8-2.2 GHZ local oscillator in the conversion module rather than in the correlator as suggested previously. For good image rejection the 90° transitions at modulation and demodulation have to be very precise ($\simeq 0.5^{\circ}$) (AT/20.1.1/020) and therefore need to be set up digitally as in the fringe rotators. The choice of very show 0/90° switching rates is a direct consequence of this mode of operation because a significant dead time will result at each transition while a new phase is being established.

Local oscillator distribution to the antennas via optical fibre marginally failed to meet the required phase precision. The decision has therefore been made to use coaxial cable for that purpose. Optical fibres will still be used for returning the digitized IF signals.

The precision required of the level and gain monitors and the resolution of the fine and coarse level controllers have been specified in AT/20.1.1/016. These specifications are consistent with a dynamic range $>10^4$ in a 12 hour map or >500 in a single integration.

Figure 2

The main change on this figure is the addition of a second 16 MHz bandwidth in each IF for the tied array. This addition is only necessary if a 64 MHz bandwidth is required in a single polarization. It is shown in more detail in figure 4.

The precision of the gain control attenuator, used to equalize gains between polarizations and between antennas in the tied array has been specified in AT/20.1.1/016. The 0.25 dB step allows 1% polarization to be measured in a single integration time on each baseline of the LBA which involves the tied array.

Figure 3

The front end conversion scheme is considerably different to that presented at the last meeting. It is similar to that shown in Attachment 1(12) to the minutes. By providing a choice of IF bands after several of the mixers we have been able to limit the range of LO's that may otherwise have interfered with L/S and C/X observations. The frequency steps in the synthesizers have been reduced and the range of the phase rotator increased to allow for complete Doppler tracking for bandwidths below 32 MHz. For 32 MHz and above Doppler tracking in the correlator is provided.

Only minor changes have been made to the narrow band tuning scheme. (1) Some of the filter frequencies have been changed. (2) The line correlator sampler uses a fixed frequency clock and oversamples (the surplus samples will be discarded in the correlator). (3) A band inverter has been added to provide compatibility with other receiving systems. (4) A second 16 MHz band is filtered and tied so that a full 64 MHz band in a single polarization can be recorded for the LBA. (5) 0/180° phase modulation is applied to the tied array signals. The switching waveform is orthogonal to those used at other LBA antennas. (6) Sample statistics are monitored immediately after the tied array sampler and used to control the reference levels of the digitizer.

The most important change is to the 80 MHz local oscillator synthesizer. It now has a range of 1 MHz and frequency steps of 4 KHz. When combined with the frequency steps available in the front end local oscillators and the 5 KHz range of the fringe rotators this gives us complete Doppler tracking for bandwidths below 32 MHz.

Figure 5.

The main purpose of this figure is to illustrate how the sample statistics for controlling the reference levels of the digitizers are accumulated in the correlators. These statistics are monitored before the 0/180° phase switching is removed digitally. Also associated with each correlator is a switched correlator which measures the phase between related linearly polarized IF's.

Figure 6.

Four sets of array tying and polarization generation systems are provided. Two sets operate only on the additional 16 MHz bands shown in figure 4. The other two deal with bandwidths selectable from 0.5 to 16 MHz in factors of two. To provide circular polarization the phases between X-Y pairs of inputs are monitored with analogue switched correlators and precision so that the tied array beams in opposite polarizations maintained at 90°. The gains are also equalized to high are identical (but 90° out of phase) to a very high precision. These can be combined to give equal left and right circularly polarized signals or recorded directly as linearly polarized signals.

Long Baseline Array Receiving System

For Siding Spring, Parkes and possibly Hobart, it may be convenient to provide CA-like receiving systems complete with delay tracking, fine tuning, fringe rotation and digitally stabilized IF return from antenna focal cabin to control room. No additional design is then required and substantial parts of

the CA system can then simply be copied for these sites. Figures 7-10 show a system of this type. The system is slightly simpler than for the CA because only 4 bit sampling of a 64 MHz bandwidth signal has to be provided at the antenna.

This system requires that digital rather than analogue IF inputs be supplied to the VLBA tape recorders. This modification is already a requirement for the tied array.

An option that might be used for Tidbinbilla and later additions to the LBA system is shown in figure 8. IF signals in the range 500-1000 MHz are input to complete VLBA recording systems via phase stabilized cables. For this option "add on" fringe rotation at the correlator is proposed with some loss of sensitivity.

Parkes and Siding Spring antennas must function as stand-alone systems as well as elements of the LBA. It is important however that these two functions be combined without a proliferation of different receivers but also without degradation of performance in either mode. Specifications for the Parkes receivers that meet these aims have been set out in AT/22.1.1/014. The first dewar will contain two channels each at L.S.C and X bands. The inputs will be separate circular waveguides accepting both polarizations for C and X bands and pairs of coaxial inputs at L and S bands. A variety of feeds can be attached to this dewar to give a selection of linear or circular polarizations single or dual beam or limited dual frequency operation in L/S, C/X or S/X bands. A second dewar with dual channels in L and S bands will be provided later to give better sensitivity for both LBA and stand-alone operation.

A similar approach will probably be adopted to provide dual beam stand-alone operation in bands above X band at Siding Spring. No beam switching is contemplated at either site. Rather beam differencing will be carried out in correlation receivers. These will also provide stand-alone polarization capabilities.

Compact Array Correlator (Figures 11-13).

16 MHz operation is now planned although chips to replace the earlier faulty ones have not yet arrived. It is expected that they also will be capable of operating at 16 MHz.

The correlator control computer will be a μVAX II and an associated Sky Warrior 15 M flop array processor which will share memory with the μVAX . This system will be capable of supporting:

1. The largest line maps. (AT/24.1.1/009 Doppler tracking, (AT/23.4/011) Bandwidth Synthesis. (AT/20.1.1/019)

(AT/20.1.1/013)2 m sec integration

times, for wideband continuum.

(AT/20.1.1/012) and Pulsar observations, (AT/24.1.1/009)

6. Data output rates far in excess of the capabilities of current optical disk

Computers

The nature of the on-line computers for the compact array is now fairly well defined. uVAX II's will be used for the synchronous, asynchronous and correlator control computers and possibly also for the antenna link controller. At the antennas the antenna control computers will be LSI 11/83 computers. The synchronous, asynchronous and correlator control computers will probably share access to disks and optical disks.

The choice of an off-line computing system will be made at an appropriate later date. One solution has always been to use a cluster of work stations using μVAX computers and some form of shared disk facilities for the smaller tasks and the cyber 205 for the large data cubes and wide field maps. Ιt seems now that it may be unwise to rely too heavily on the Cyber 205 and a powerful computer such as the Convex C-1 with multiple work stations may be a better compromise.

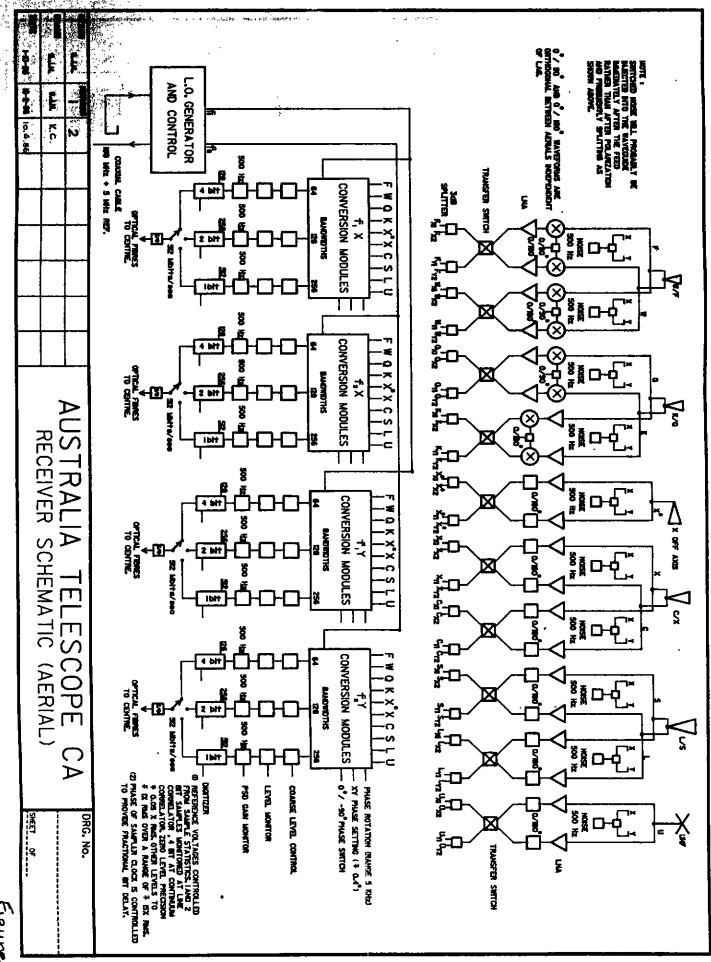
RF Interference Suppression

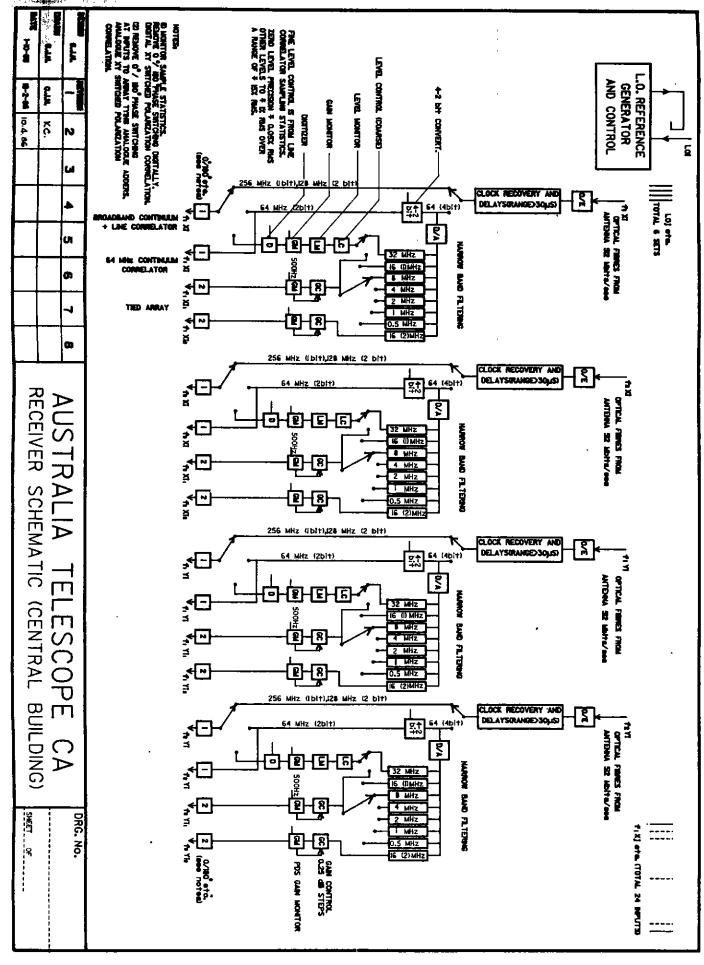
Minor modifications to the 22 m antennas will be carried out by the contractor so that adequate RF shielding of the vertex room can be achieved.

At a later date we will design and fit a rotating RFI contactor attached to the turret to seal the opening between vertex and feed cone rooms. Additional protection may involve absorbing material on the walls of the feed cone room and local shielding of computers in the pedestal room.

Consideration is also being given to means of shielding the Culgoora control building (the correlator will certainly be in a shielded room) and the Siding Spring Control room.

Graham Nelson, 23rd Arril, 1986.





Figi. + 2

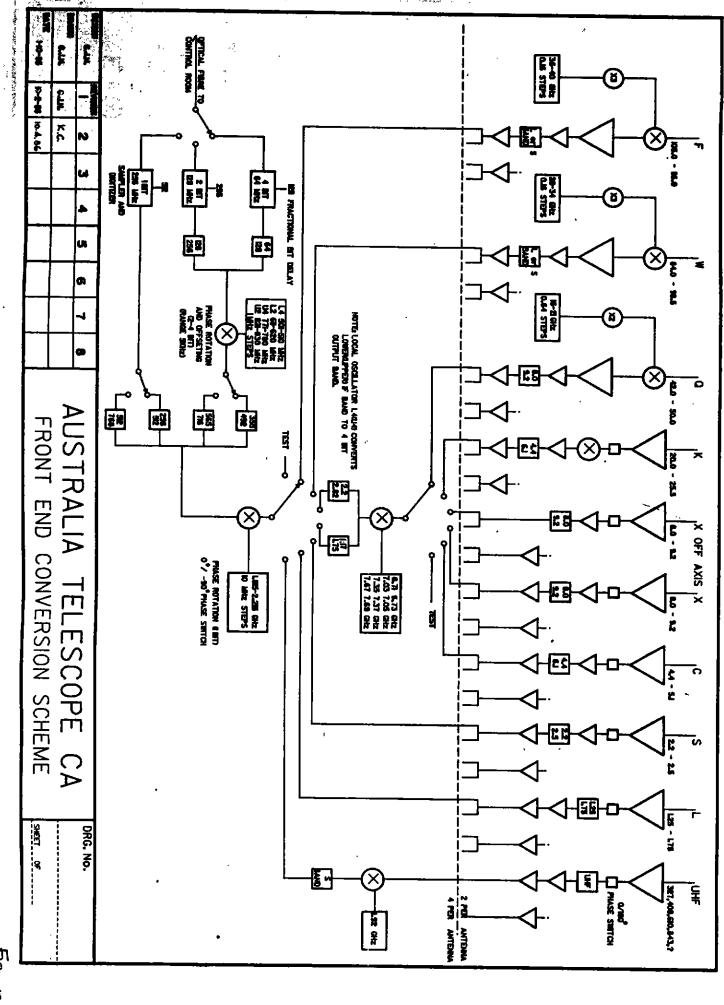
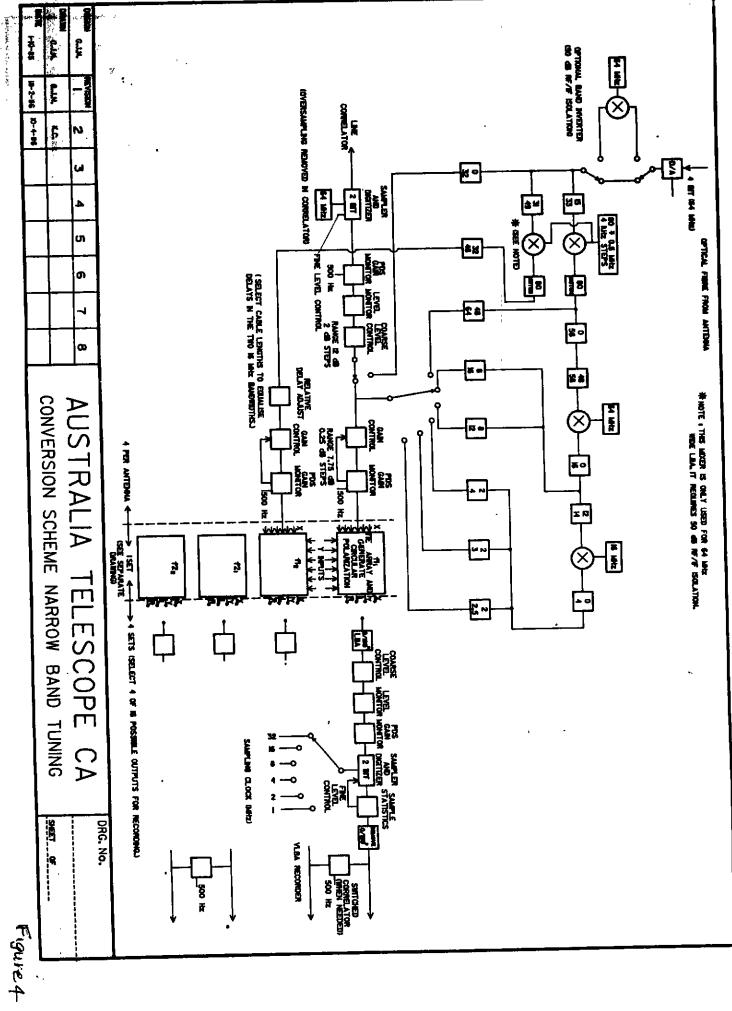
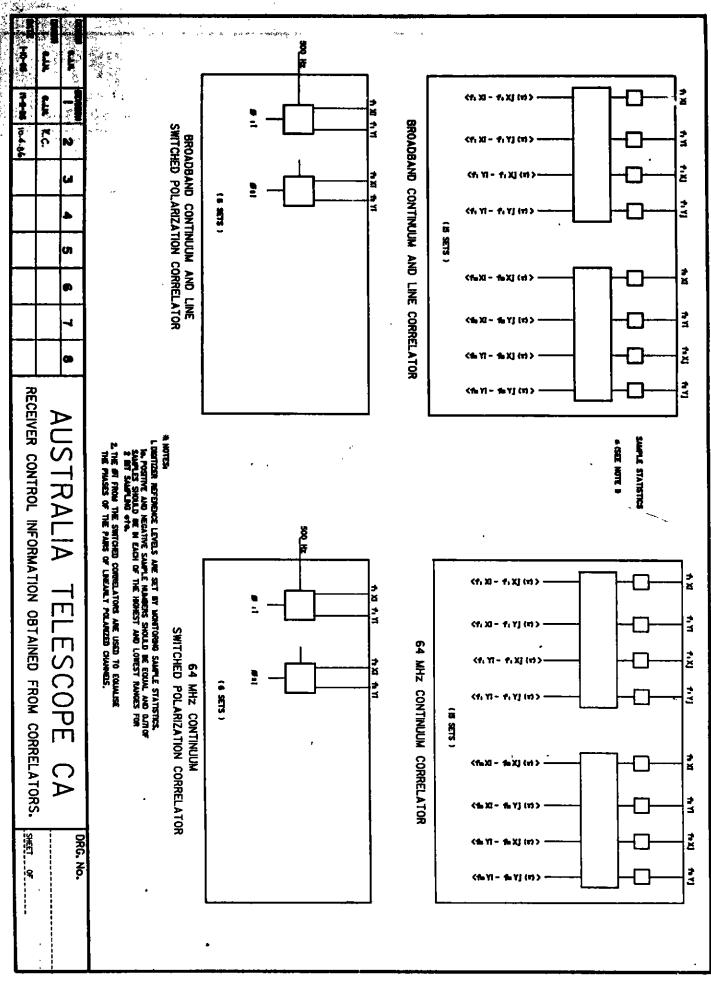


Figure 3





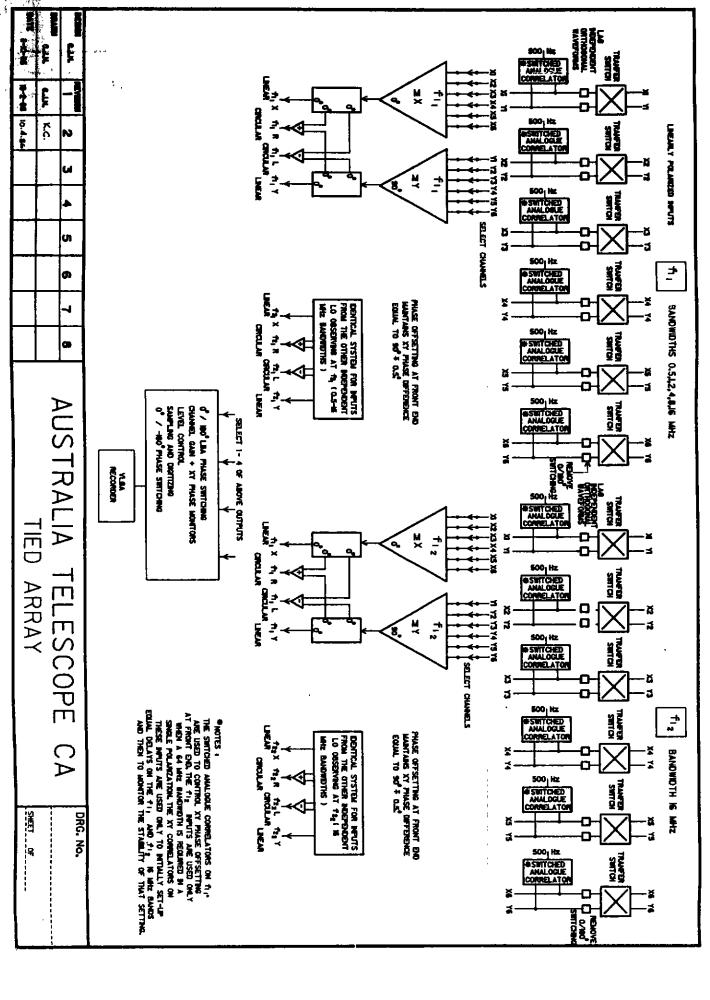


Figure 6

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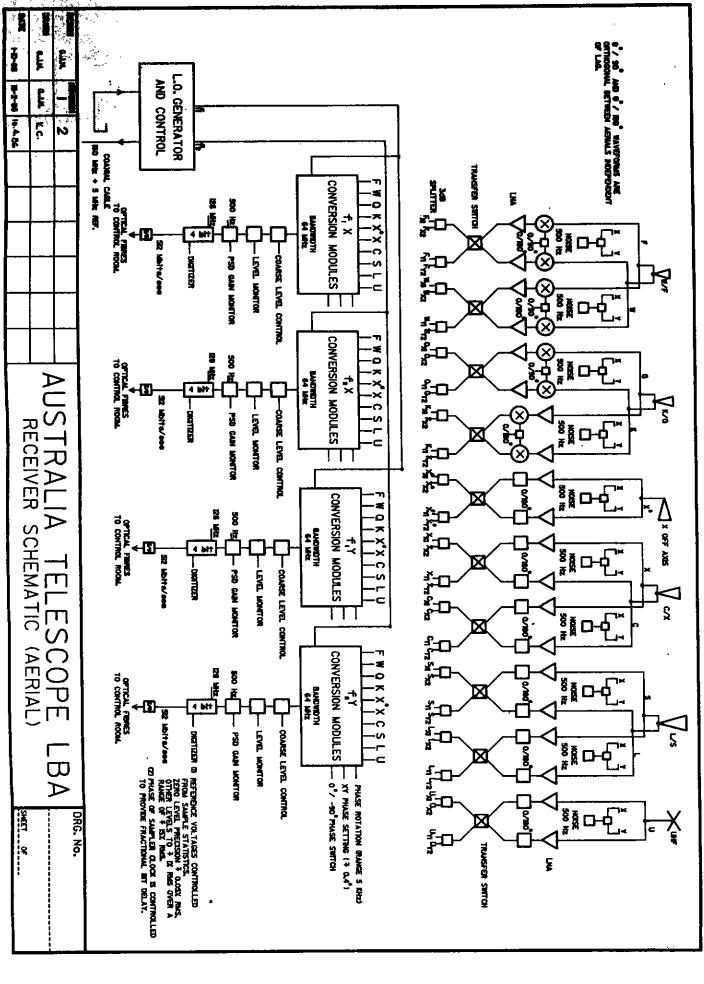
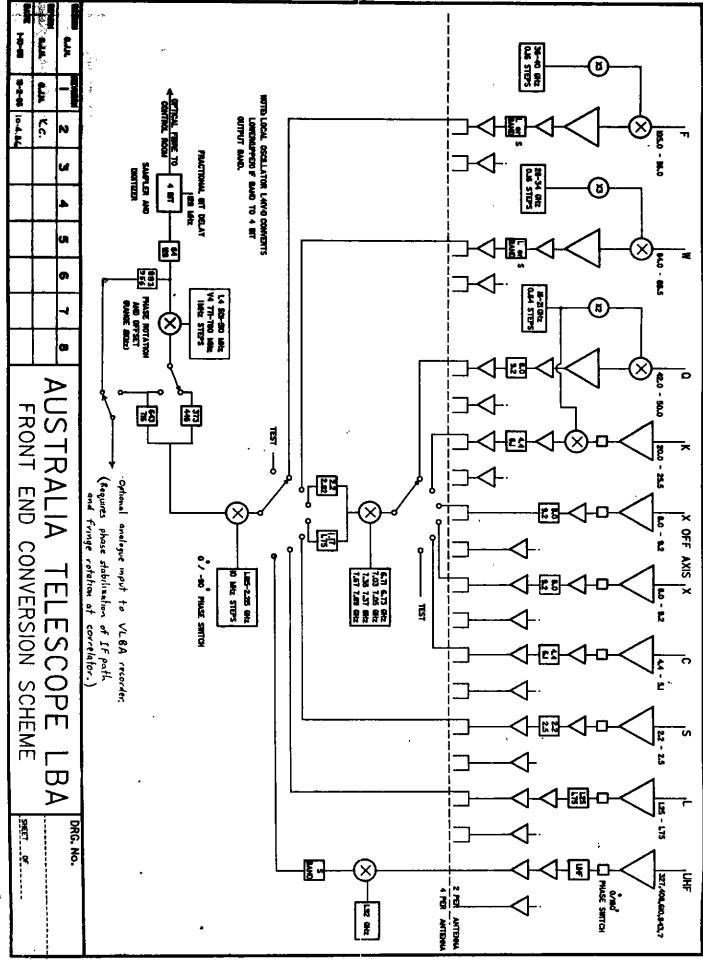
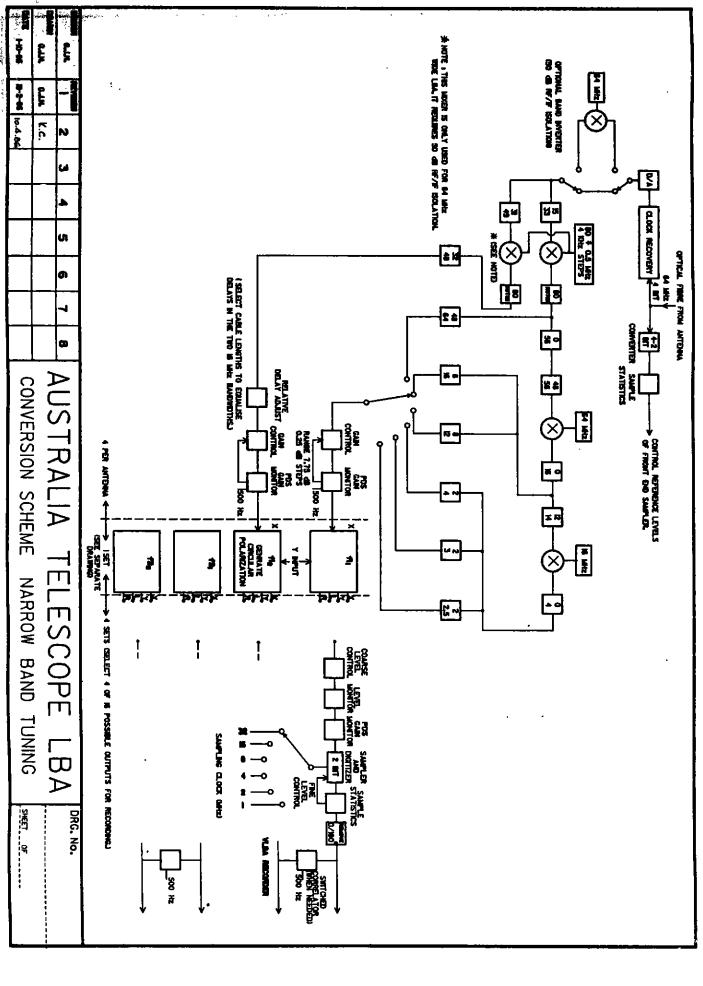


Figure 7

高さる 事に養べかれ





Figureq

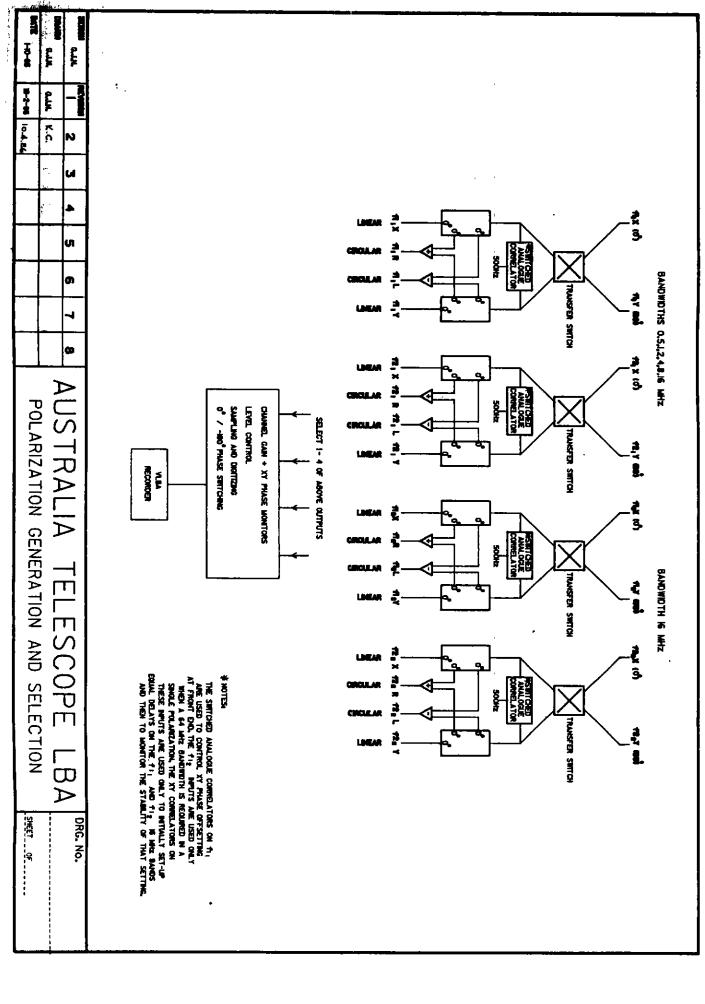
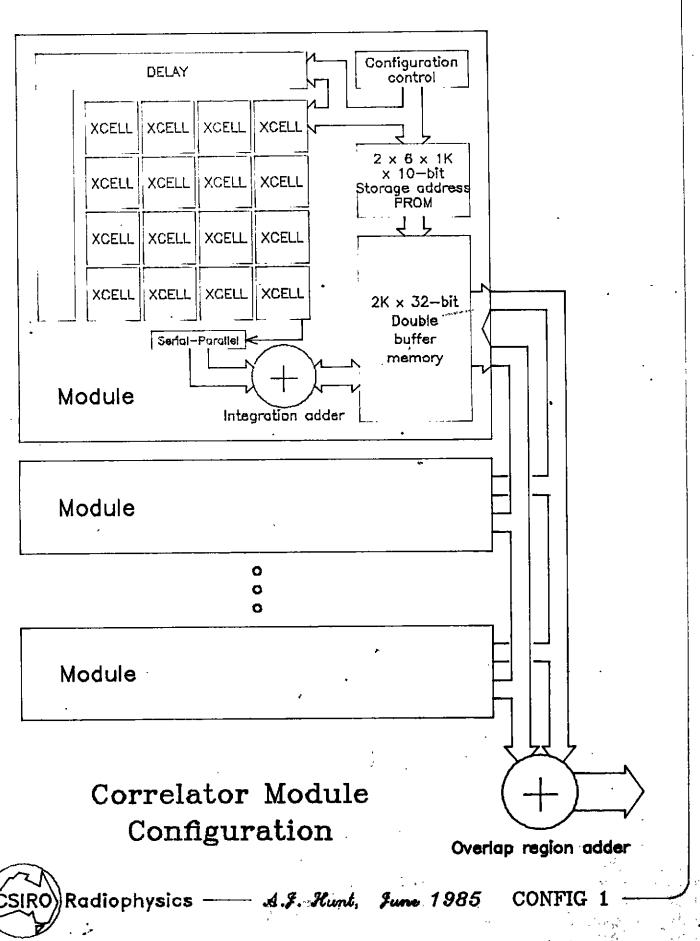
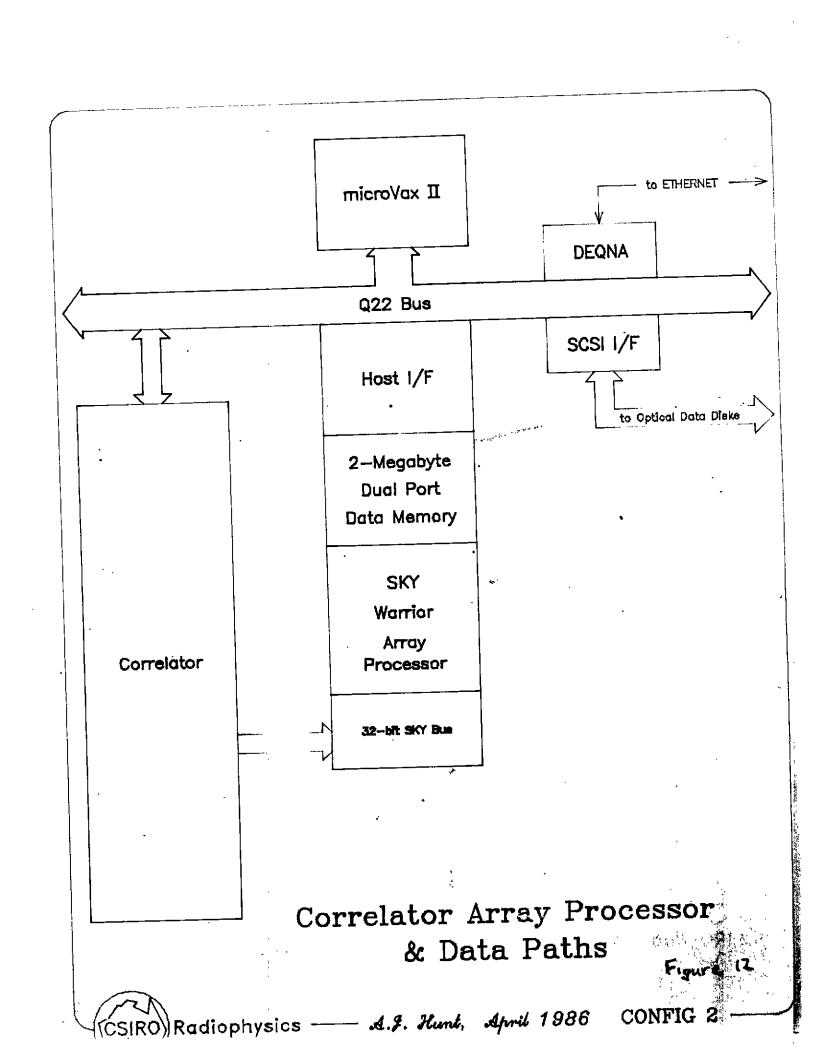


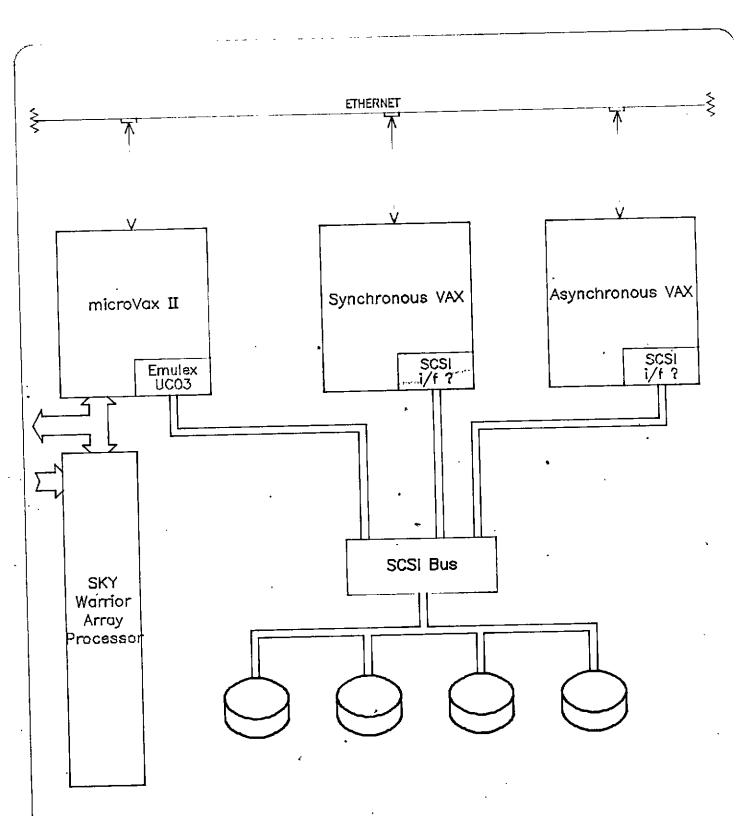
Figure 10

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Correlator Data Paths to Disk

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Figure 13