

Interferometric Spectral Line Imaging

Martin Zwaan

(Chapters 11 + 12 of synthesis imaging book)

Topics

- Calibration
- Gibbs phenomenon
- Continuum subtraction
- Flagging
- First reduction steps

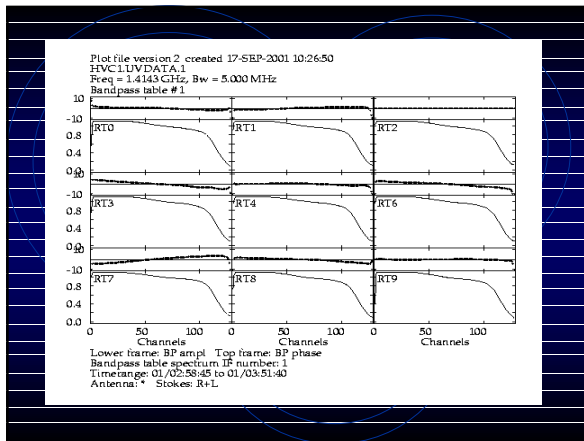
After imaging: Barbel's talk

Why Spectral Line Interferometry?

- Spectroscopy
 - Important spectral lines
 - HI hyperfine line
 - Recombination lines
 - Molecules (CO, OH, H₂O, masers)
 - Calculate column densities (physical state of ISM) and line widths (rotation of galaxies)
- Continuum
 - Reduce bandwidth smearing
 - Isolate RFI

Calibration

- Continuum data: determine complex gain solutions as function of time
- Spectral line data: same, but also function of ν
- **Bandpass: complex gain as function of frequency**
- Factors that affect the bandpass:
 - Front-end system, IF transmission system (VLA 3 MHz tripple), back-end filters, Correlator, atmosphere, standing waves
- Different for all antennas
- Usually not time-dependent



Calibration

- Determine bandpass $B_{ij}(\nu)$
 - Peak continuum/ rms noise image
 - Pcal-Scal-target-Scal
- Pcal: strong (point) source with known ν , observe at same ν as target
- Observe Pcal more often for high spectral DR
- Observe long enough so that uncertainties in BP do not contribute significantly to image

Calibration procedure

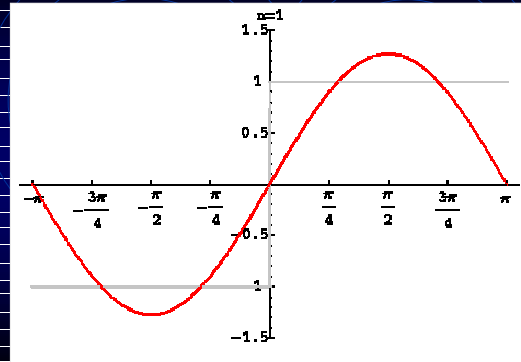
- Create pseudo-continuum (inner 75% of channels)
- Determine complex gains $G_{ij}(t)$
- Determine $B_{ij}(\nu)$
- Effects of atmosphere and source structure are removed by dividing by pseudo-continuum
- N unknowns, $N(N-1)/2$ measurables
- Compute separate solution for every observation of Pcal

Check bandpass calibration

- Smooth variation with frequency
- Apply BP solution to Scal: should be flat
- Compare BP solutions of different scans (for all antennas)

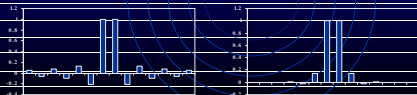
Gibbs Phenomenon

- Wiener-Khinchine theorem:
Spectral content $I(\nu)$ of stationary signal is Fourier transform of the time cross-correlation function $R(\tau)$
 - Need to measure $R(\tau)$ from $-\infty$ to ∞
 - In practice: only measure from $-N/2B$ to $N/2B$
→ Multiply $R(\tau)$ with a window function (uniform taper)
 - In ν domain: $I(\nu)$ convoluted with $\text{sinc}(x)$
 - Nulls spaced by channel separation
 - Effective resolution: 1.2 times channel separation
 - ~22% spectral side lobes



Solutions

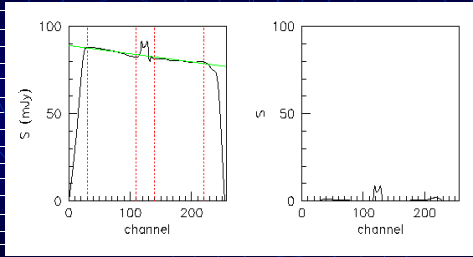
- Observe with more channels than necessary
- Remove first channels
- Tapering sharp end of lag spectrum $R(\tau)$
 - Hanning smoothing: $f(\tau) = 0.5 + 0.5 \cos(\pi\tau/T)$
 - In frequency space: multiplying channels with 0.25, 0.5, 0.25
 - After Hanning smoothing:
 - Effective resolution: 2.0 times channel separation
 - ~3% spectral side lobes



Continuum Subtraction

- Every field contains several continuum sources
 - Separate line and continuum emission
 - Two basic methods:
 - Subtract continuum in map domain (IMLIN)
 - Subtract continuum in UV domain (UVSUB, UVLIN)
 - Know which channels are line free
 - Use maximum number of line free channels
- Iterative process*

Continuum Subtraction



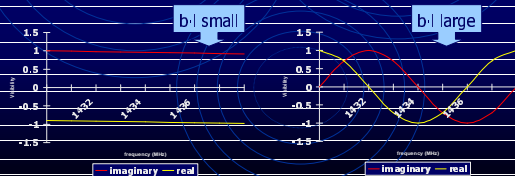
IMLIN

- Fit low-order polynomials to selected channels (free from line emission) at every pixel in image cube and subtract the appropriate values from all channels
- Don't have to go back to uv data
- Can't flag data
- Clean continuum in every channel
 - Time-consuming
 - Non-linear: noisy data cube
 - Noisy continuum map

UVLIN

- Linear fits to real and imaginary components versus channel number for each visibility and subtracts the appropriate values from all channels

• Visibilities: $\frac{\text{Baseline length}}{\text{Distance from phase center}}$
 $V = \cos(2\pi b l/c) + i \sin(2\pi b l/c)$



UVLIN (cont'd)

- Allows to shift visibilities to move single strong source to image center → do fitting → shift back
- No need to deconvolve continuum sources in all channels (deconvolution is non-linear)
- Yields better continuum image
- Fast
- Allows flagging (remove baselines with high residuals)
- Corrects for spectral slope
- Only works for restricted field of view

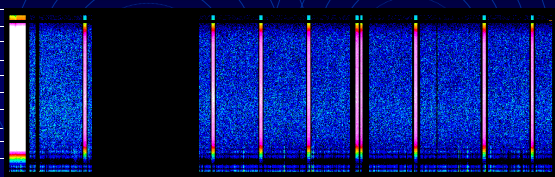
UVSUB

- Subtract Fourier transform of specified model from visibility data set. Input model may consist of the CLEAN components, input images, or specified model
- Works well for strong sources far away from phase center
- Non-linear: introduces errors in maps
- Slow!

A procedure for continuum subtraction

- Make large continuum map to find far field sources
- UVLIN on large number of channels
- Do Fourier transform and find line emission
- Look for artifacts from strong continuum sources
- Use UVLIN if one source dominates
- Use UVSUB if many sources dominate, then UVLIN
- Quality of continuum subtraction depends on quality of bandpass calibration

Flagging of Spectral Line Data



- Try UVLIN
- Try to maintain similar uv coverage in all channels

Basic Reduction Steps

- Read data
- Check quality and edit (flag)
- Make pseudo-continuum
- Determine gain solutions
- Determine bandpass
- Split-off calibrated program source
- Subtract continuum
- Make image cube